



Video 9.1

Jianbo Shi





$820 \times 546 \times 3$

$$420 \times 546 \times 3$$



(a)



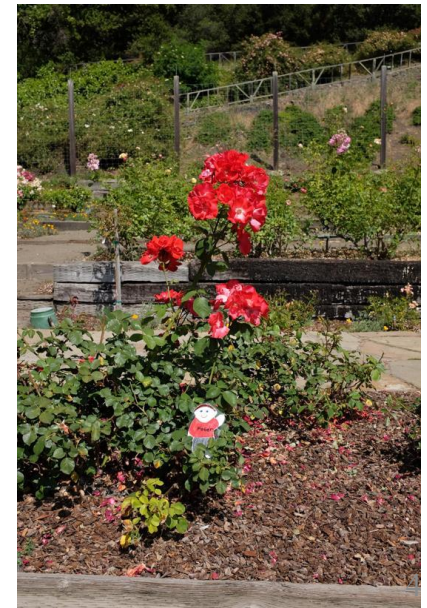
(b)

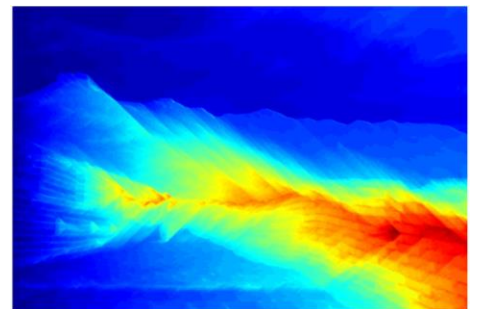
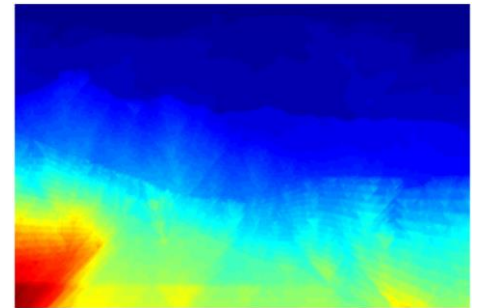
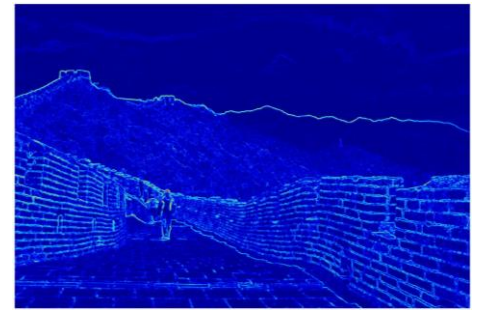


(c)

Guess

- We use “crop”, “scaling” and “carving” for resizing the given image
- Guess which one is for carving?





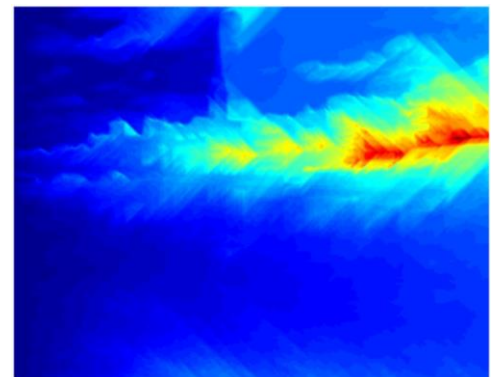
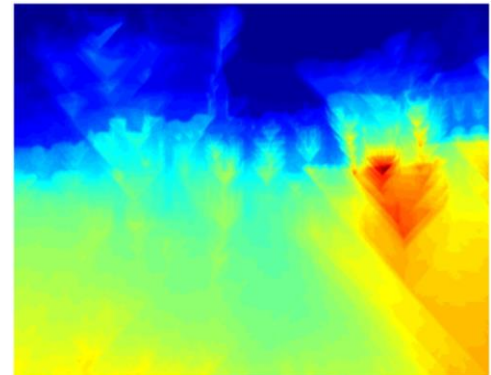




- Guess which one is for carving?

Property of Penn Engineering, Jianbo Shi







- Guess which one is for carving?

Property of Penn Engineering, Jianbo Shi





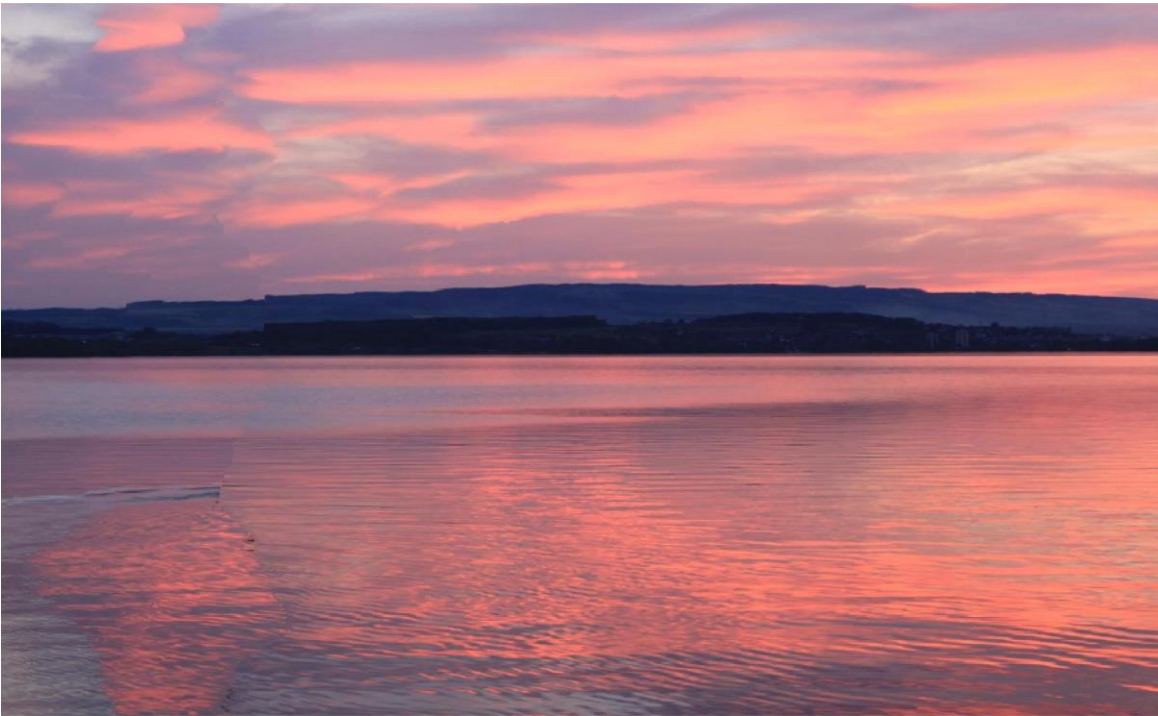




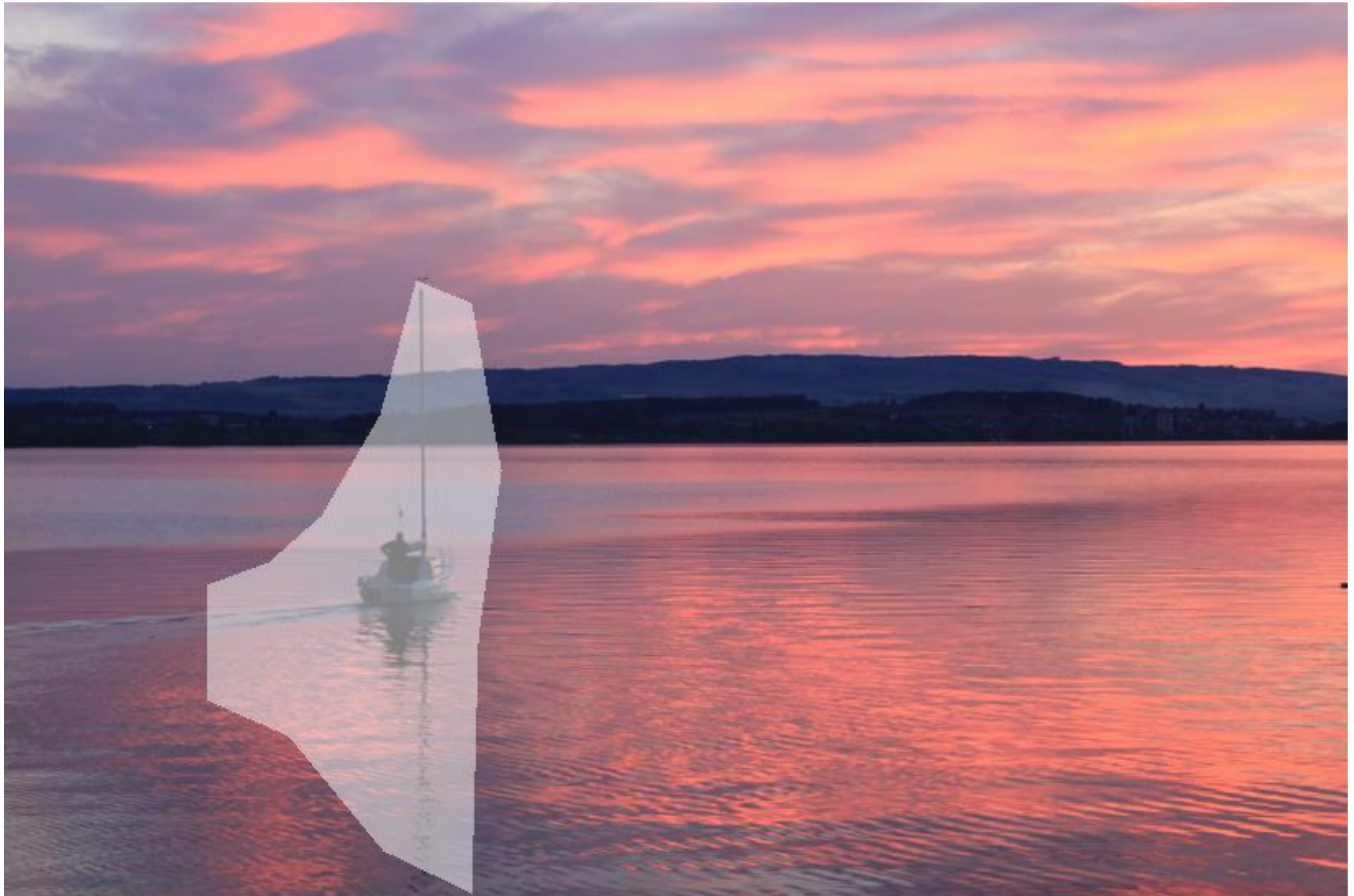




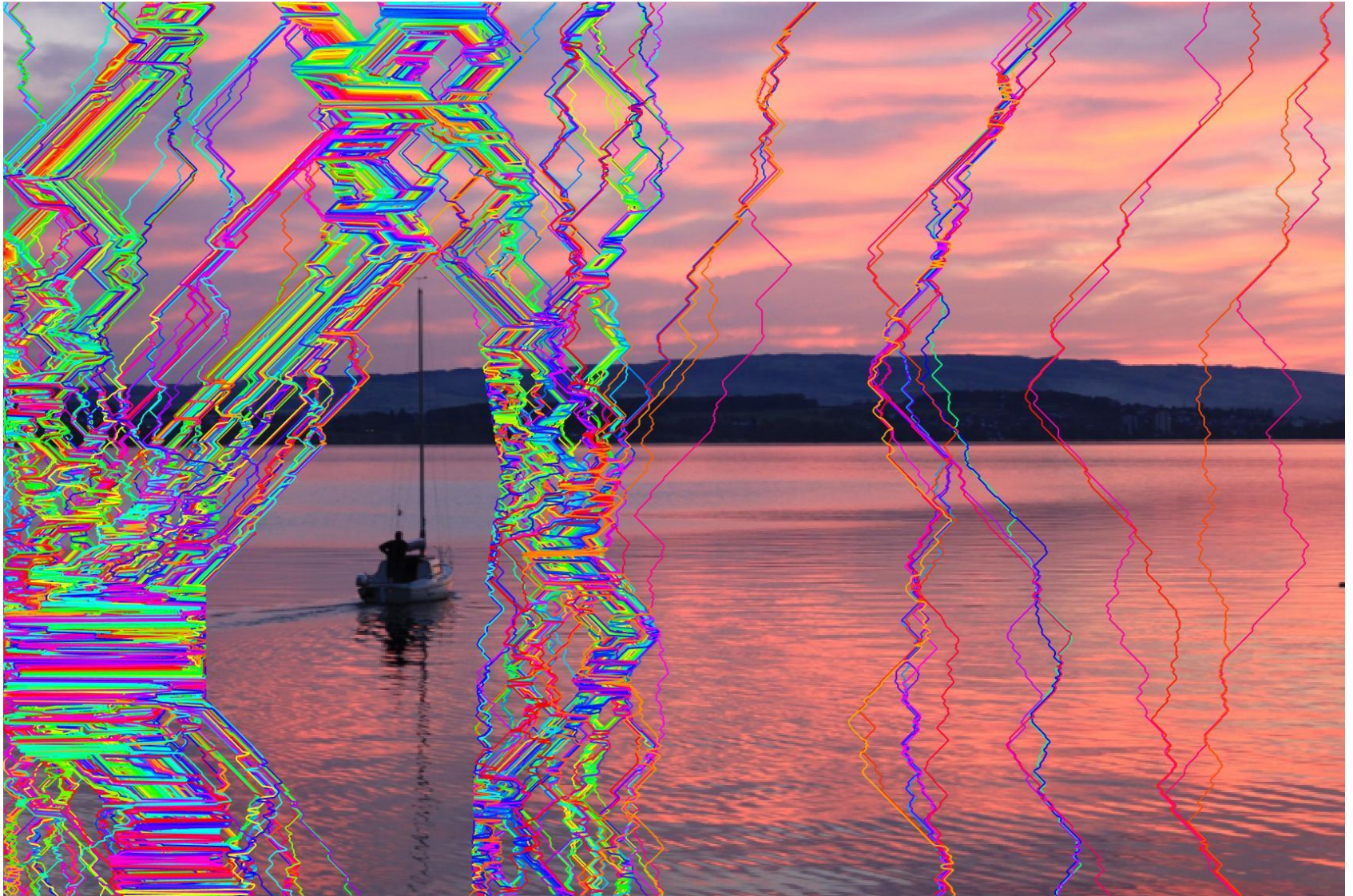
Expanded













Video 9.2

Jianbo Shi



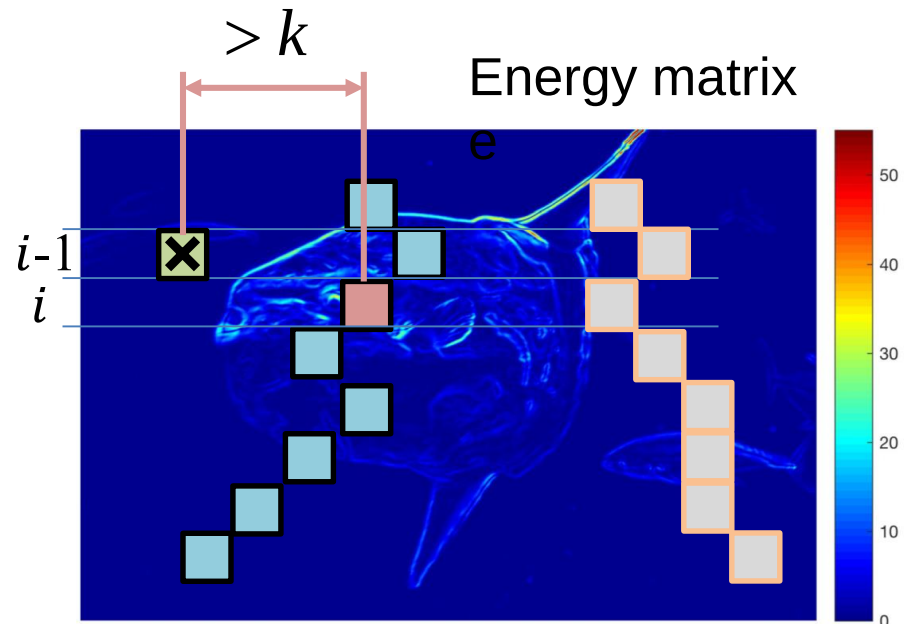




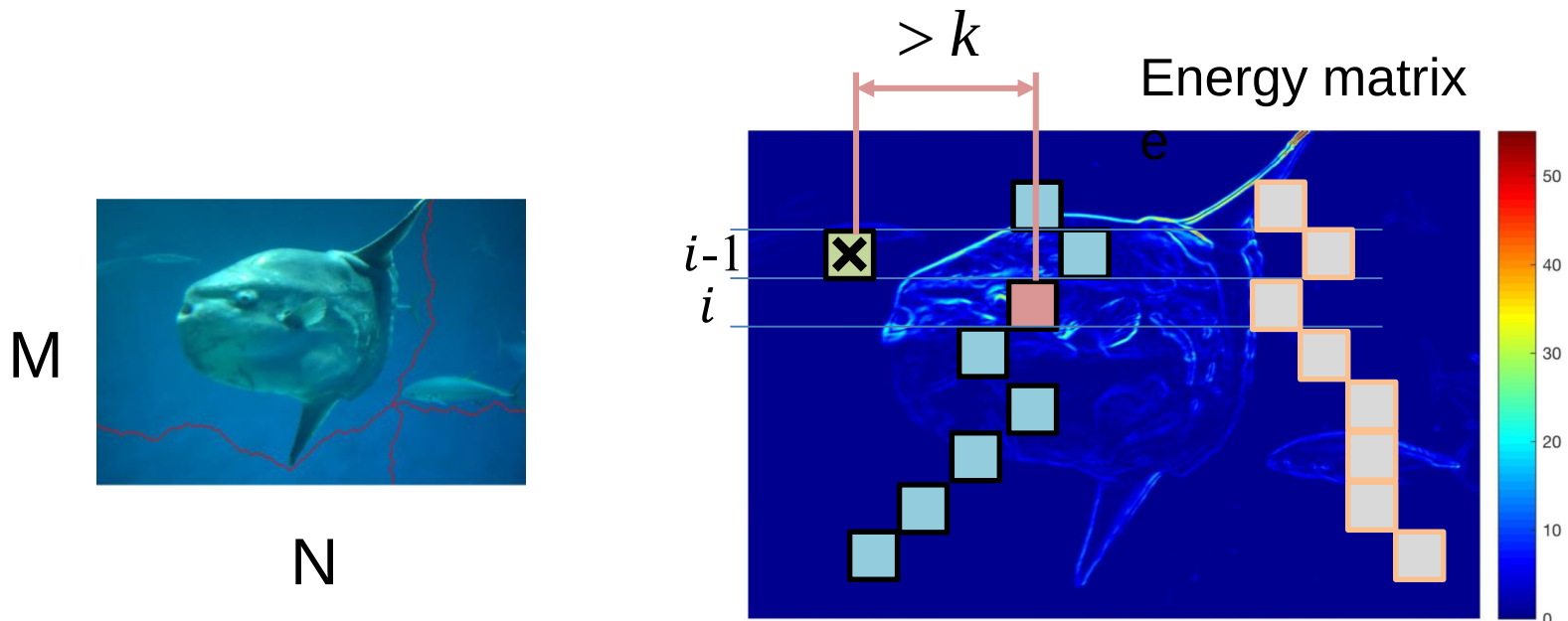
M



N



Seam: $S^y : \{(i, y(i)) \mid i = 1, \dots, M\}$ s.t. $|y(i) - y(i-1)| \leq k$



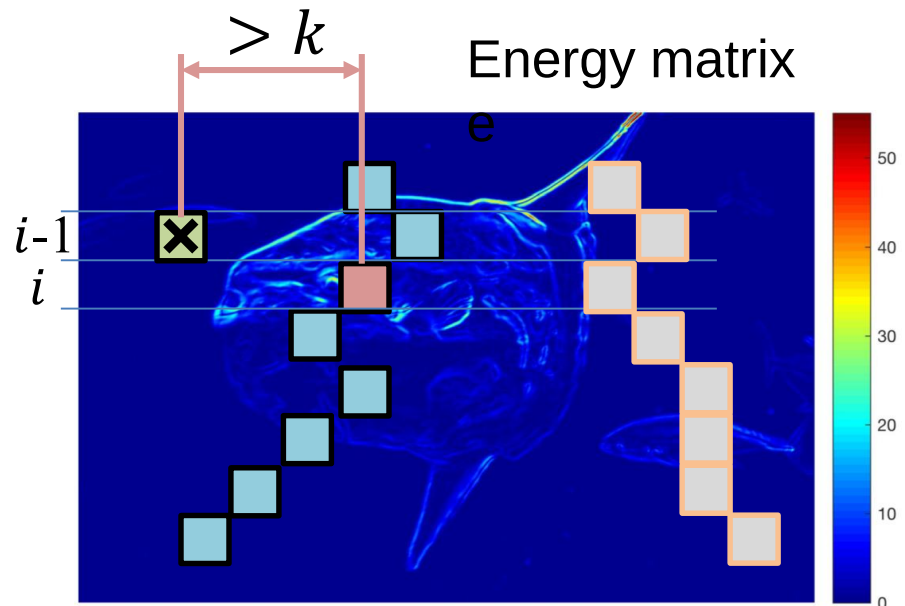
$$S^y : \{(i, y(i)) \mid i = 1, \dots, M\} \text{ s.t. } |y(i) - y(i-1)| \leq k$$

