## Introduction to Phasors 1: <br> Sinusoidal signals

If all the sources in a circuit are sinusoidal sources and our interest is in only the steady state component (because the transient component decays to approximately zero within a short time after connecting the circuit to the ac source), we can use the phasor domain technique to analyze the circuit.

The phasor domain technique-also known as the frequency domain technique-applies to ac circuits only, and provides a solution of only the steady state component of the total solution.

## Sinusoidal signals

Before we can dive into the phasor technique, we need to be clear on what the mathematical expression for a sinusoidal signal tells us.

The expression

$$
\mathrm{v}(\mathrm{t})=\mathrm{V}_{\mathrm{m}} \cos (\omega \mathrm{t})
$$

describes a sinusoidal voltage $v(t)$ that has an amplitude $V_{m}$ and an angular frequency $\omega$. The amplitude defines the maximum or peak value that $v(t)$ can reach, and $-V_{m}$ is its lowest negative value. The argument of the cosine function, $\omega t$, is measured either in degrees or in radians, with

$$
\pi(\mathrm{rad}) \approx 3.1416(\mathrm{rad})=180^{\circ}
$$



Note that the angular frequency $\omega$ is related to the oscillation frequency (or simply the frequency) $f$ of the signal by:

$$
\omega=2 \pi f(\mathrm{rad} / \mathrm{s})
$$

with f measured in hertz $(\mathrm{Hz})$, which is equivalent to cycles/second. A sinusoidal voltage with a frequency of 100 Hz makes 100 oscillations in 1 s , each of duration $1 / 100=0.01 \mathrm{~s}$. The duration of a cycle is its period T .

The general form of a sinusoid also includes a phase shift or phase angle, $\phi$ :

$$
v(t)=V_{m} \cos (\omega t+\phi)
$$

The phase shift tells us by how much the sinusoid is shifted from a reference cosine, as in the example below, which shows a reference cosine and cosines with negative and positive phase shifts.


Plots of $v(t)=V_{\mathrm{m}} \cos [(2 \pi t / T)+\phi]$ for three different values of $\phi$.

$$
\begin{aligned}
& v_{1}(t)=V_{m} \cos \left(\frac{2 \pi t}{T}-\frac{\pi}{4}\right) \\
& v_{2}(t)=V_{m} \cos \left(\frac{2 \pi t}{T}\right) \\
& v_{3}(t)=V_{m} \cos \left(\frac{2 \pi t}{T}+\frac{\pi}{4}\right)
\end{aligned}
$$

For reference:

$$
\begin{aligned}
& \sin x= \pm \cos \left(x \mp 90^{\circ}\right) \\
& \cos x= \pm \sin \left(x \pm 90^{\circ}\right) \\
& \sin x=-\sin \left(x \pm 180^{\circ}\right) \\
& \cos x=-\cos \left(x \pm 180^{\circ}\right) \\
& \sin (-x)=-\sin x \\
& \cos (-x)=\cos x \\
& \hline \sin (x \pm y)=\sin x \cos y \pm \cos x \sin y \\
& \cos (x \pm y)=\cos x \cos y \mp \sin x \sin y \\
& \hline 2 \sin x \sin y=\cos (x-y)-\cos (x+y) \\
& 2 \sin x \cos y=\sin (x+y)+\sin (x-y) \\
& 2 \cos x \cos y=\cos (x+y)+\cos (x-y)
\end{aligned}
$$

Some material reproduced with permission from Ulaby, F. T., \& Maharbiz, M. M. (2012). Circuits. 2 ${ }^{\text {nd }}$ Edition, NTS Press.

