



**ITMO UNIVERSITY**

# **How to Win Coding Competitions: Secrets of Champions**

**Week 3: Sorting and Search Algorithms**

**Lecture 7: Lower bound. Stable sorting. Comparators**

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Saint Petersburg 2016**

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Mergesort is **asymptotically optimal**.

Quicksort is **asymptotically optimal on average**.

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Cons:

- ▶ Additional memory needed for storing the indices
- ▶ More complicated ordering, may further decrease performance

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**Requirements** for a comparator:

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- ▶ If it reports  $a = b$ , then  $a$  and  $b$  must be equal (in a problem-dependent sense)
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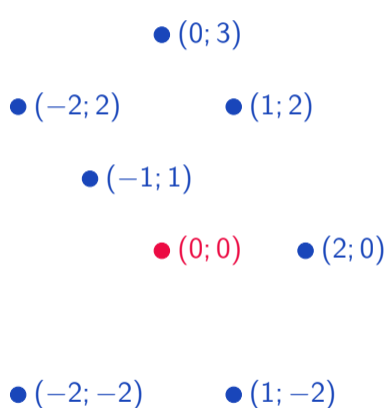
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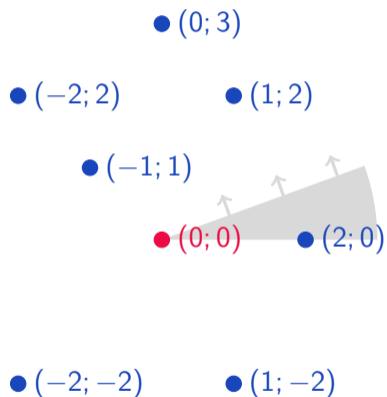
**Implementation** of a comparator:

- ▶ Java-way: return 0 if “equal”, negative if “less”, positive if “greater”
- ▶ C++-way: return `true` if “less”, `false` otherwise



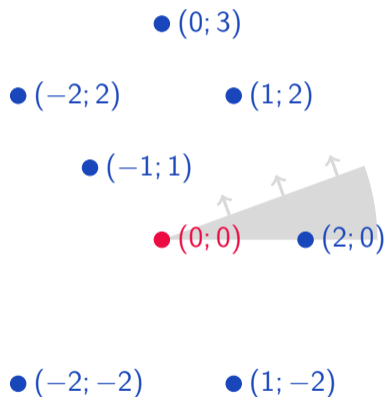


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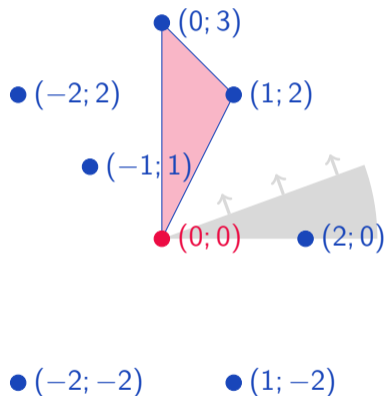
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**Idea:** compare using oriented triangle area

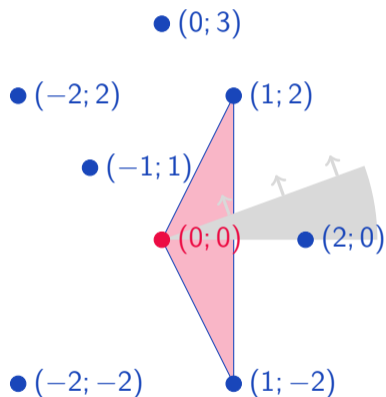


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function LESSTHAN((x1, y1), (x2, y2))
  return x1 · y2 - x2 · y1 > 0
end function
```



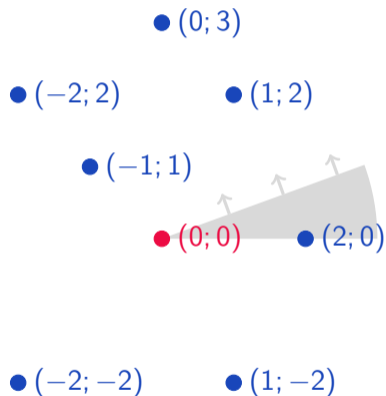
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Wait, what happens there?

```
function LESSTHAN( $(x_1, y_1)$ ,  $(x_2, y_2)$ )
  return  $x_1 \cdot y_2 - x_2 \cdot y_1 > 0$ 
end function
```



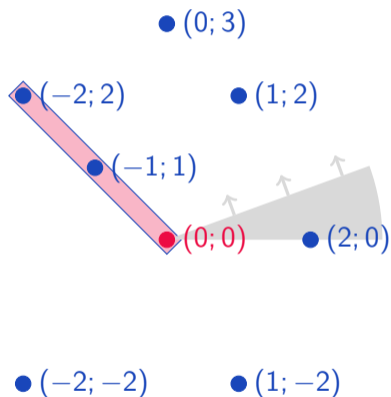
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**Idea:** compare using oriented triangle area  
... but first check the halfplanes

```

function LESSTHAN( $(x_1, y_1), (x_2, y_2)$ )
   $h_1 \leftarrow 0, h_2 \leftarrow 0$ 
  if  $y_1 < 0$  or ( $y_1 = 0$  and  $x_1 < 0$ ) then  $h_1 \leftarrow 1$  end if
  if  $y_2 < 0$  or ( $y_2 = 0$  and  $x_2 < 0$ ) then  $h_2 \leftarrow 1$  end if
  if  $h_1 \neq h_2$  then return  $h_1 < h_2$  end if
  return  $x_1 \cdot y_2 - x_2 \cdot y_1 > 0$ 
end function
  
```



Sort the points counterclockwise around the red dot

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Idea: compare using oriented triangle area  
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Okay, but what happens for colinear points?

**function** LESSTHAN( $(x_1, y_1), (x_2, y_2)$ )

$h_1 \leftarrow 0, h_2 \leftarrow 0$

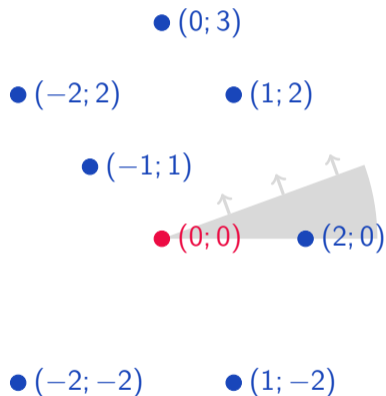
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**if**  $h_1 \neq h_2$  **then return**  $h_1 < h_2$  **end if**

**return**  $x_1 \cdot y_2 - x_2 \cdot y_1 > 0$

**end function**



**Sort** the points counterclockwise around the red dot

► Need to break a circle: start at  $\vec{Ox}$

**Idea:** compare using oriented triangle area

... but first check the halfplanes

... and, from colinear points, favor closer ones.

```

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  h1 ← 0, h2 ← 0
  if y1 < 0 or (y1 = 0 and x1 < 0) then h1 ← 1 end if
  if y2 < 0 or (y2 = 0 and x2 < 0) then h2 ← 1 end if
  if h1 ≠ h2 then return h1 < h2 end if
  z ← x1 · y2 - x2 · y1
  if z = 0 then return x12 + y12 < x22 + y22 end if
  return z > 0
end function
  
```