Seam Cost: $E(S^y) = \sum_{i=1}^M e(S^y(i))$

M



N

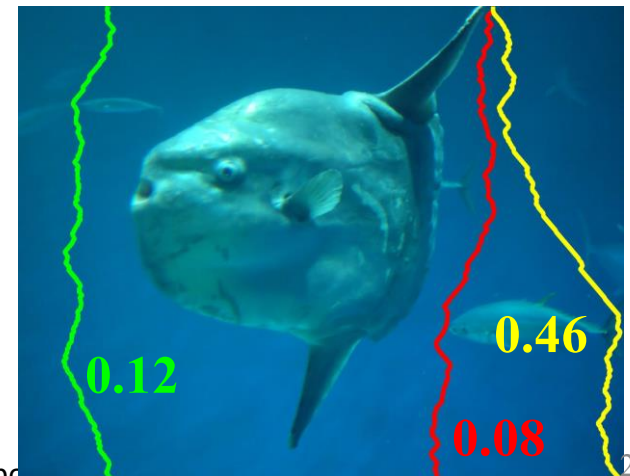


- Seam $S^y: \{(i, y(i)) | i = 1, \dots, M\}$ s.t. $|y(i) - y(i-1)| \leq k$

- Seam Cost:**

$$E(S^y) = \sum_{i=1}^M e(S^y(i))$$

- Goal:** $S^* = \min E(S^y)$



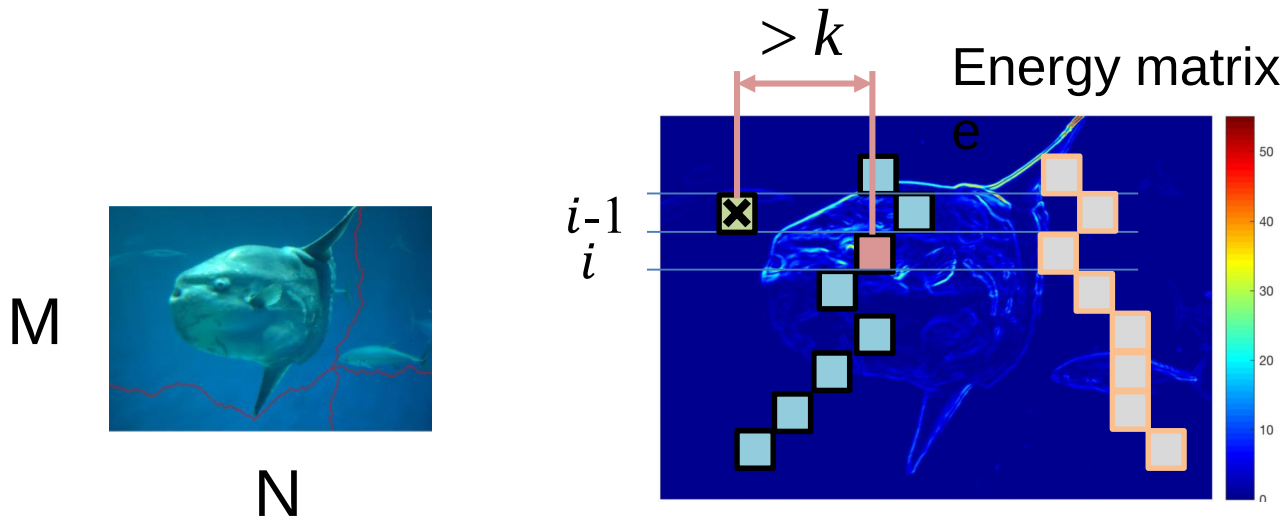
Where does the energy matrix come from?

$$\begin{array}{c}
 \text{abs}(\text{img}) \otimes \text{Energy matrix} \\
 + \\
 \text{abs}(\text{img}) \otimes \text{Energy matrix}
 \end{array}
 = \text{Energy matrix}$$

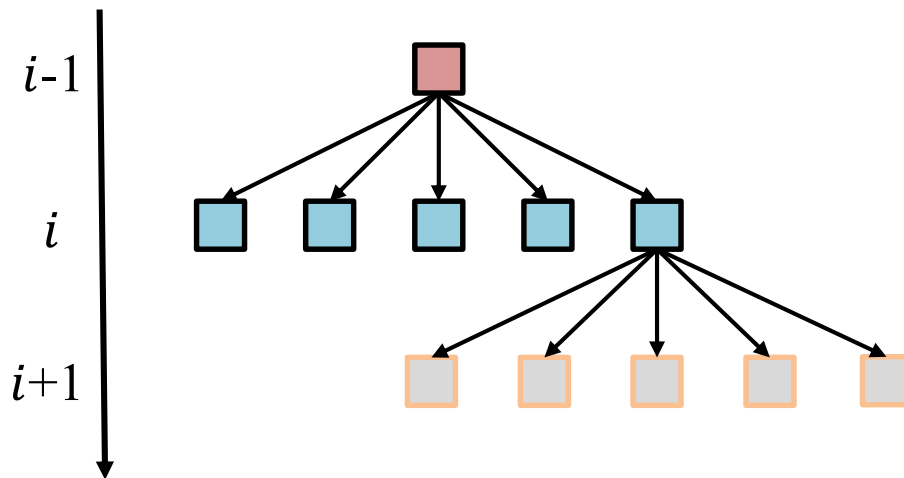
Energy matrix

For example: L1 norm of the edge gradients for the energy function

How to find the best seam?

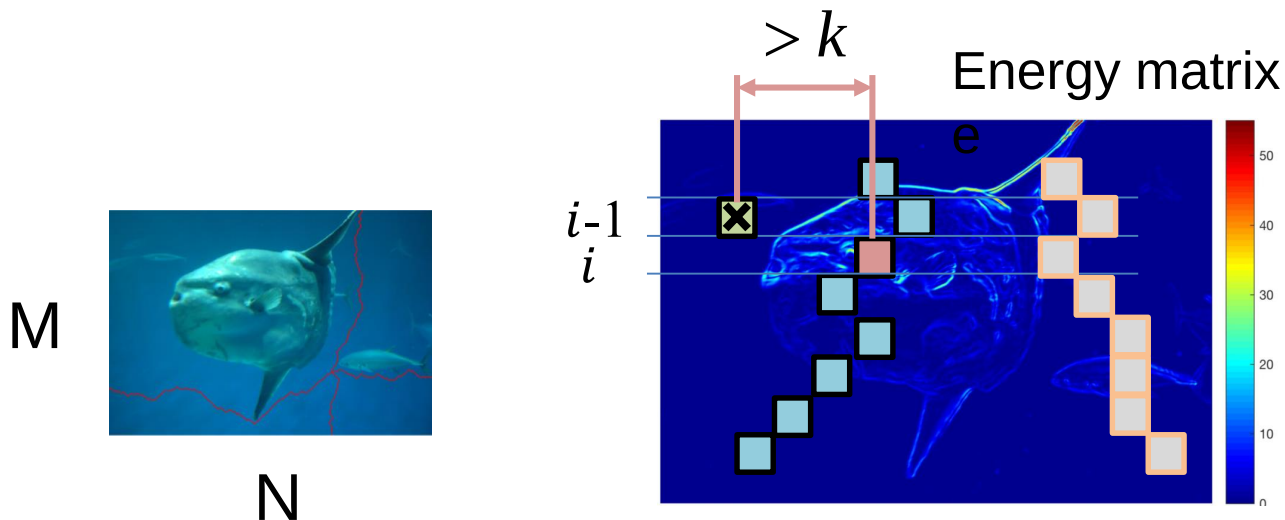


Idea 1: Brute force search

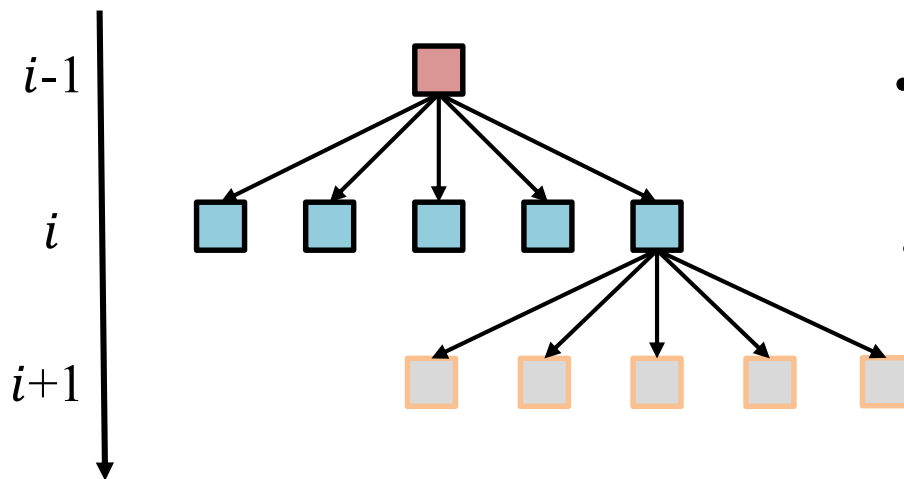


- 1st row: N
- 2nd row: $(2k + 1)N$
- 3rd row: $(2k + 1)^2 N$
-
- M^{th} row: $(2k + 1)^{(M-1)} N$

- How many possibilities for Seam S^y ?



Idea 1: Brute force search



- M^{th} row: $(2k + 1)^{(M-1)}N$

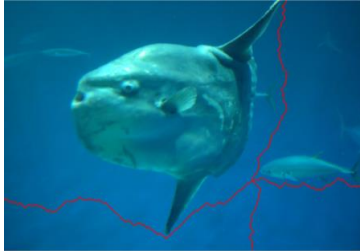
- Given $M = 768, N = 1024, k = 1$

- How many possibilities for Seam S^y ? 1024×3^{767}

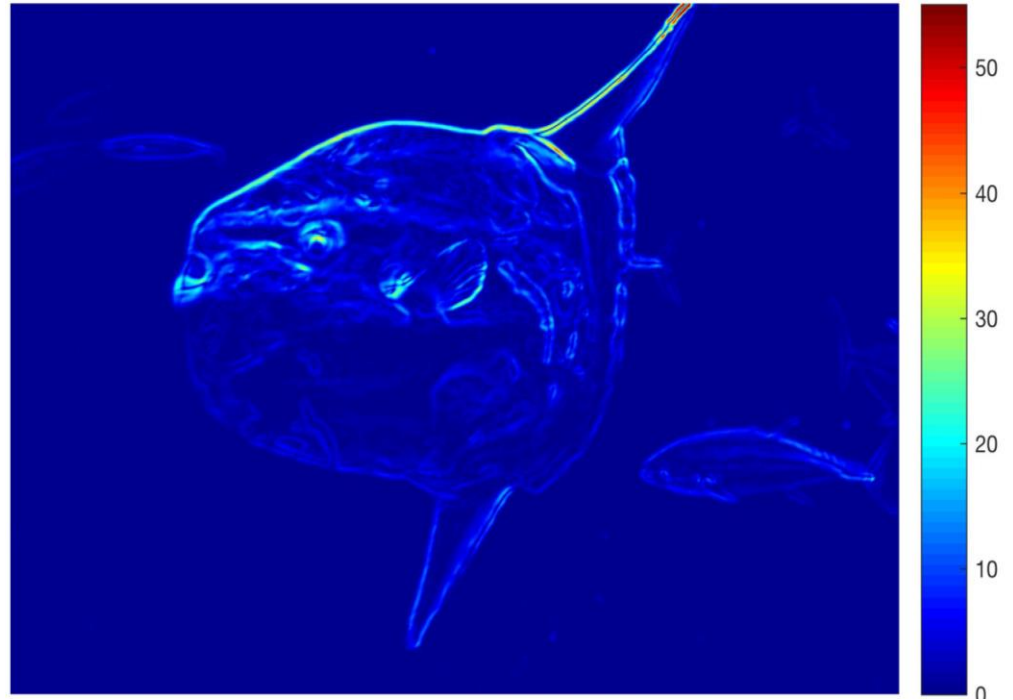
Too many possibilities!

$$1024 \times 3^{767}$$

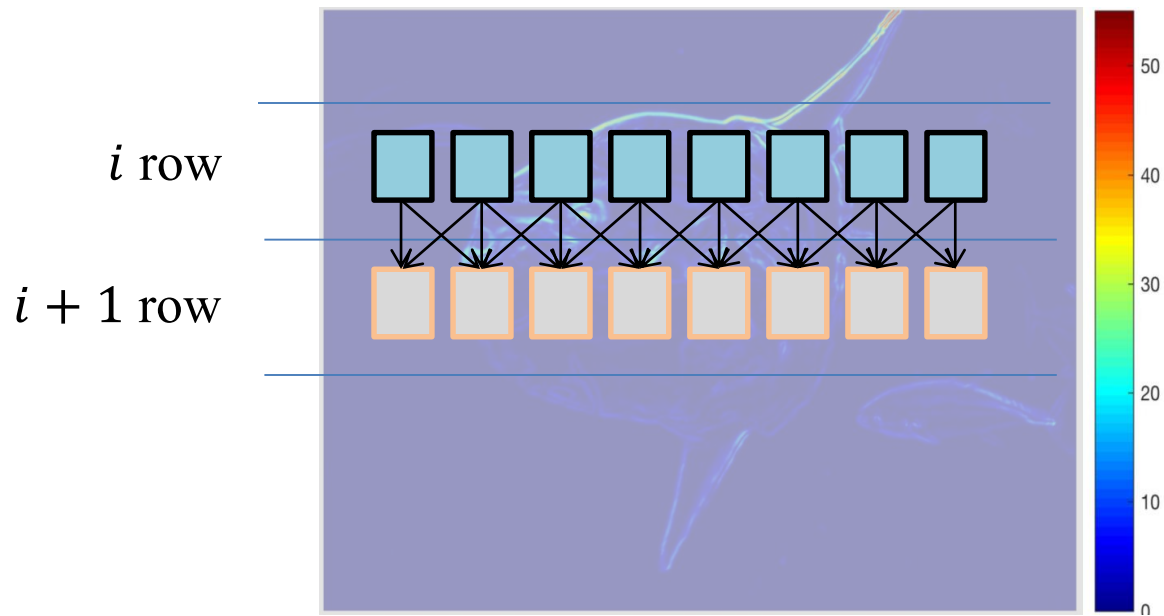
M



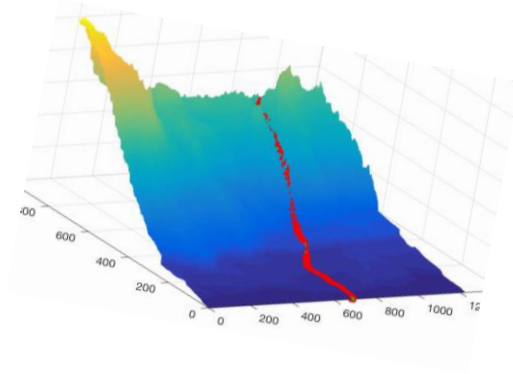
N



Idea 2: Find the shortest path from first
row to the the last row in the energy
domain!

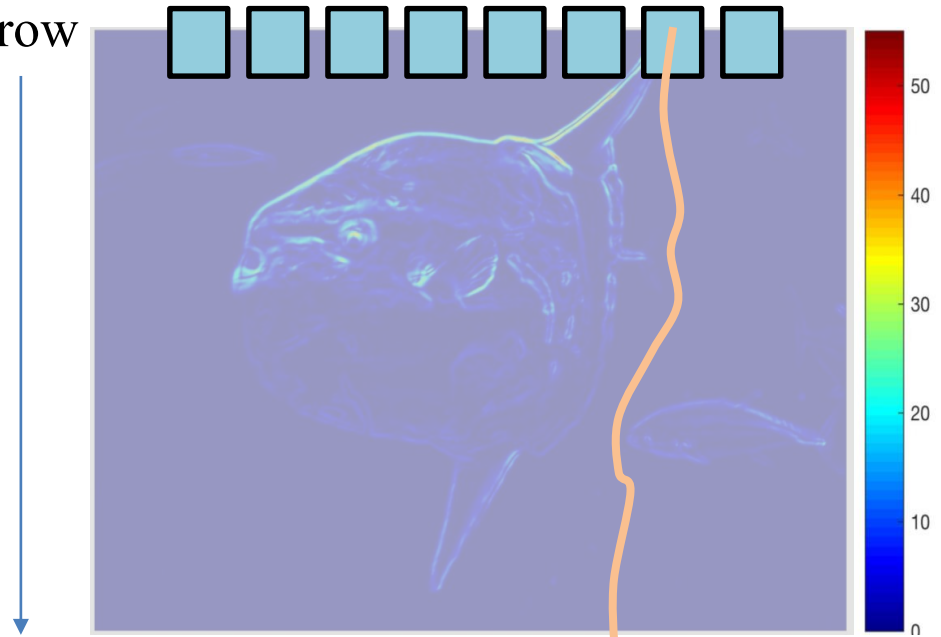


Construct the directed graph where
each pixel (node) is connected to the $(2k+1)$ neighbors in
the next row

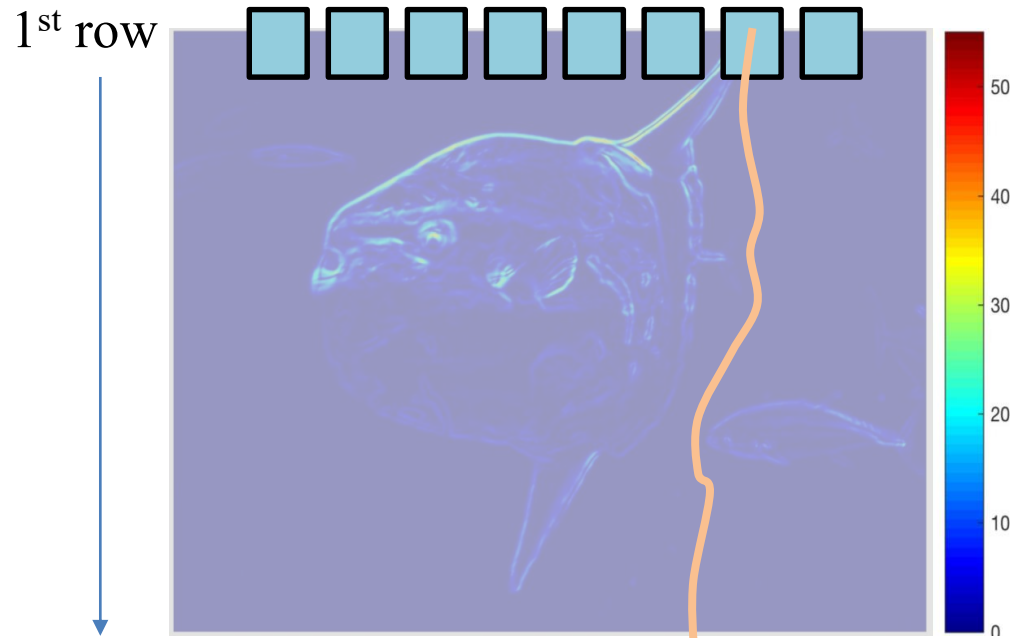


$V(u)$

1st row



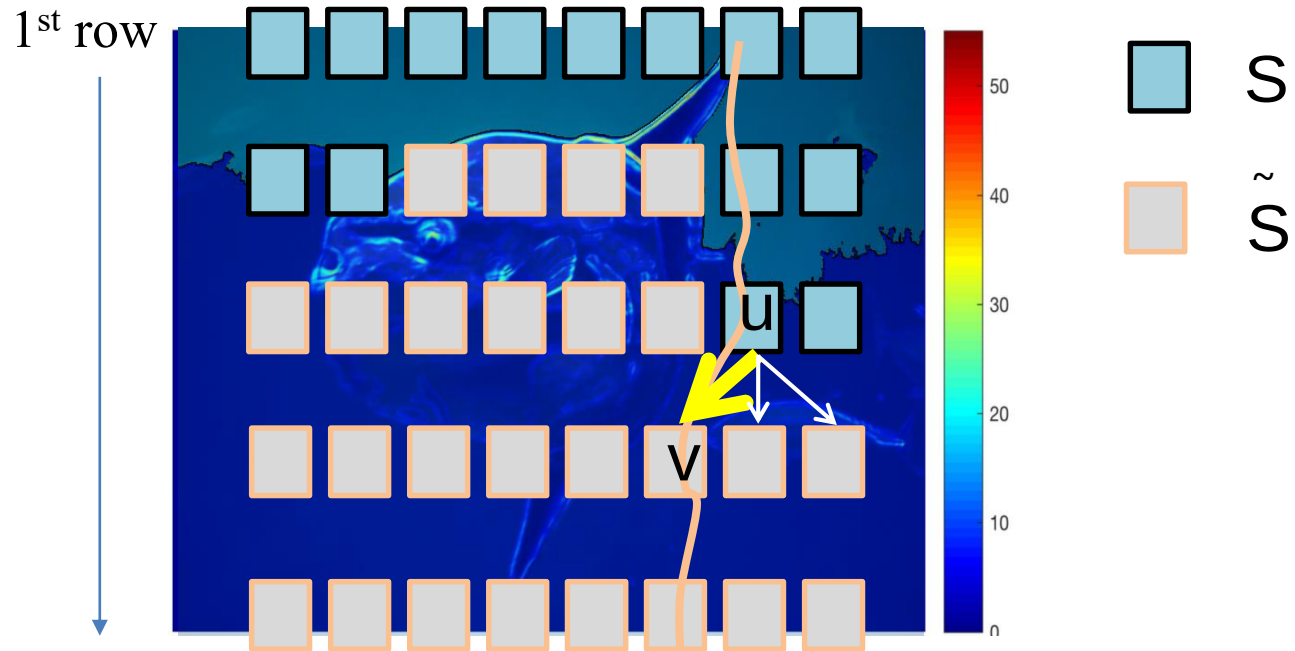
- Create an 'interior' set S , initialize with the first row
- Growing S with 'least-resistant' step
- Construct a 'Value' matrix with value $V(u)$ encoding the shortest path cost to each node in S



- Initialize S to include the first row, and set the Value function

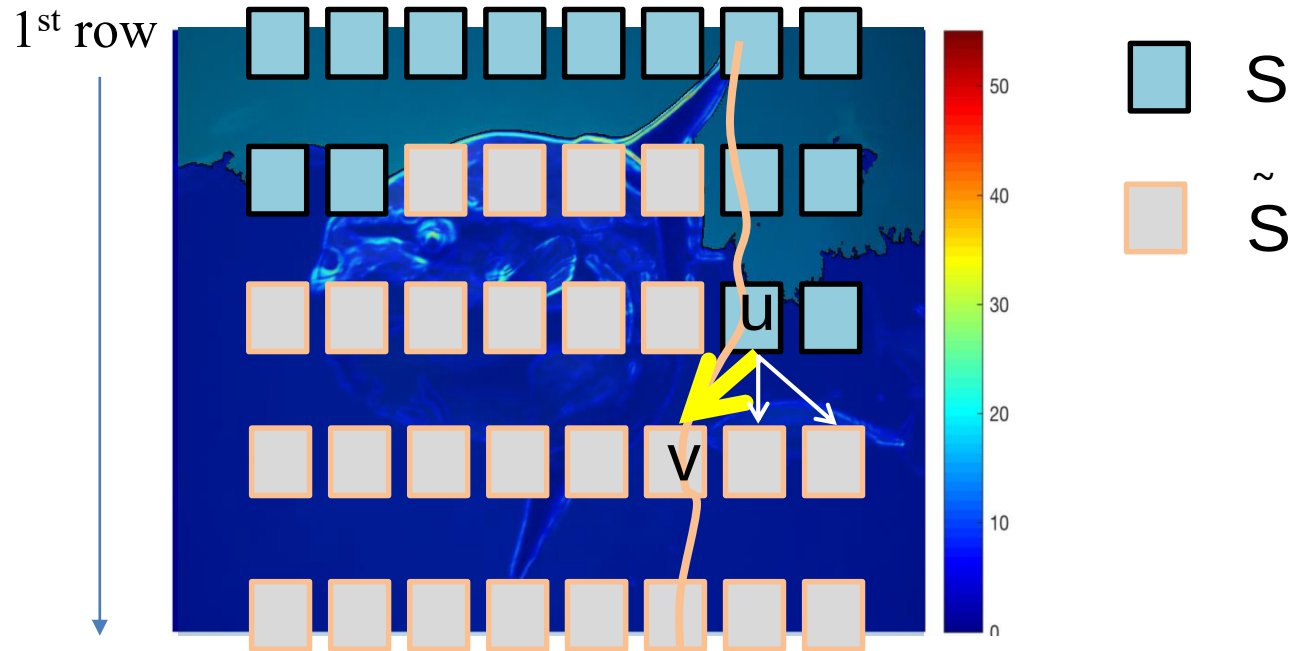
$$V(u) = e(u), u \in S$$

For the first row, the shortest path contains only itself



Iterate: find the step expansion of least resistant from $\tilde{S} \rightarrow S$

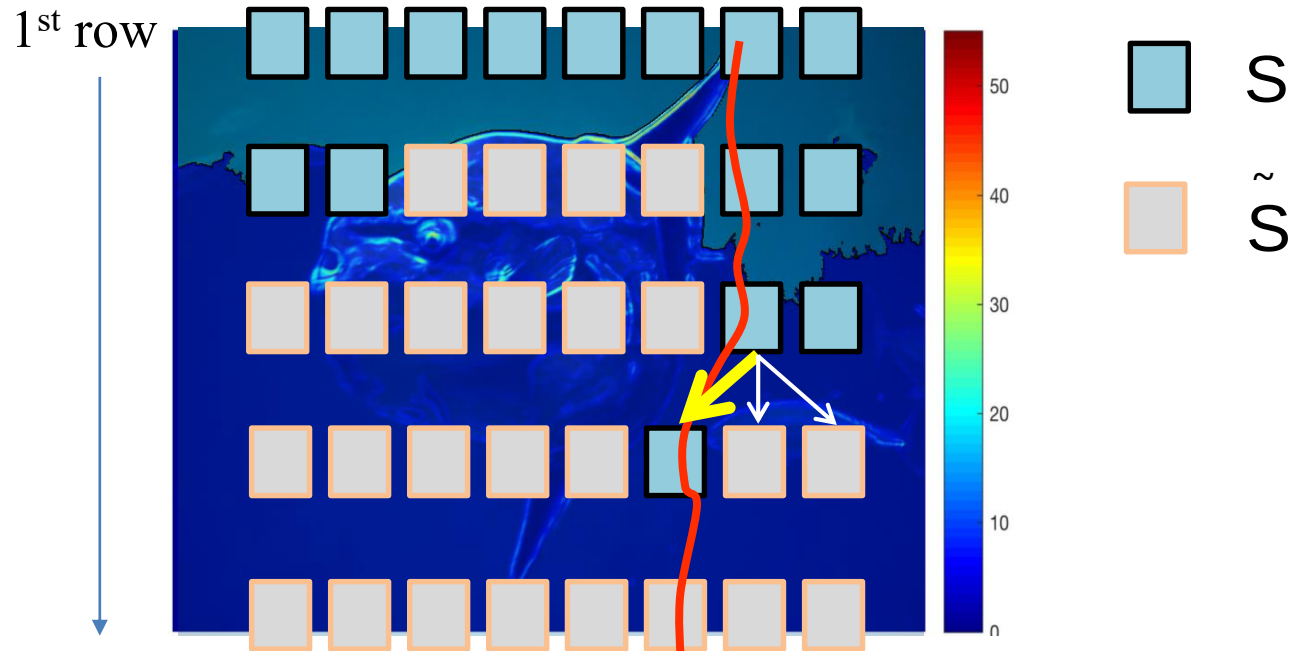
$$v = \underset{u \in S, v \in \tilde{S}}{\operatorname{argmin}} [V(u) + e(v)] \quad \text{where } (u \rightarrow v) \text{ is a graph edge}$$



Iterate: find the step expansion of least resistant from $\tilde{S}_m \rightarrow \tilde{S}$

$$v = \underset{u \in S, v \in \tilde{S}}{\operatorname{argmin}} [V(u) + e(v)] \quad \text{where } (u \rightarrow v) \text{ is a graph edge}$$

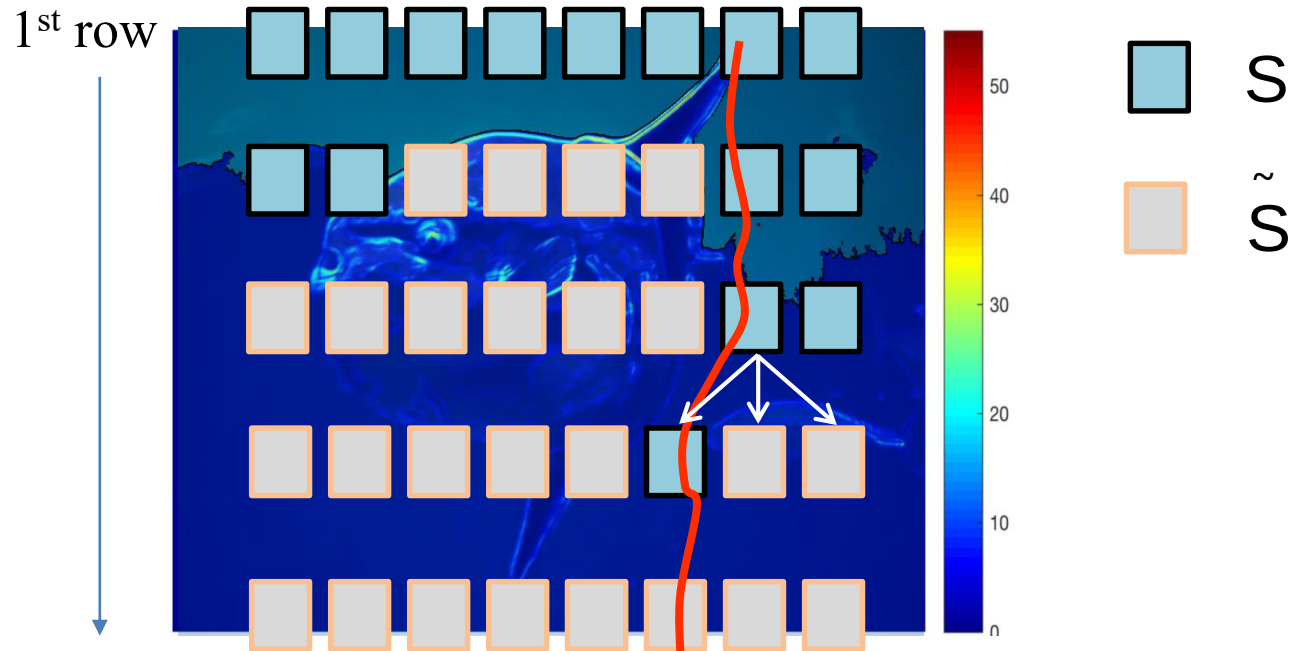
Remember the path back from $(v \rightarrow u) P(v) = u$



- Updating the “interior” set: $S = S \cup \{v\}$, $\tilde{S} = \tilde{S} \setminus \{v\}$.

- Updating the Value function $V(v) = \min_{u \in \tilde{S}} [V(u) + e(v)]$

$V(v)$: Is the **contingent cost** of the shortest path connecting the pixel v to the first row

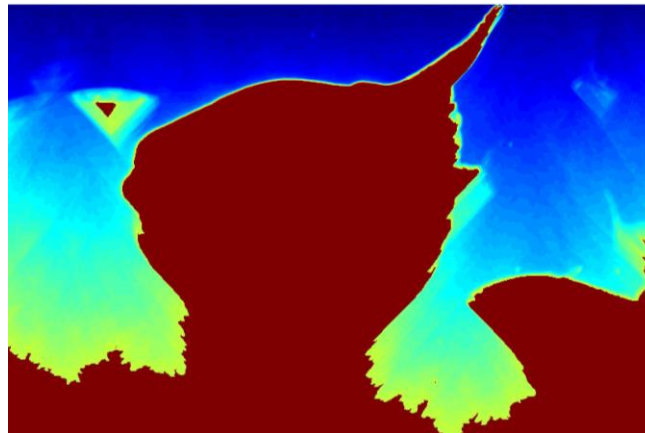


- Updating the “interior” set: $S = S \cup \{v\}$, $\tilde{S} = \tilde{S} \setminus \{v\}$.
- Updating the Value function: $V(v) = \min_{v \in \tilde{S}} [V(u) + e(v)]$
- Until reaching one of the pixels on the last row.

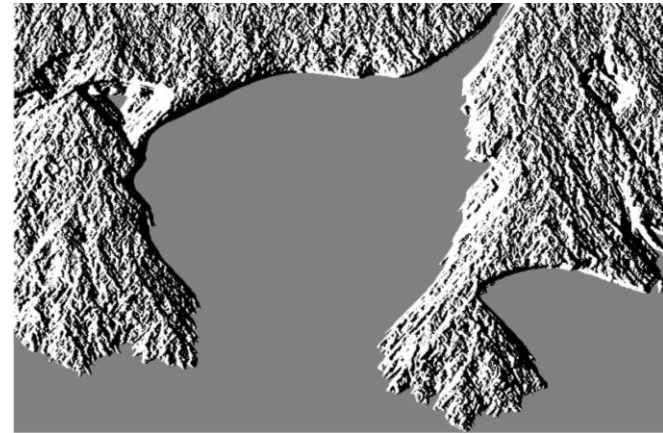
Energy Matrix e



Value function $V(u)$



Path Matrix P





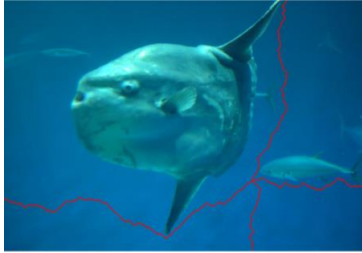
Video 9.3

Jianbo Shi

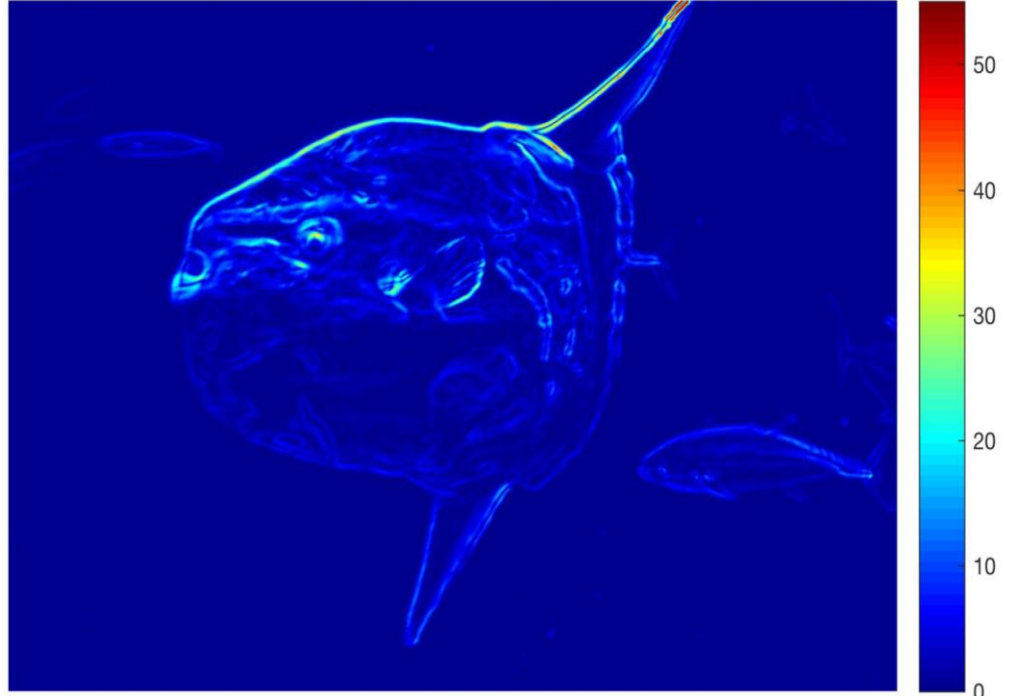
Dynamic Programming

Frontier growing row by row

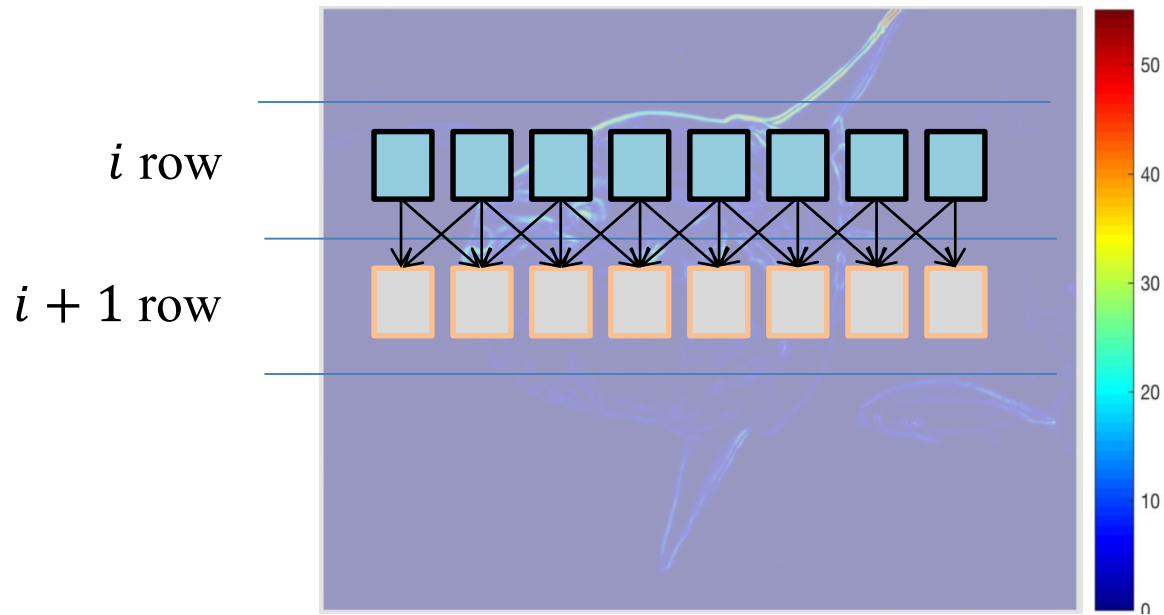
M



N

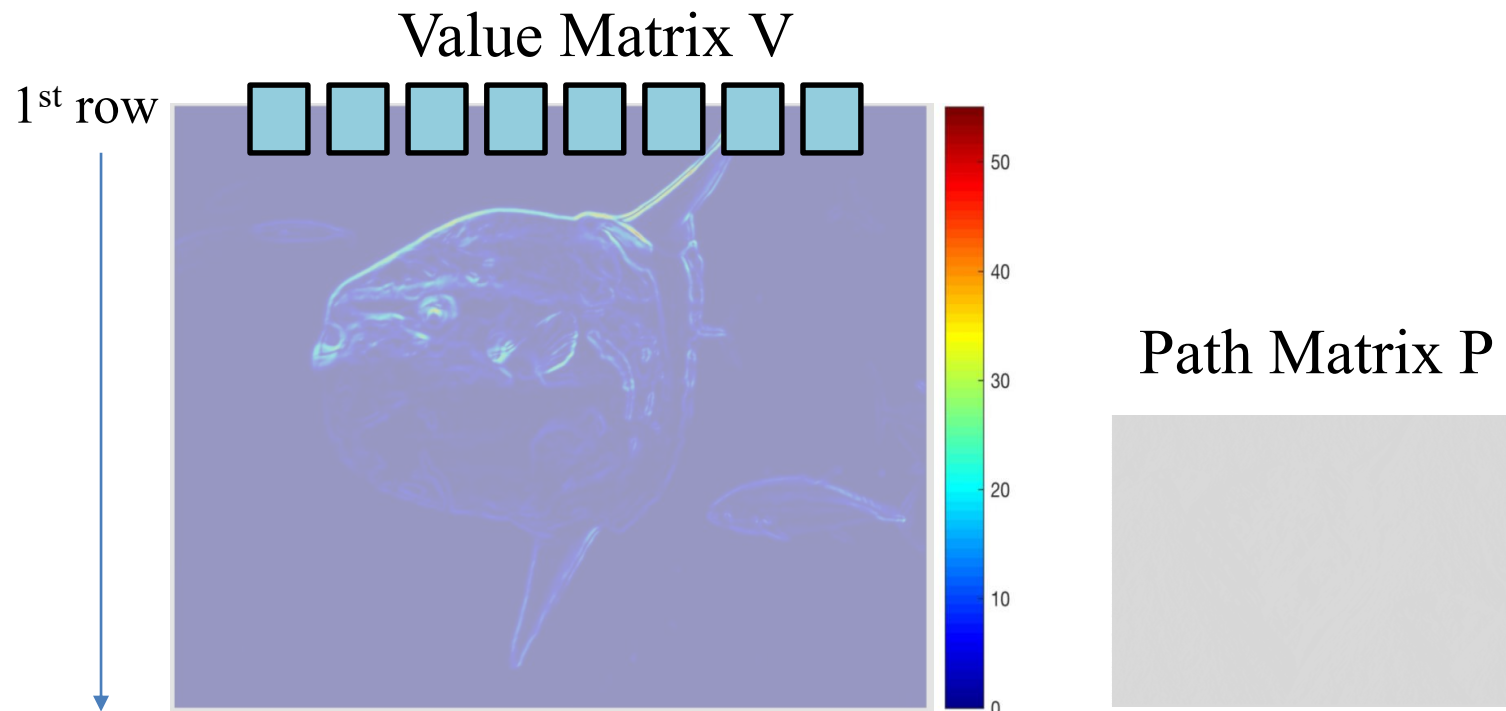


Idea 3: Dynamic programming!



Use the same graph structure

Propagate the frontier row by row to construct the Value
Matrix

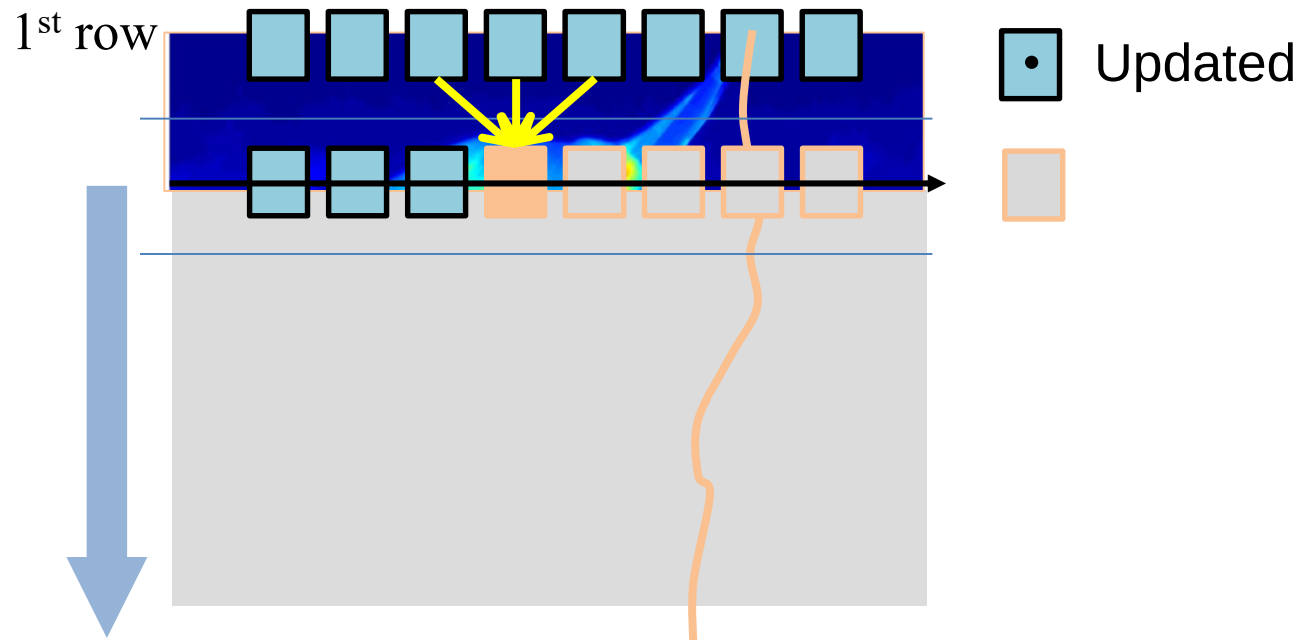


- Still start from first row, and initialize the Value function

$$V(1, j) = e(1, j)$$

- Set the Path function

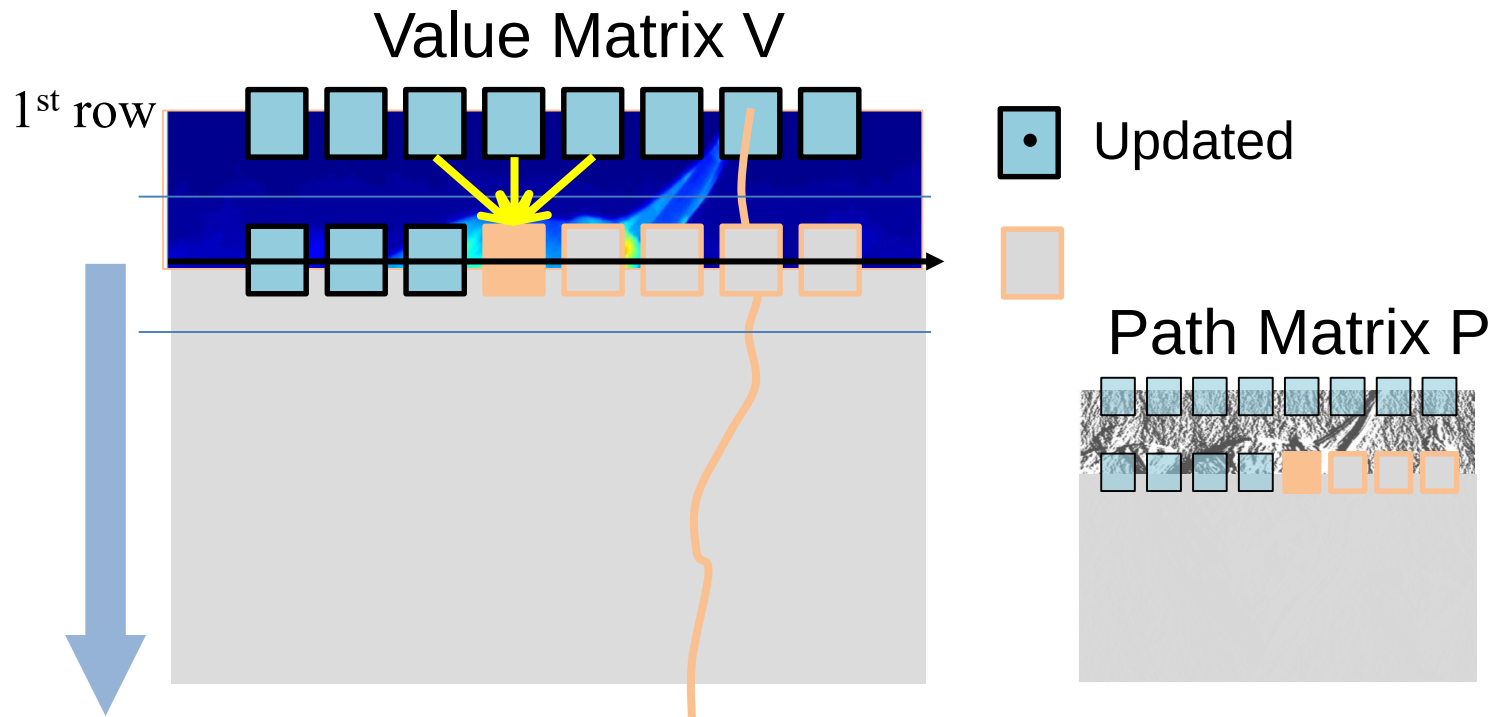
$$P(1, j) = 0$$



- Propagate to the second row, and update the value matrix

$$V(2,j) = e(2,j) + \min(V(1,j-k), \dots, V(1,j), \dots, V(1,j+k))$$

$V(2,j)$: Is the **contingent cost** of the shortest path connecting the pixel **(2,j)** to the first row

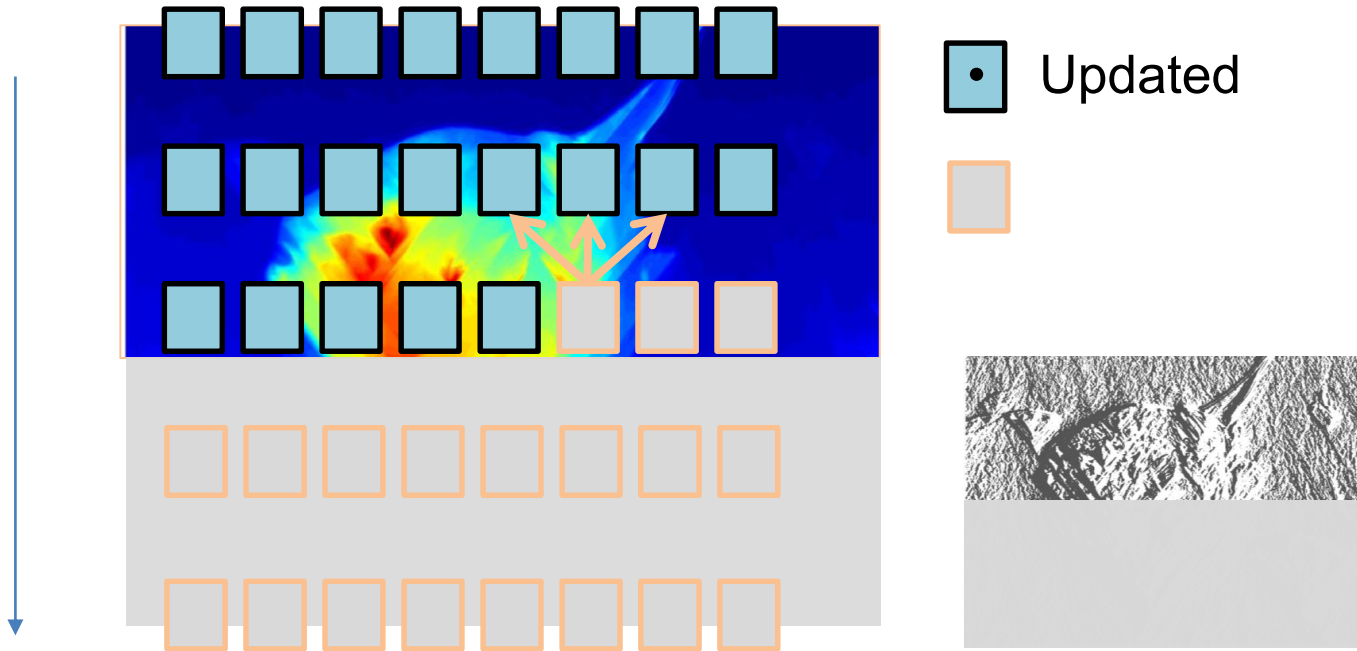


- Propagate to the second row, and update the value matrix

$$V(2,j) = e(2,j) + \min(V(1,j-k), \dots, V(1,j), \dots, V(1,j+k))$$

- Set the Path function

$$P(2,j) = \operatorname{argmin}(V(1,j-k), \dots, V(1,j), \dots, V(1,j+k))$$



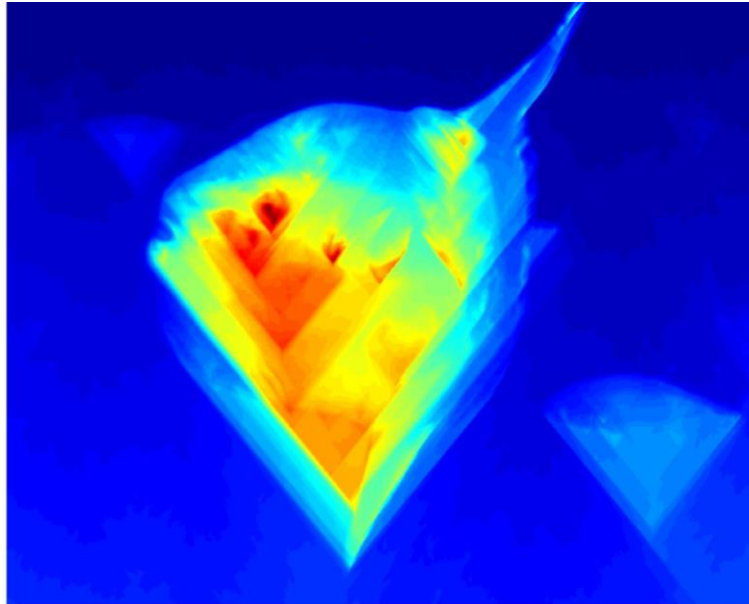
- Iteratively propagate to the **ith** row, and update the value matrix

$$V(i,j) = e(i,j) + \min(V(i-1,j-k), \dots, V(i-1,j), \dots, V(i-1,j+k))$$

- Set the Path function

$$P(i,j) = \operatorname{argmin}(V(i-1,j-k), \dots, V(i-1,j), \dots, V(i-1,j+k))$$

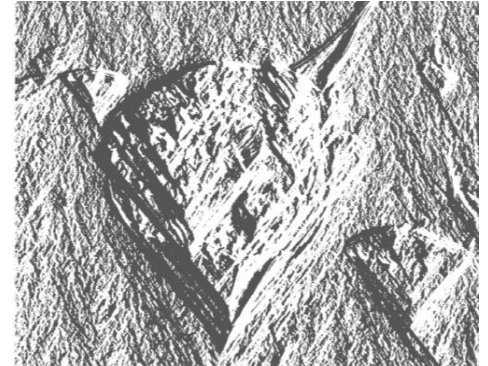
Value Matrix V



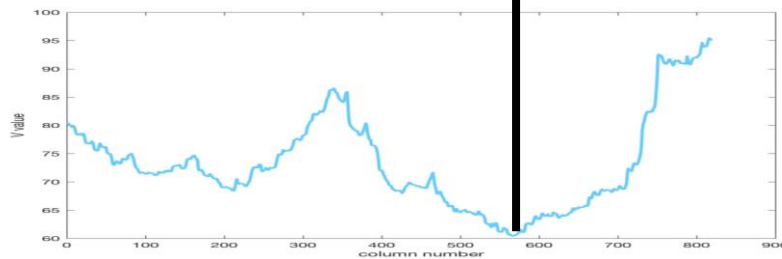
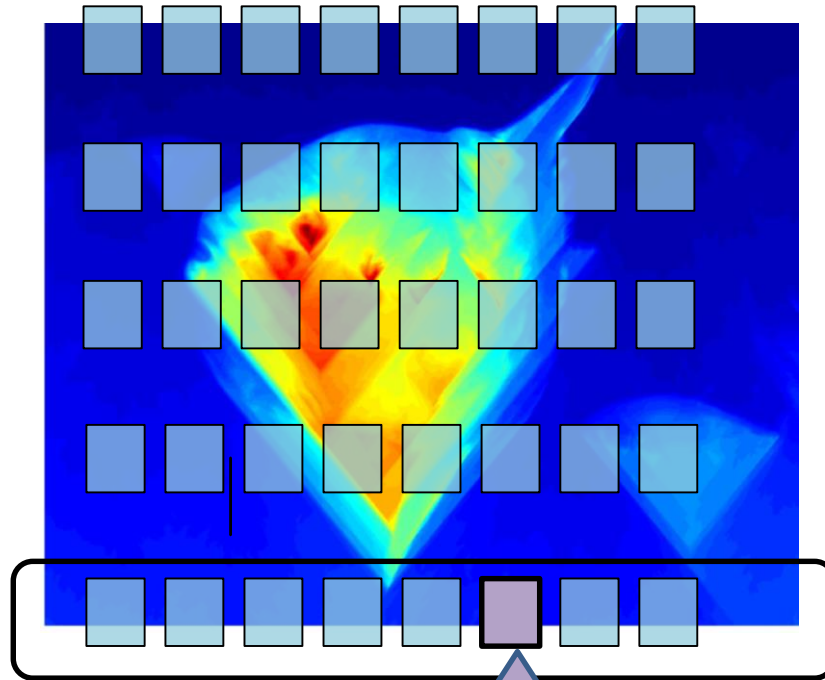
Energy Matrix e



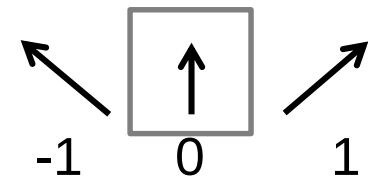
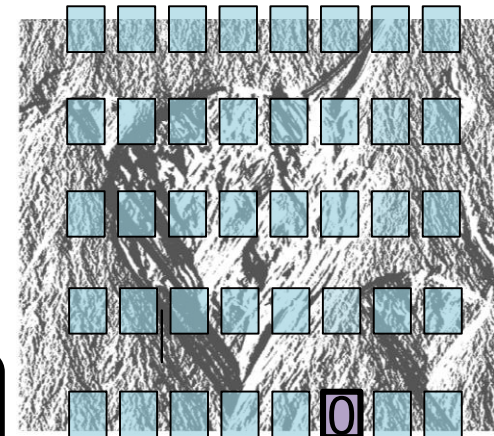
Path Matrix P



Value Matrix V



Path Matrix P

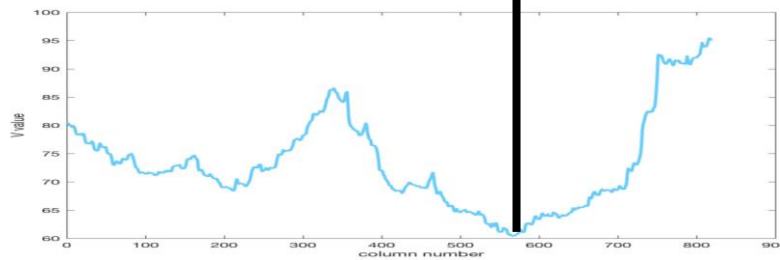
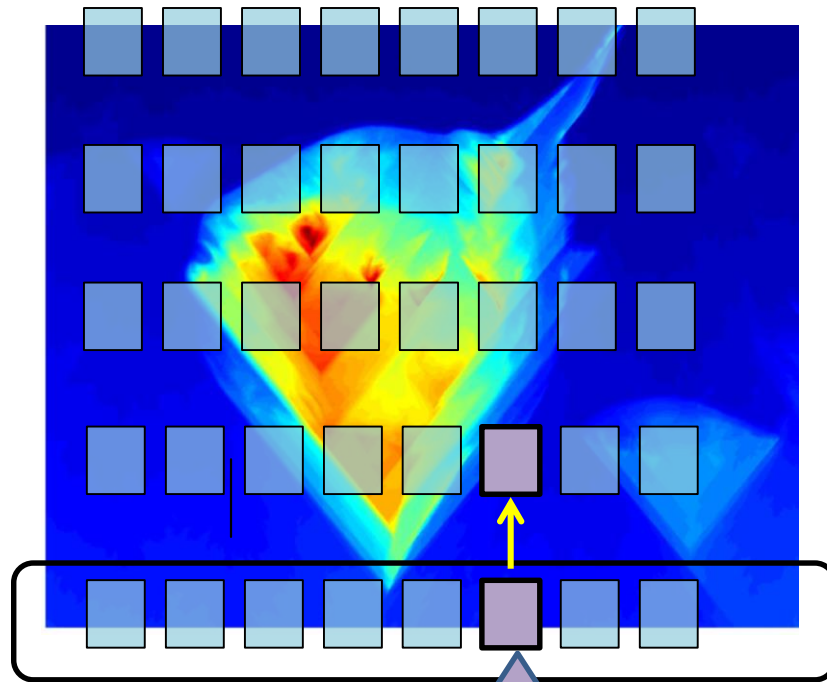


- Localize the minimum of the last row of

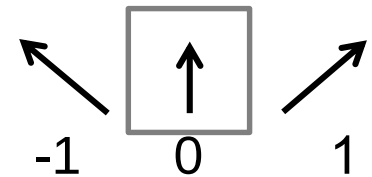
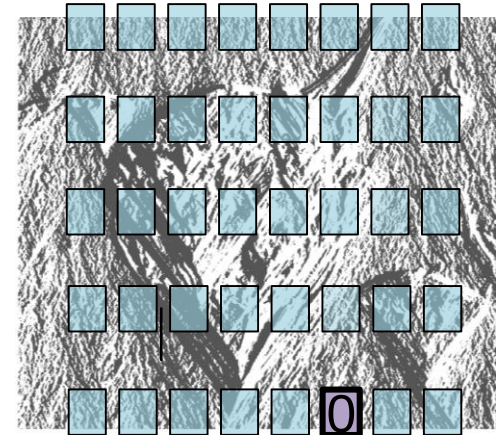
$$\text{argmin } V(M, :)$$

Property of Penn Engineering, Jianbo Shi

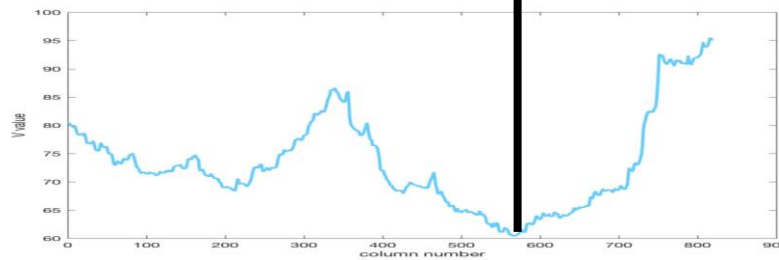
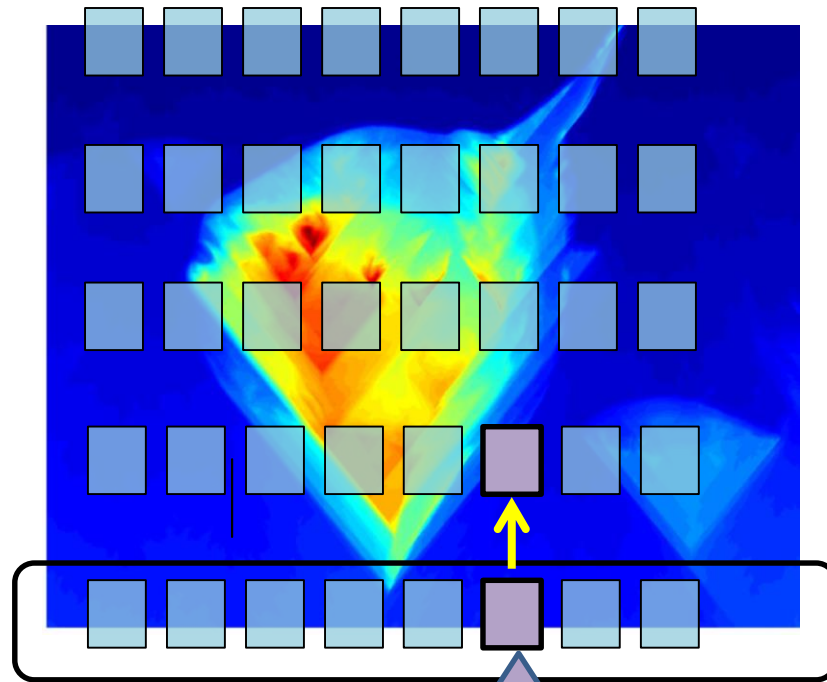
Value Matrix V



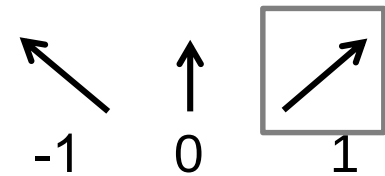
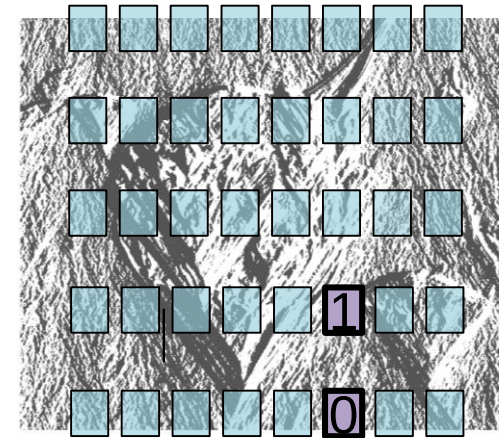
Path Matrix P



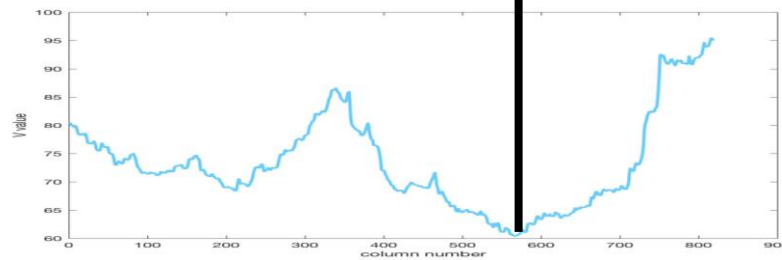
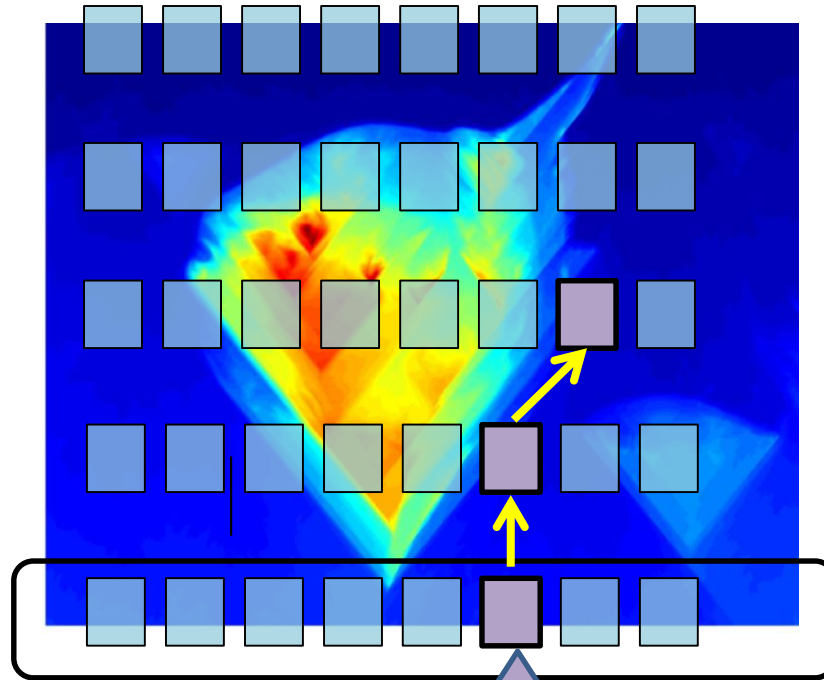
Value Matrix V



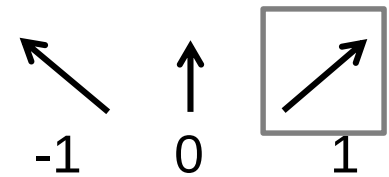
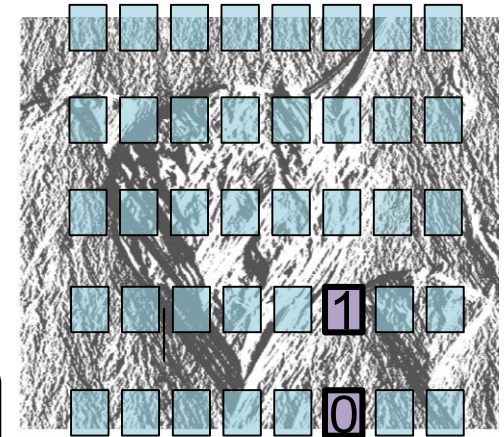
Path Matrix P



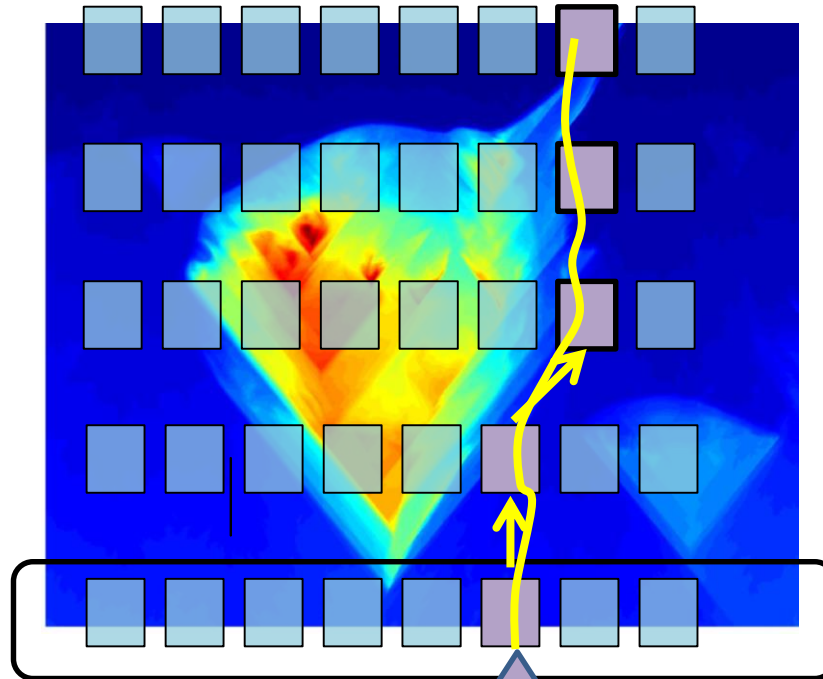
Value Matrix V



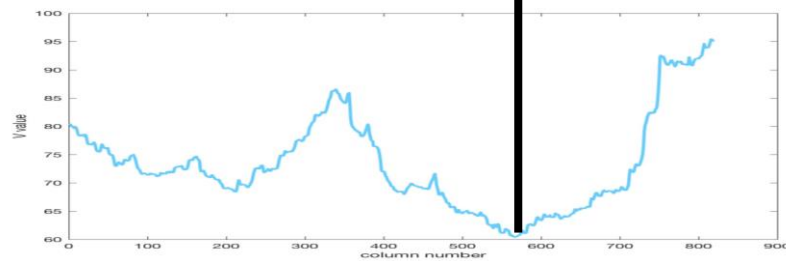
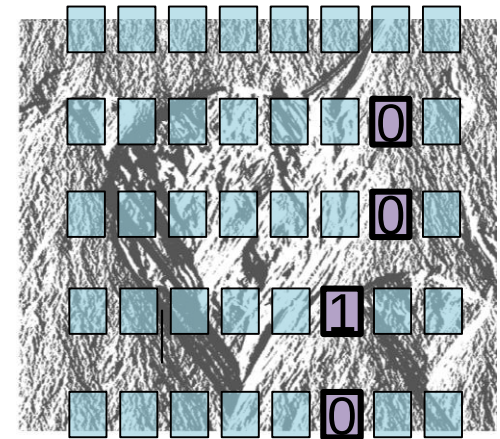
Path Matrix P

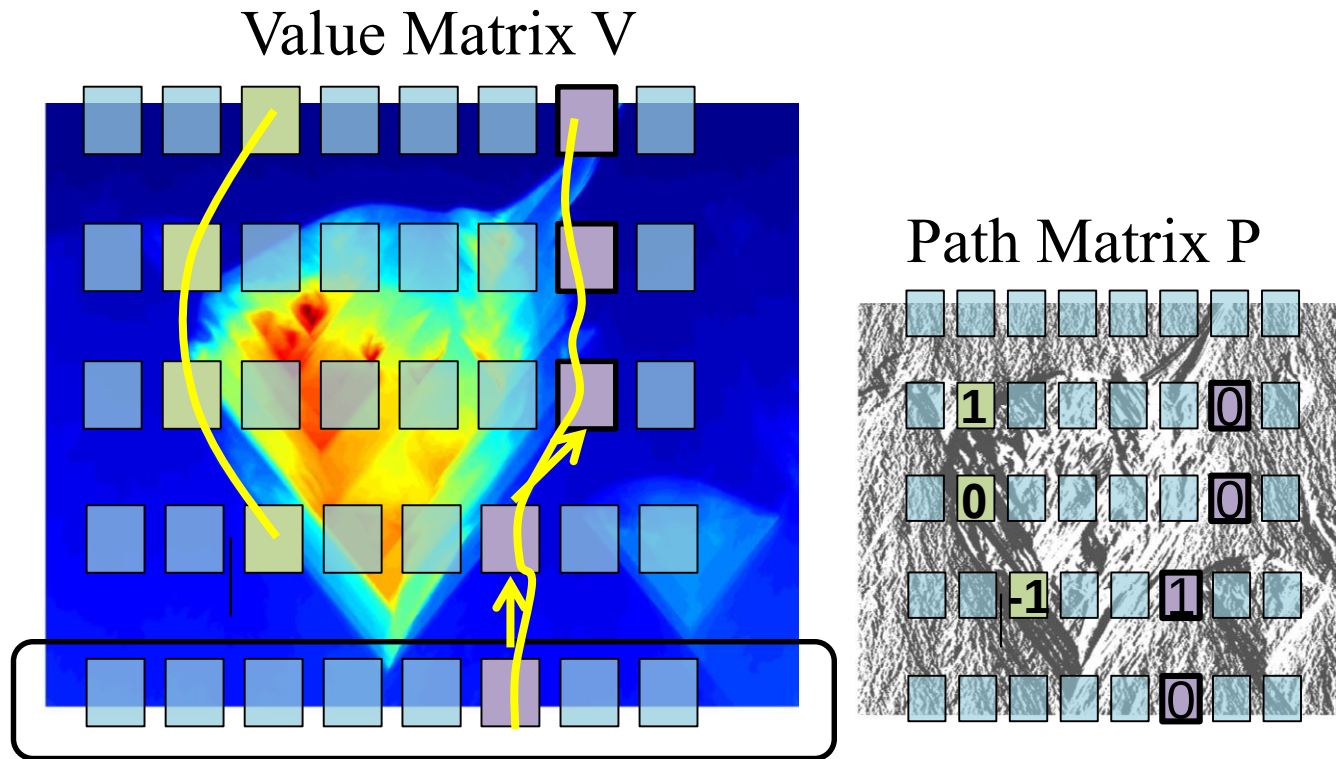


Value Matrix V



Path Matrix P





- Since V is the contingency table, we can start from any pixel and find a shortest path to the first row!

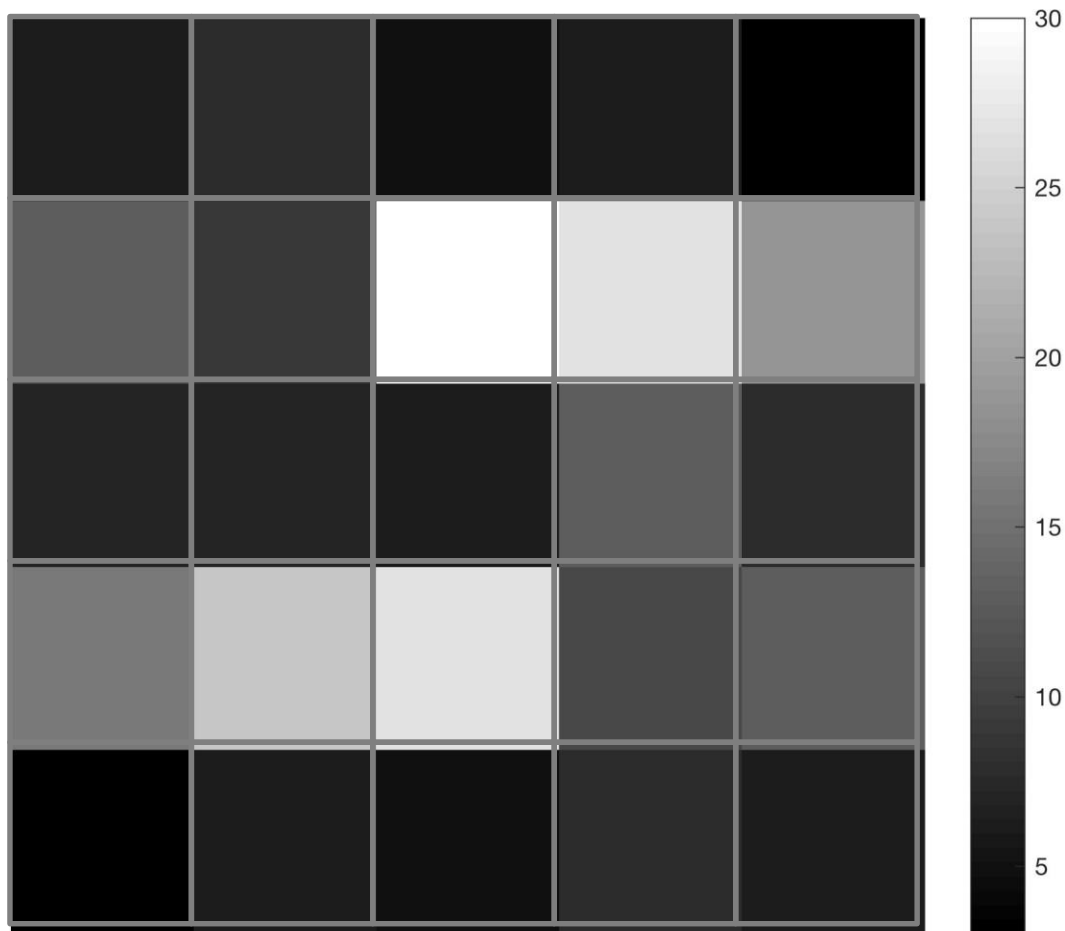


Video 9.4

Jianbo Shi

Illustration for synthetic case

Energy matrix



Energy matrix



Value matrix



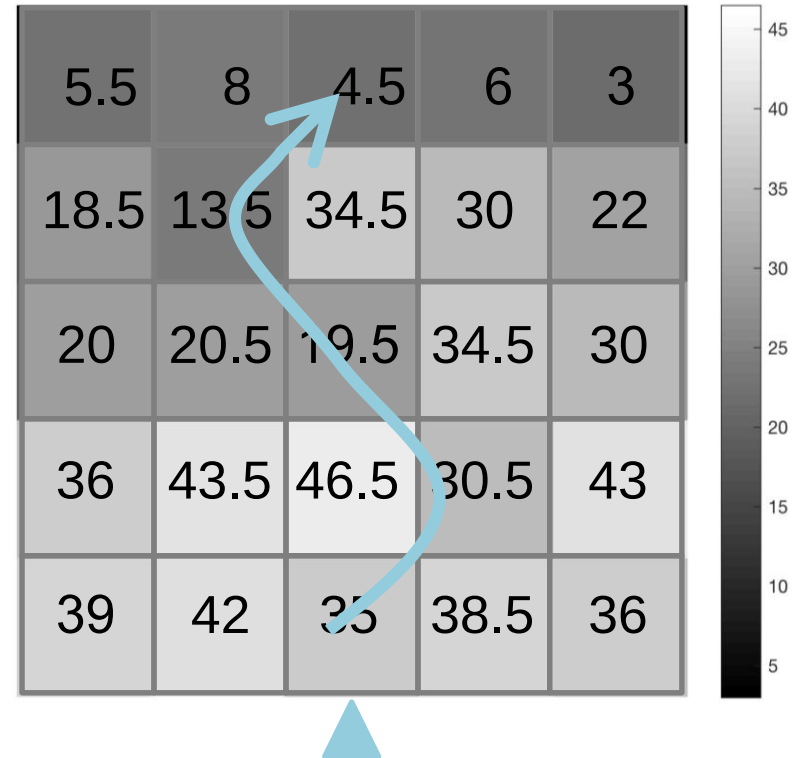
Goal:

- Construct **value and path matrix** from the **energy matrix**
- **Value matrix** records the **energy of the shortest path** from the starting row to the current pixel

Energy matrix

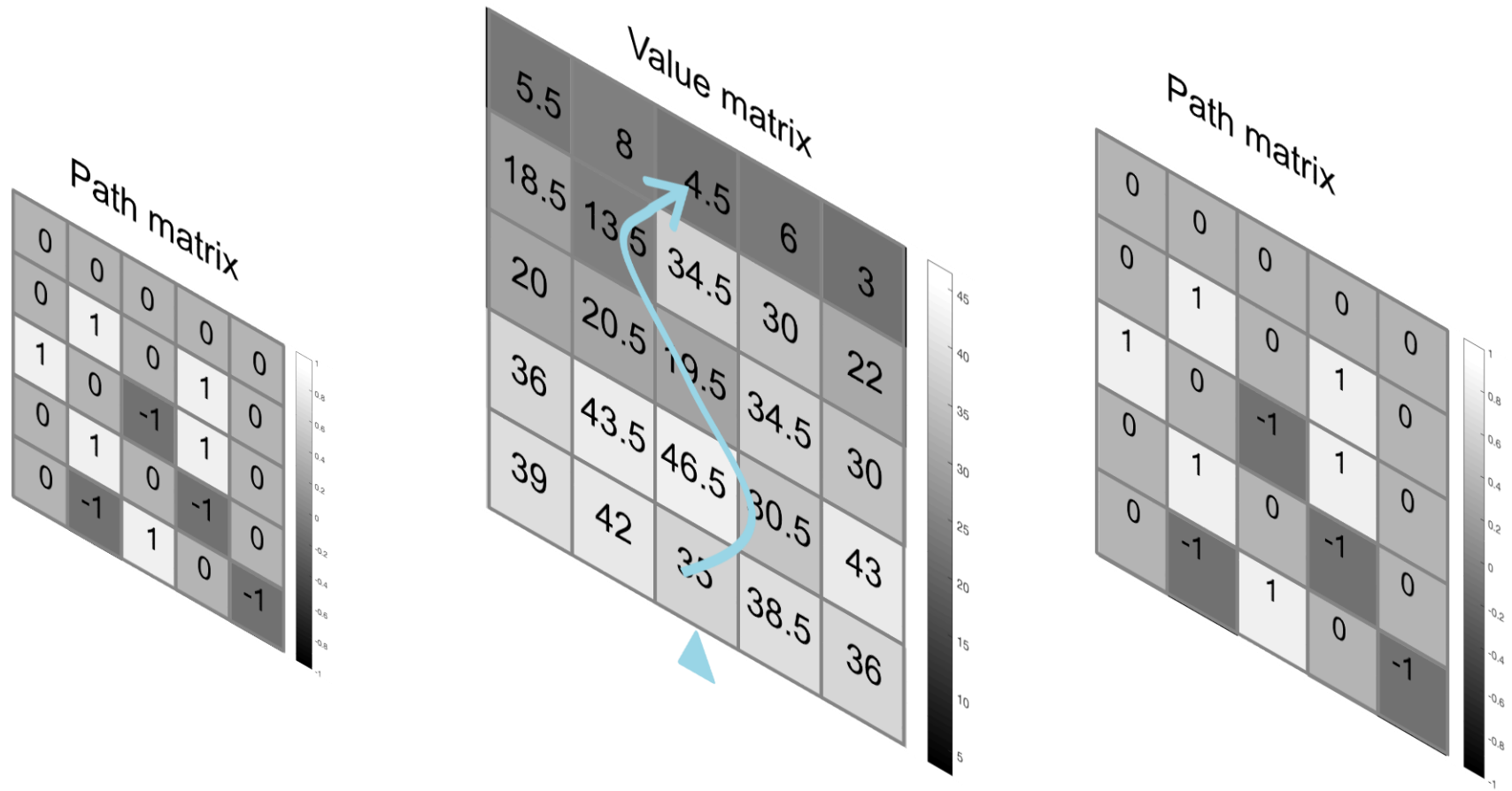


Value matrix



Goal 1:

- Construct **Value matrix** from the **energy matrix**
- **Value matrix** records the **energy of the shortest path** from the starting row to the current pixel
- Property: every entry encodes the minimal shortest path to that node from starting row



Goal 2:

- Construct **Path matrix**
- The Path matrix records the immediate predecessor in the shortest path, for every node



e : energy function



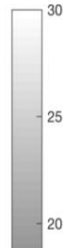
Energy function

- Energy function records the cost of a pixel.
- Typically it is the image gradient magnitude

How to generate the two matrices?

Energy matrix

5.5	8	4.5	6	3
13	9	30	27	19



Value matrix V

5.5	8	4.5	6	3
18.5	13.5	34.5	30	22
20	20.5	19.5	34.5	30
36	43.5	46.5	30.5	43
39	42	35	38.5	36

Path matrix

0	0	0	0	0
0	1	0	0	0
1	0	0	1	0
0	1	0	1	0
0	-1	0	-1	0

Step1: Initializing two matrices

- Set value and path matrix **the same size** as the energy matrix
- Initialize its **first row of Value matrix** with that of the energy matrix
- Initialize its **first row of path matrix** to zero

Value matrix V

5.5	8	4.5	6	3
18.5	13.5	34.5	30	22
20	20.5	19.5	34.5	30
36	43.5	46.5	30.5	43
39	42	35	38.5	36



Step2: Propagation

- Start with 2nd row, and propagate row by row

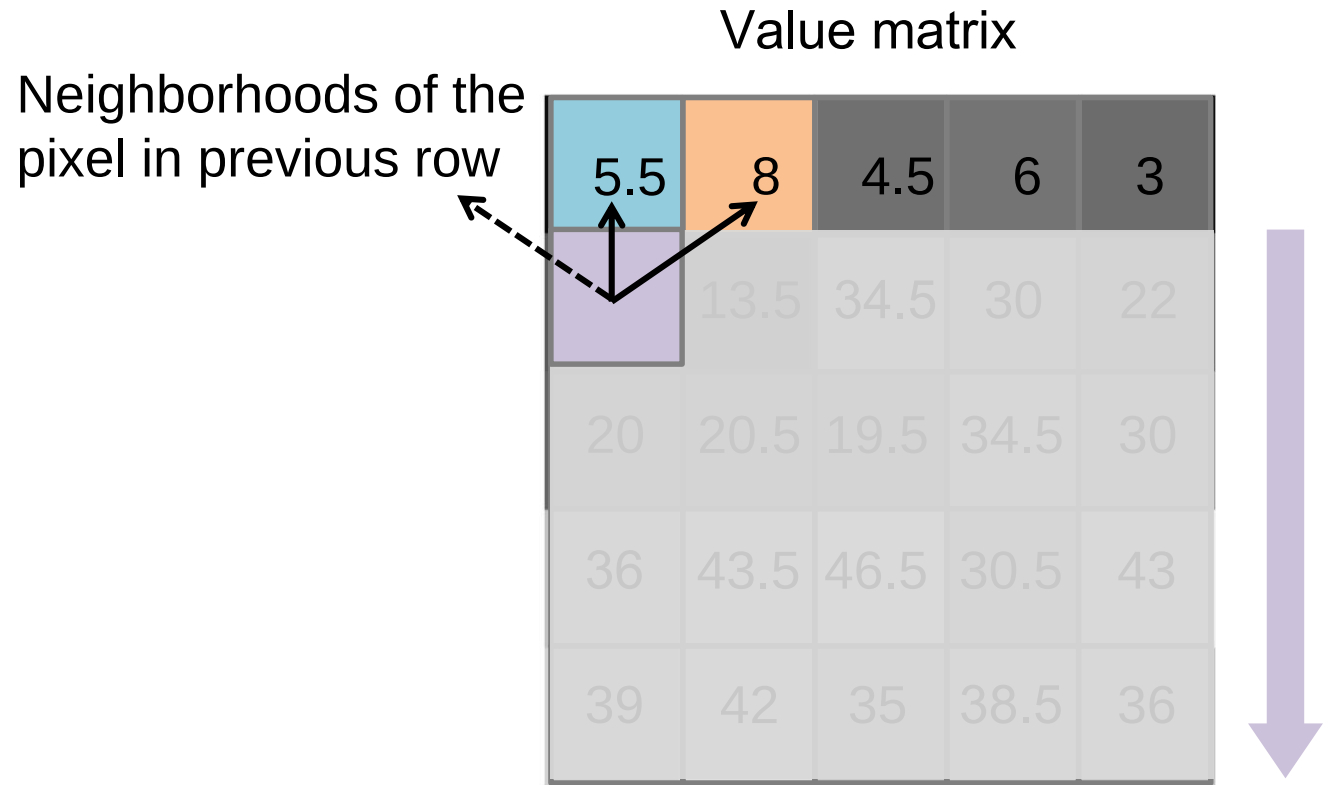
Value matrix V

5.5	8	4.5	6	3
?	13.5	34.5	30	22
20	20.5	19.5	34.5	30
36	43.5	46.5	30.5	43
39	42	35	38.5	36



Step2: Propagation

- Start with 2nd row



Step2: Propagation

- Start with 2nd row
- Find the **neighbors** of the pixel in the previous row

$$V(2,1) = \min \left(\begin{array}{c} V(1,1) \\ V(1,2) \end{array} \right) + e(2,1)$$

5.5 8

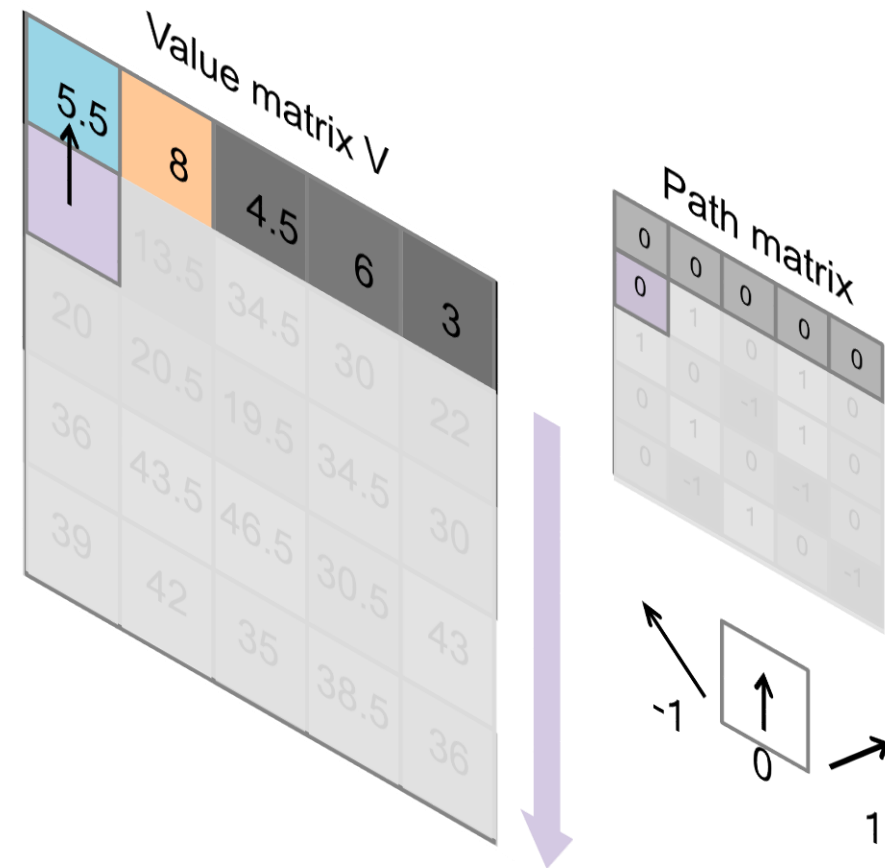
Value matrix V

5.5	8	4.5	6	3
13.5	34.5	30	22	
20	20.5	19.5	34.5	30
36	43.5	46.5	30.5	43
39	42	35	38.5	36



Step2: Propagation

- Start with 2nd row
- Find the **neighbors** of the pixel in the previous row
- Find the **minimum** among neighbors



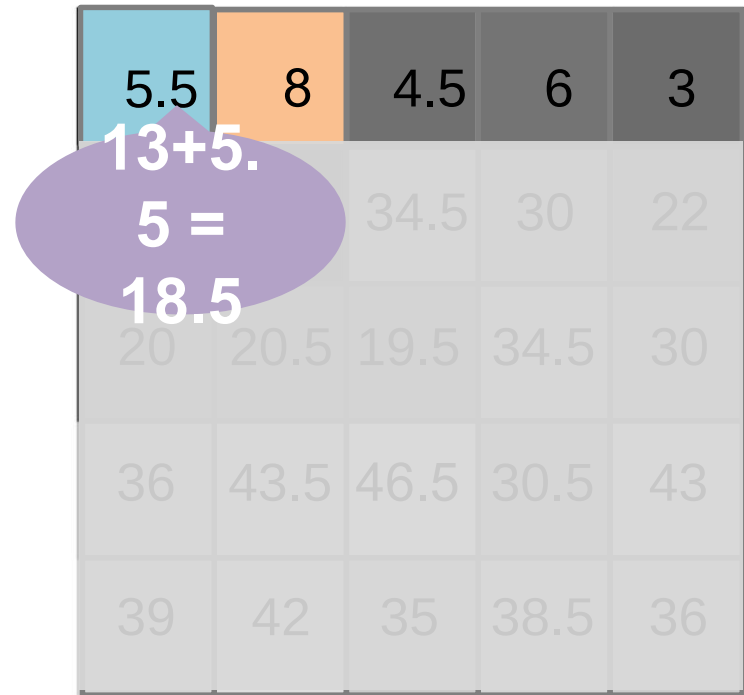
Step2: Propagation

- Start with 2nd row
- Find the **neighbors** of the pixel in the previous row
- Find the **minimum** among neighbors, record it in Path matrix

Energy matrix



Value matrix V



$$V(2,1) = \min \begin{pmatrix} V(1,1) \\ V(1,2) \end{pmatrix} + e(2,1)$$

5.5
8
13

✓

Step2: Propagation

- Start with 2nd row,
- Find the **neighbors** of the pixel in the previous row
- Find the **minimum** among neighbors
- Add the **energy value** of the pixel with the minimum

Value matrix V

5.5	8	4.5	6	3
18.5	13.5	34.5	30	22
20	20.5	?	34.5	30
36	43.5	46.5	30.5	43
39	42	35	38.5	36

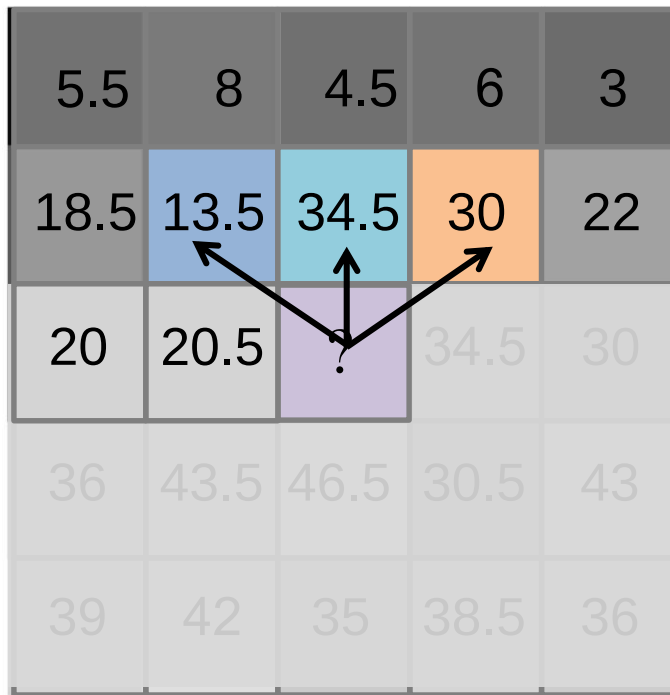


Step2: Propagation for every row

Value matrix V

Neighborhoods of the pixel in previous row

5.5	8	4.5	6	3
18.5	13.5	34.5	30	22
20	20.5	?	34.5	30
36	43.5	46.5	30.5	43
39	42	35	38.5	36



Step2: Propagation for every row

- Find the **neighbors** of the pixel in the previous row

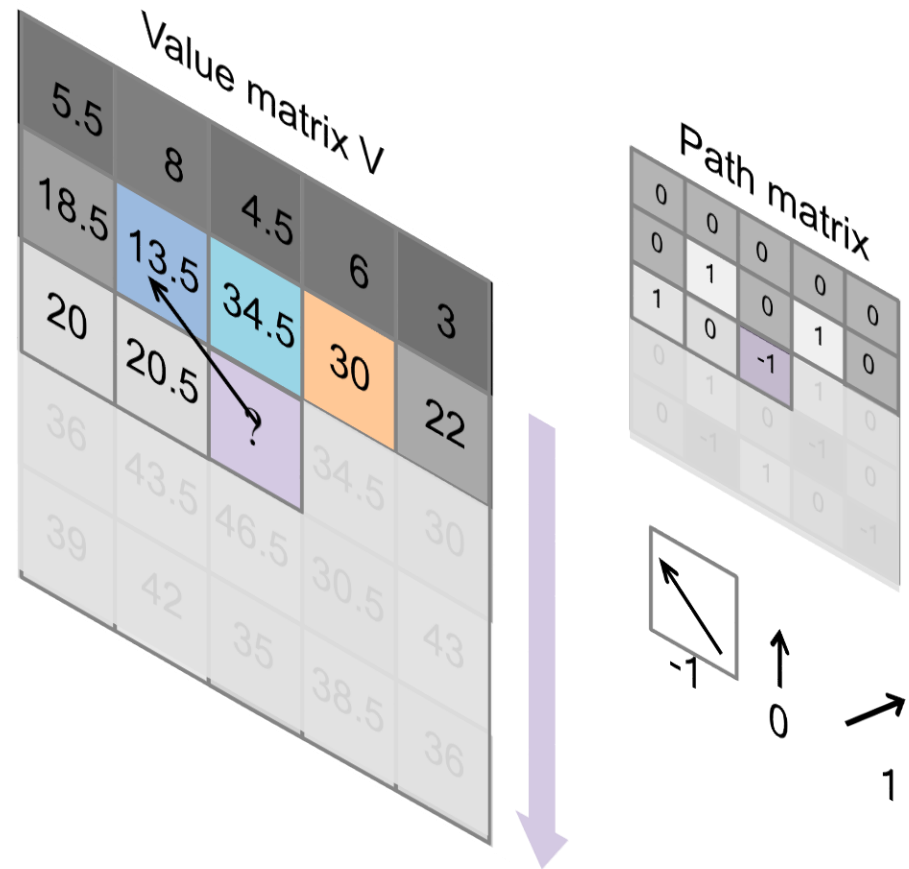
$$\min \begin{pmatrix} V(i-1, j-1) & 13.5 \\ V(i-1, j) & 34.5 \\ V(i-1, j+1) & 30 \end{pmatrix} + e(i, j)$$

Value matrix V

5.5	8	4.5	6	3
18.5	13.5	34.5	30	22
20	20.5	?	34.5	30
36	43.5	46.5	30.5	43
39	42	35	38.5	36



- Find the **neighbors** of the pixel in the previous row
- Find the **minimum** among neighbors



- Find the **neighbors** of the pixel in the previous row
- Find the **minimum** among neighbors, record it in Path matrix



Value matrix V



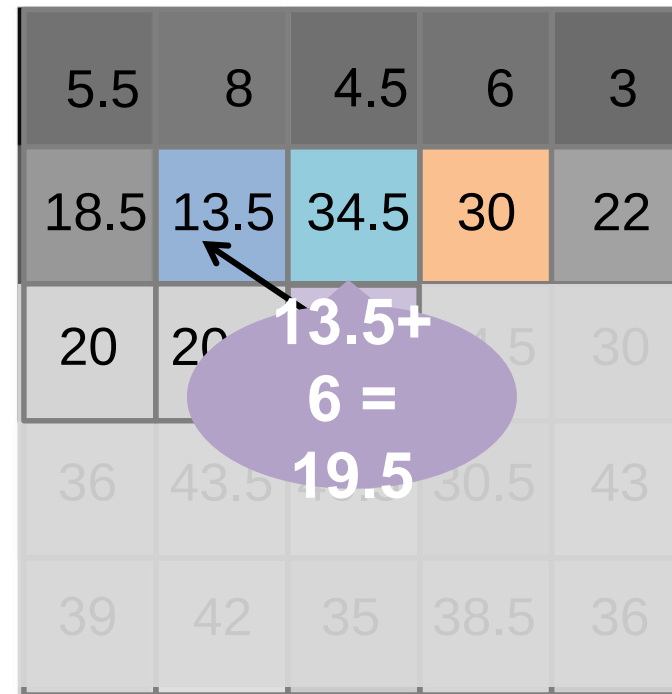
$$\min \begin{pmatrix} V(i-1, j-1) & 13.5 \\ V(i-1, j) & 34.5 \\ V(i-1, j+1) & 30 \end{pmatrix} + e(i, j) \quad 6$$

✓

- Find the **neighbors** of the pixel in the previous row
- Find the **minimum** among neighbors
- Add the **energy value** of the pixel with the minimum



Value matrix V



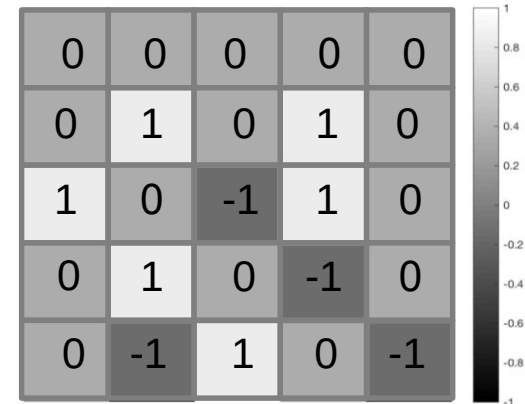
- Find the **neighbors** of the pixel in the previous row
- Get the **minimum** among neighbors
- Add the **energy value** of the pixel with the minimum

Step3: path resolving

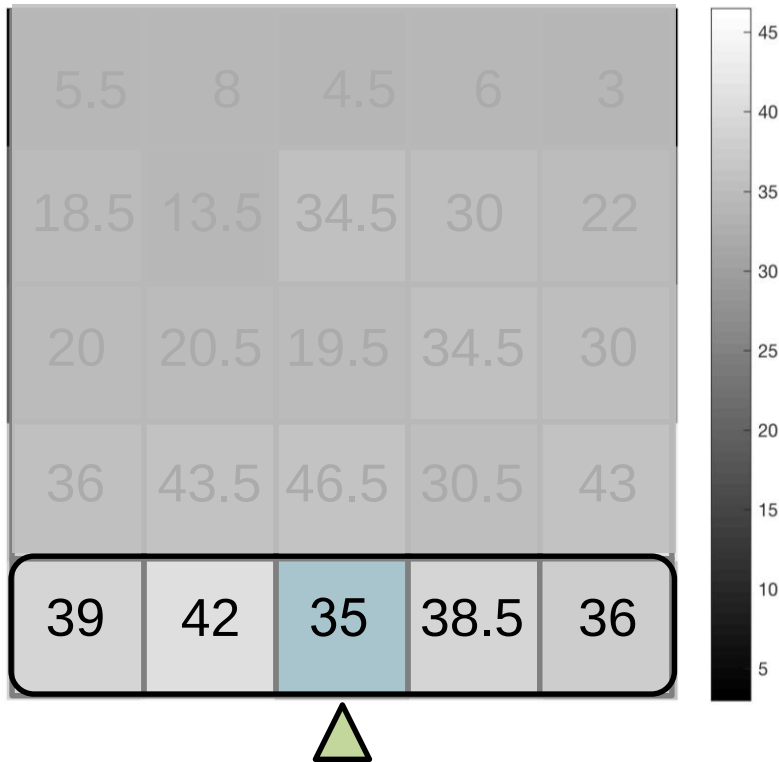
Value matrix



Path matrix

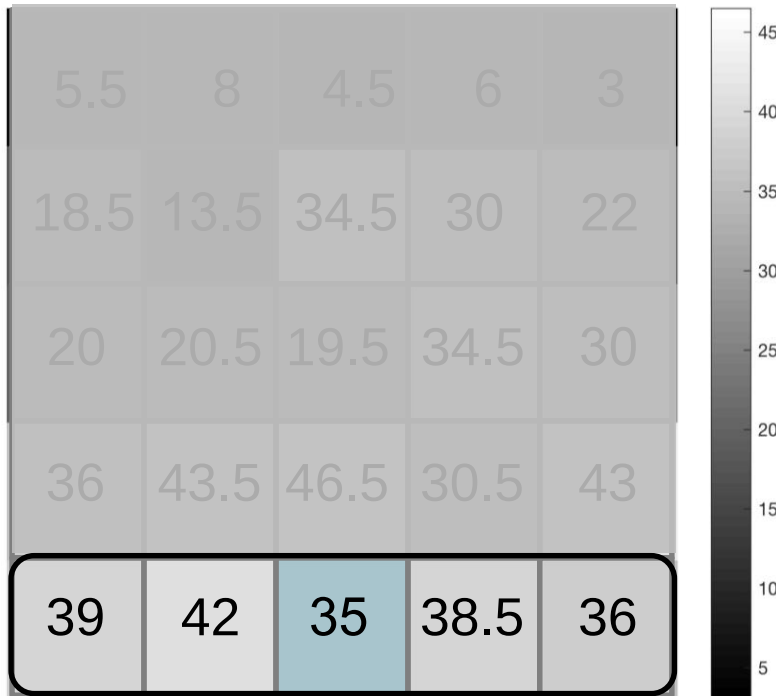


Value matrix

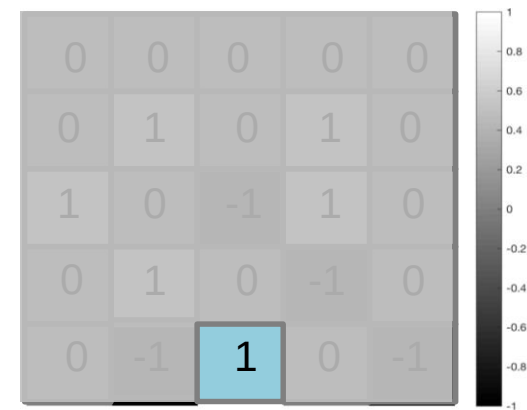


- Find the **minimum** of the last row of the Value matrix,
- Find the **predecessor** of that pixel

Value matrix



Path matrix

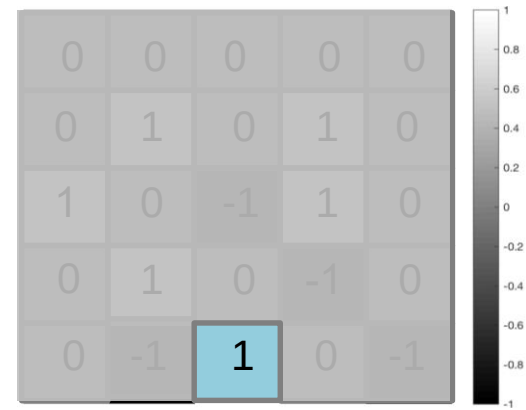


- Find the *minimum* of the last row of the Value matrix,
- Find the *predecessor* of that pixel, using Path matrix

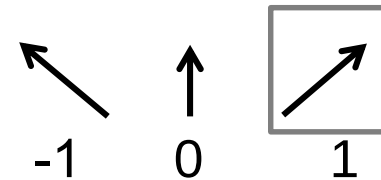
Value matrix



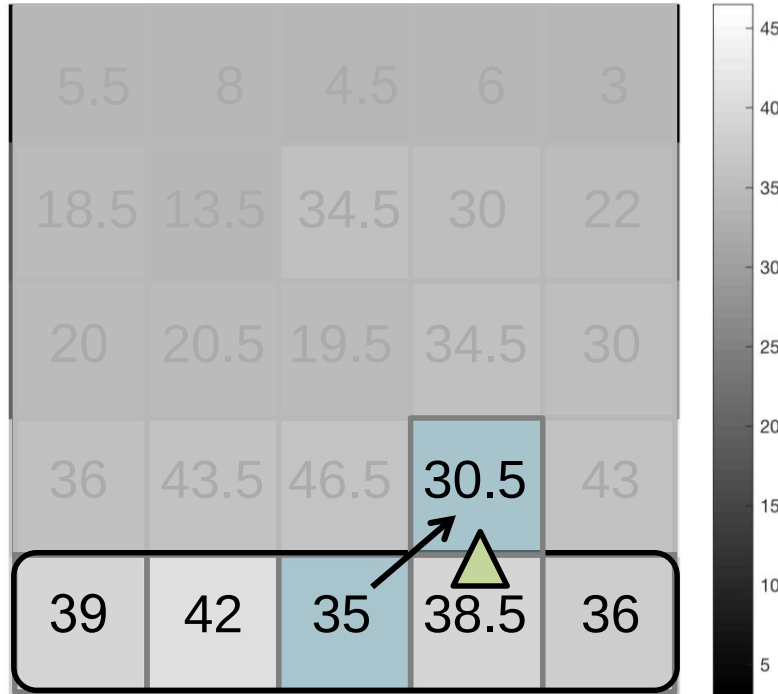
Path matrix



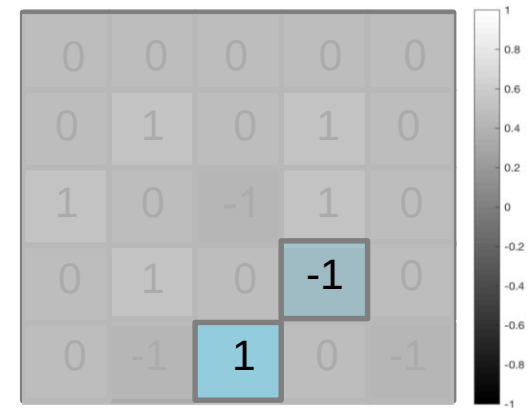
- Move to its *predecessor*



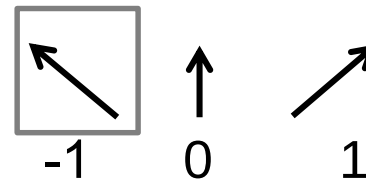
Value matrix



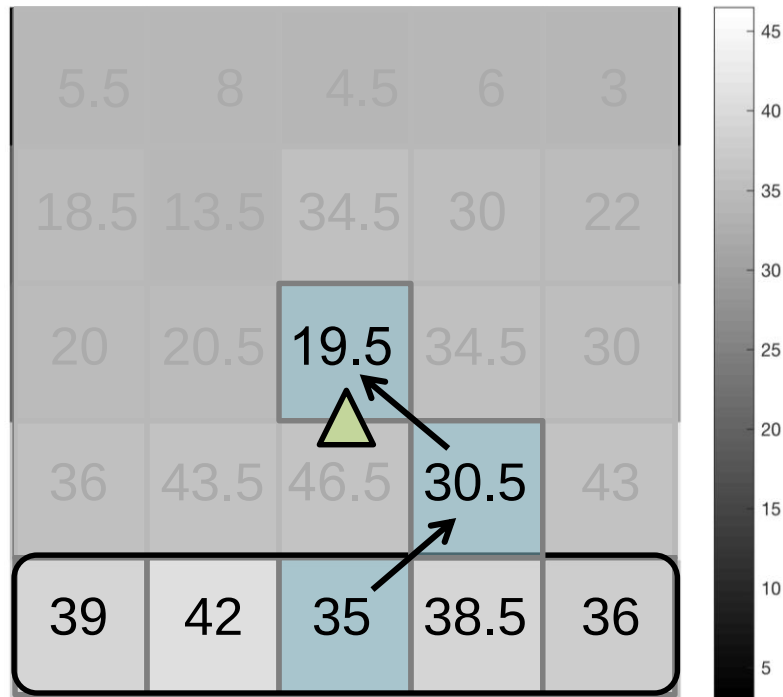
Path matrix



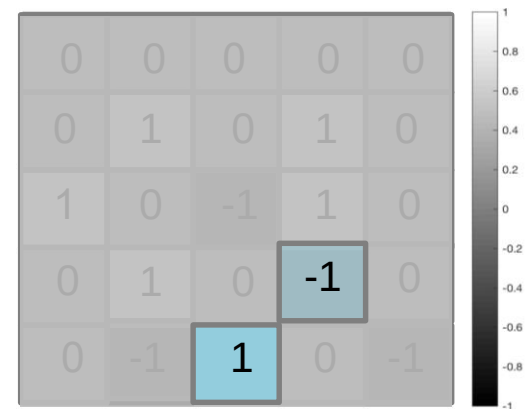
- Follow *predecessor* of current pixel,



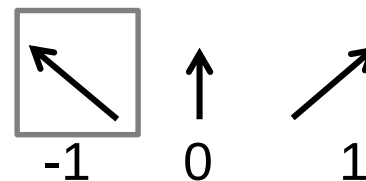
Value matrix



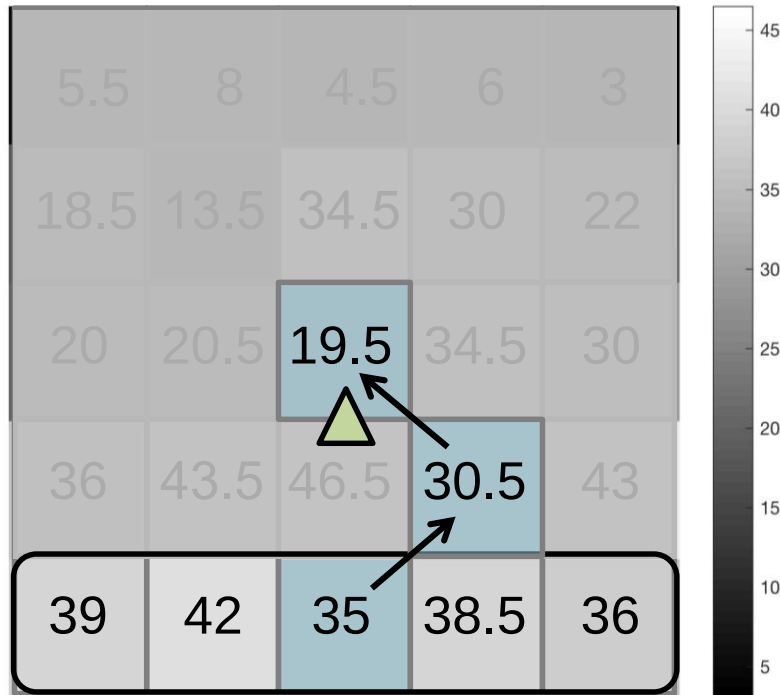
Path matrix



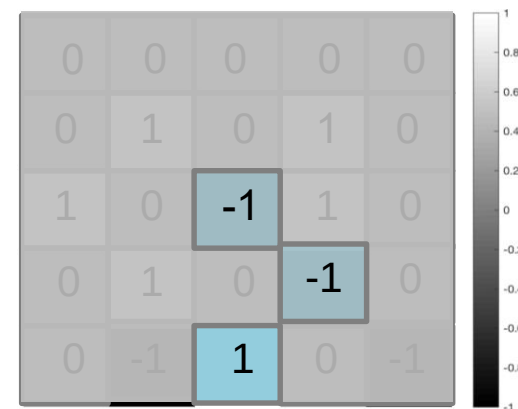
- Move to its *predecessor*



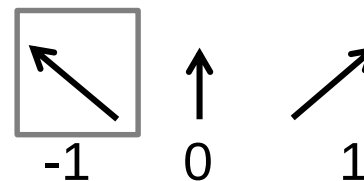
Value matrix



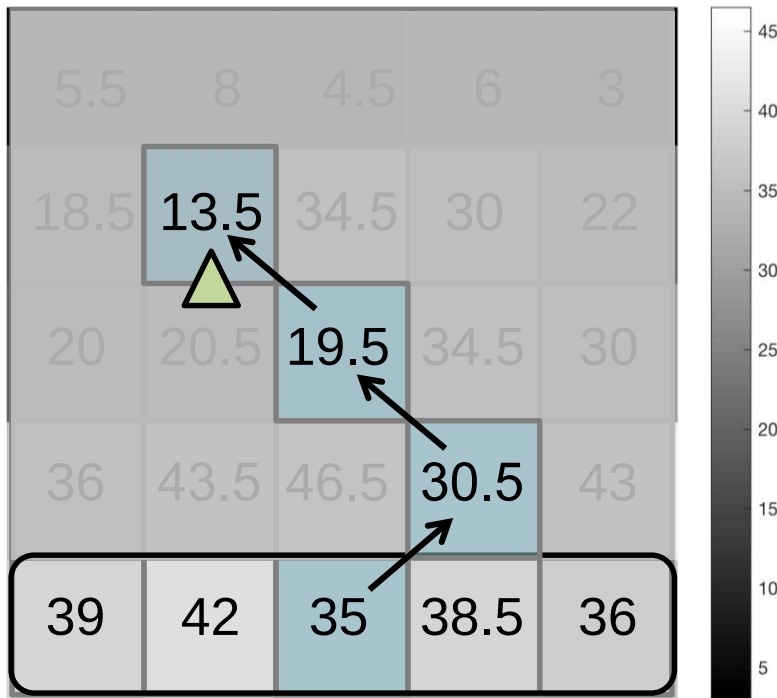
Path matrix



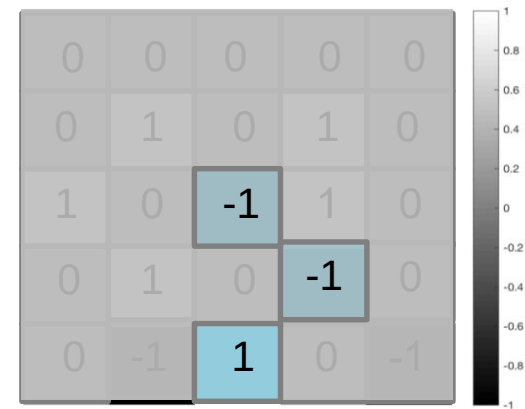
- Find the *predecessor* of current pixel



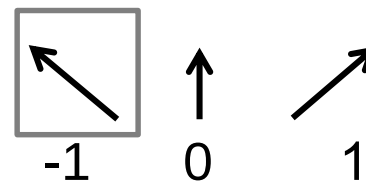
Value matrix



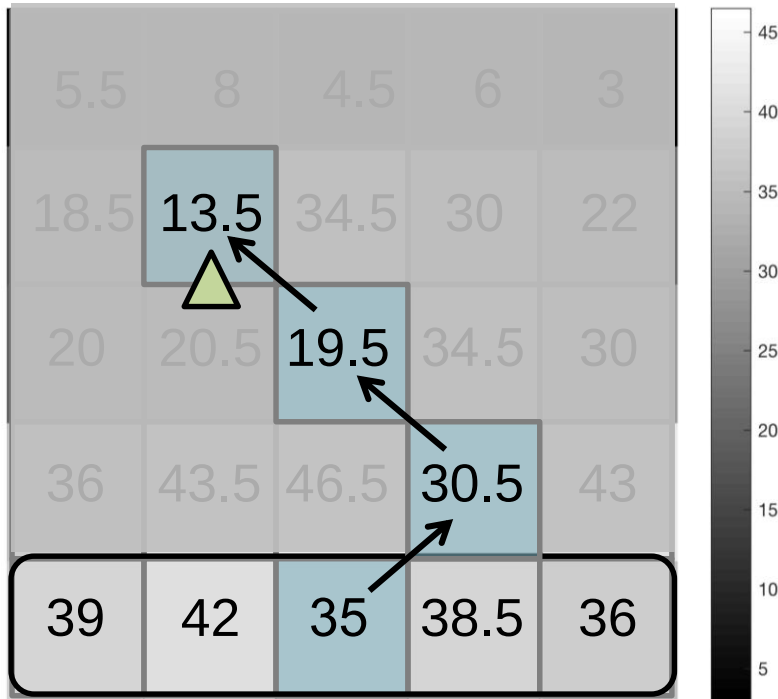
Path matrix



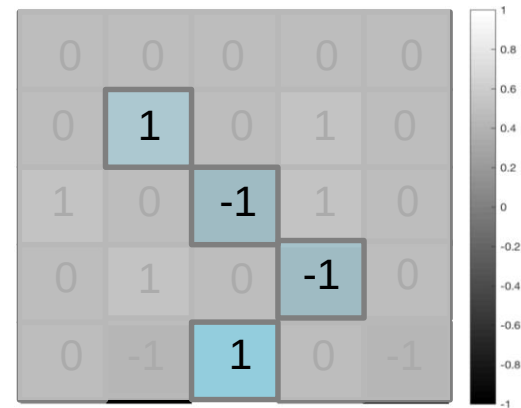
- Move to its *predecessor*



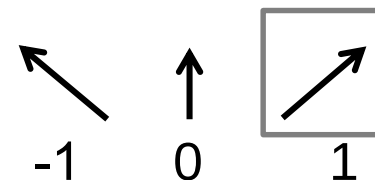
Value matrix



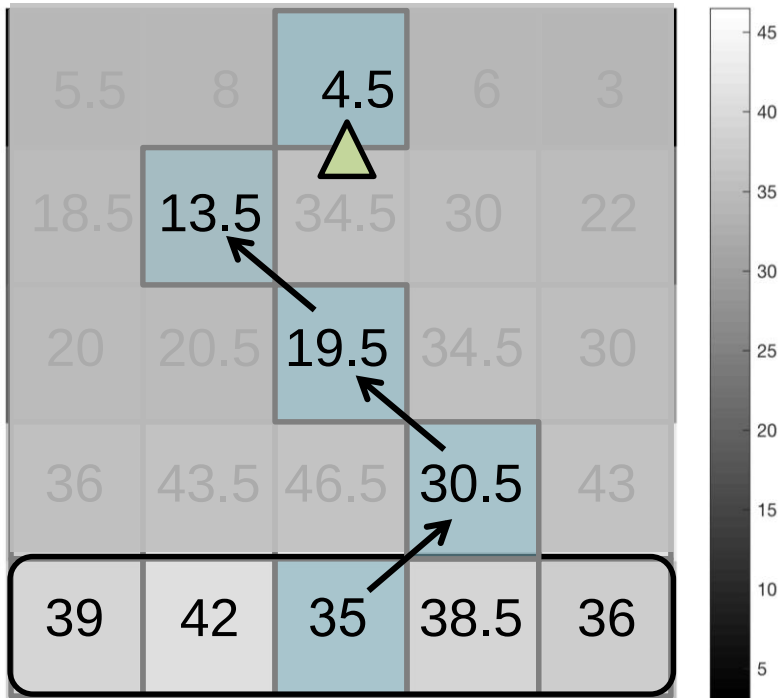
Path matrix



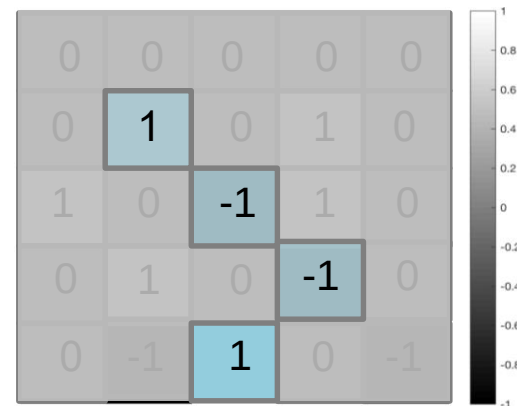
- Find the *predecessor* of current pixel



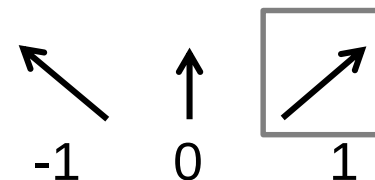
Value matrix



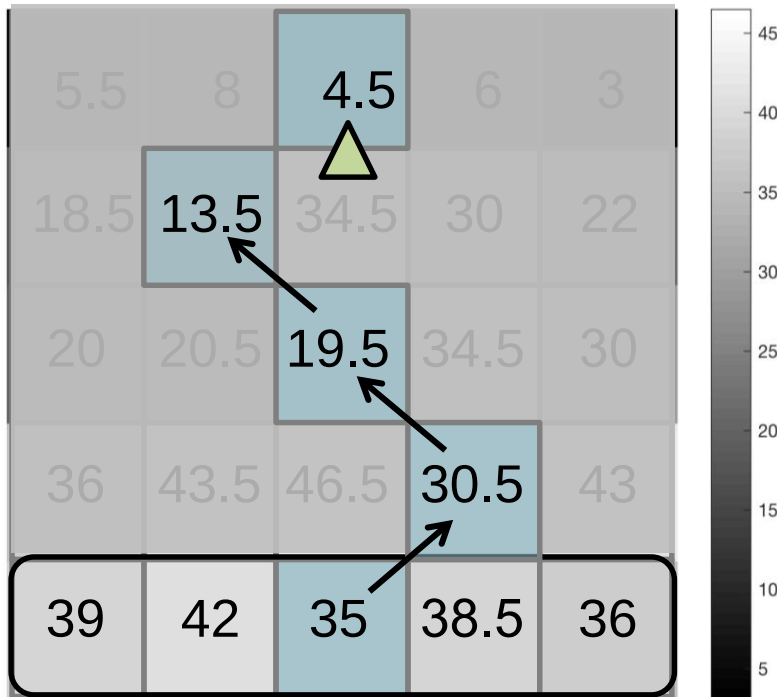
Path matrix



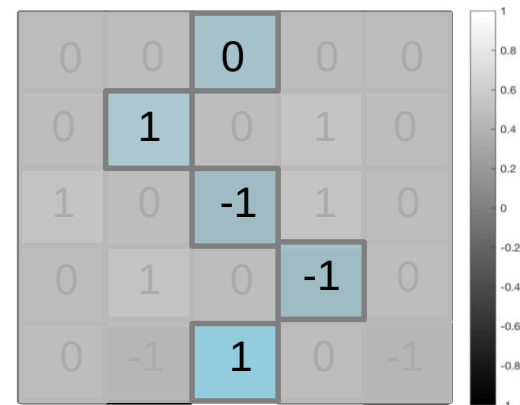
- Stop when reaching the *first row*



Value matrix

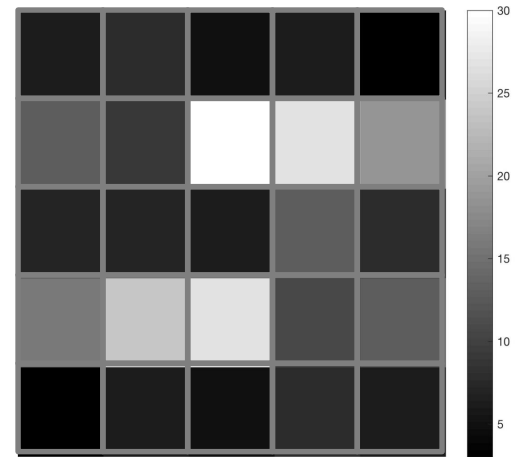
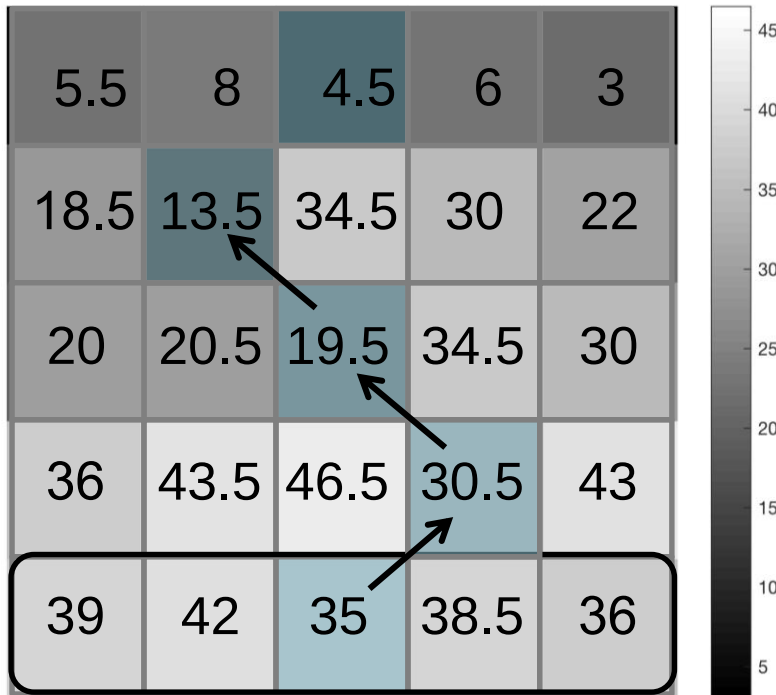


Path matrix

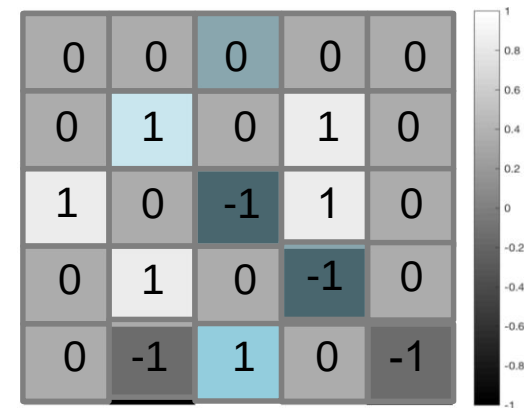


- Seam carving is to delete the path with minimum cost

Value matrix

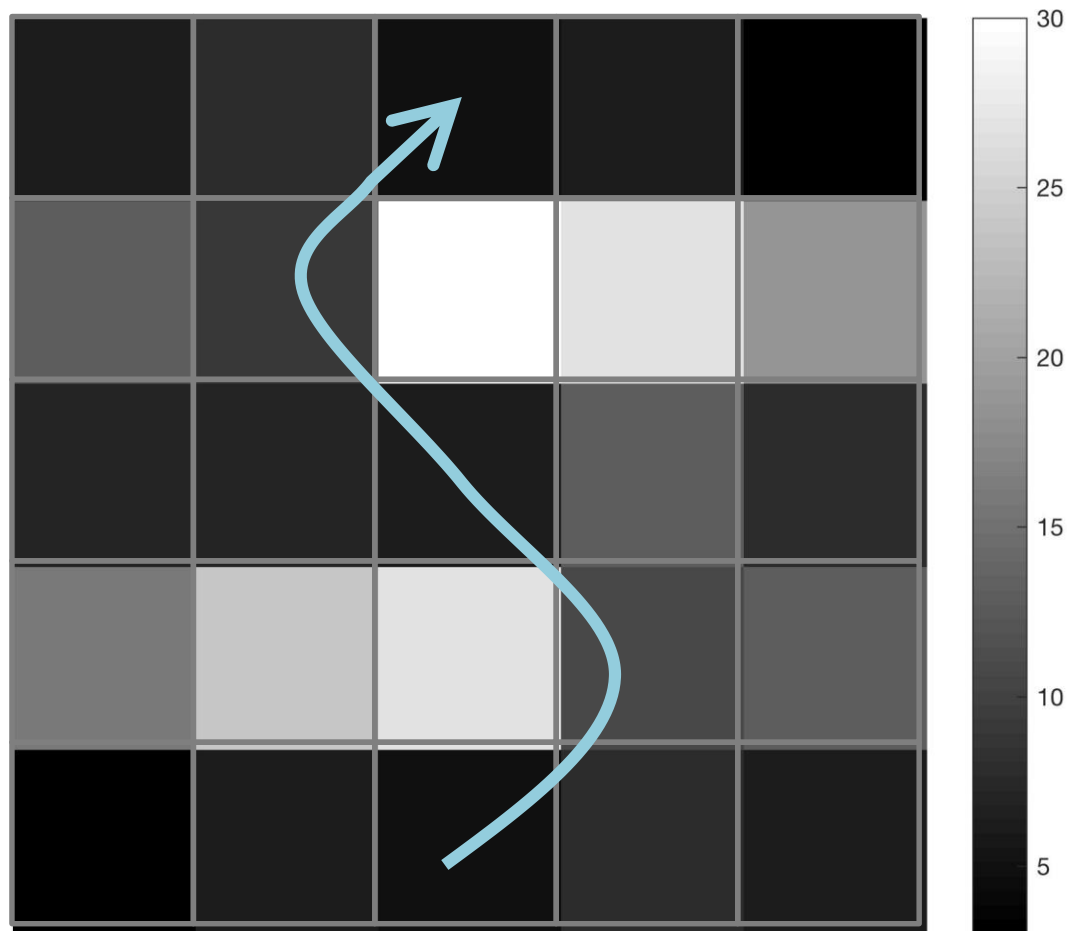


Path matrix



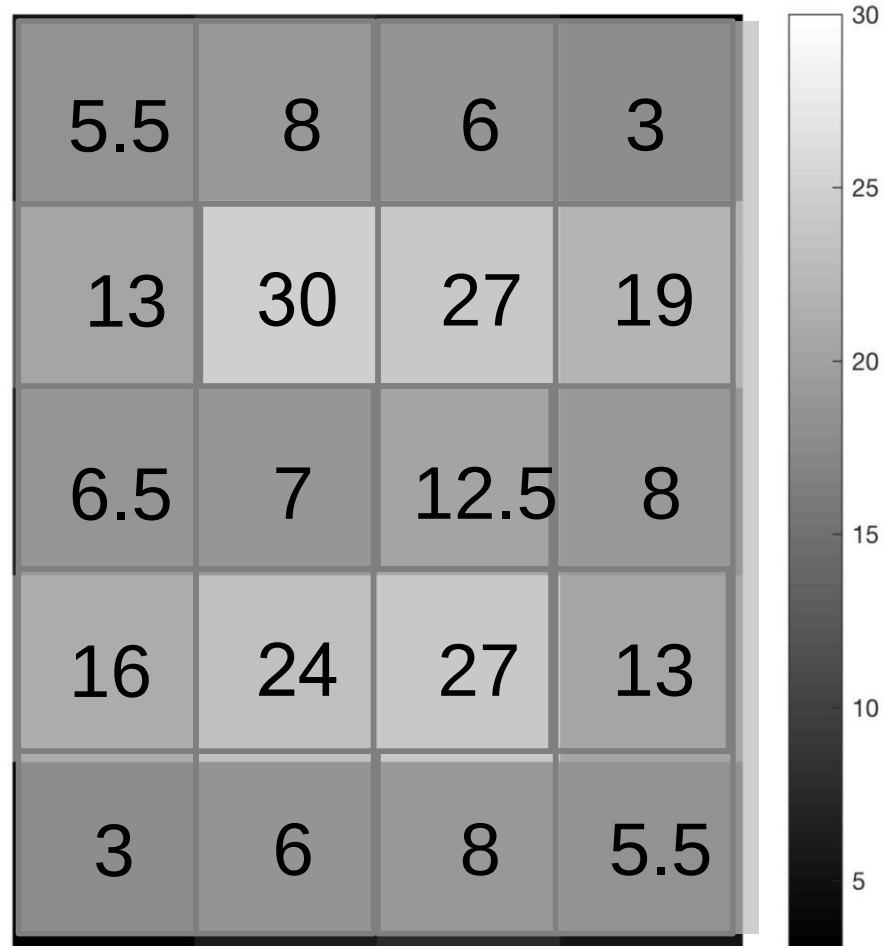
- Seam carving is to delete the path with minimum cost

Energy matrix

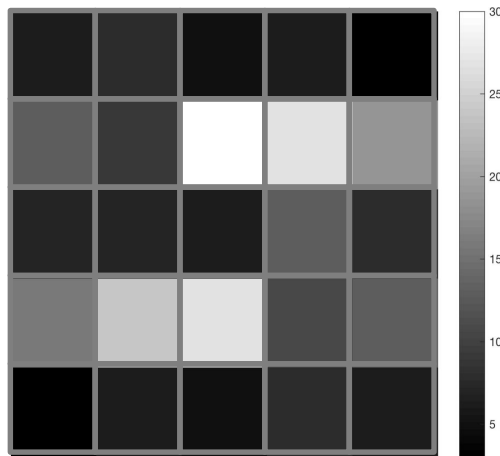


- Seam carving is to delete the path with minimum cost

Carved energy matrix



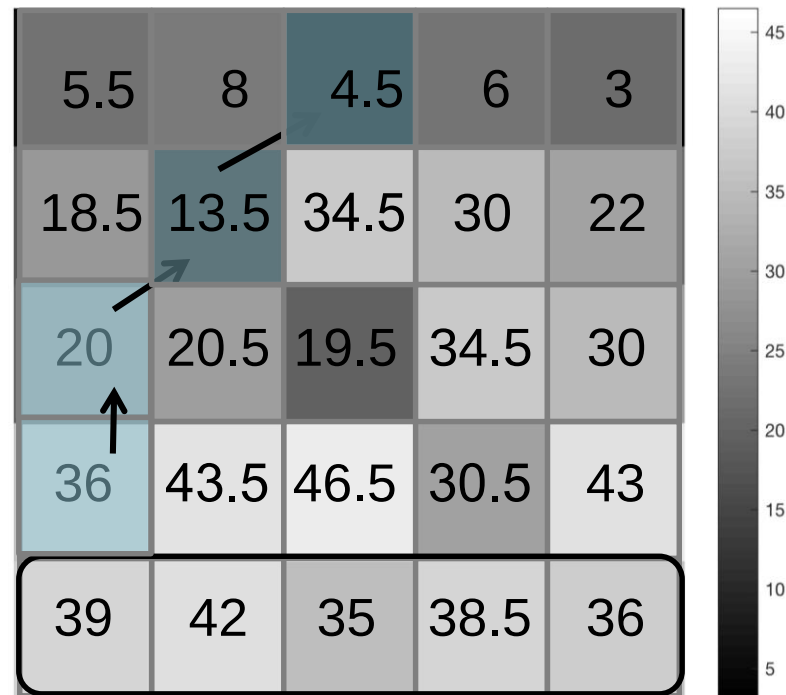
- Seam carving is to delete the path with minimum cost



Path matrix

0	0	0	0	0
0	1	0	1	0
1	0	-1	1	0
0	1	0	-1	0
0	-1	1	0	-1

Value matrix



- What if we want to remove a seam that ends on particular pixel?



Video 9.5

Jianbo Shi

Illustration on a real image



Step 0: prepare the energy function

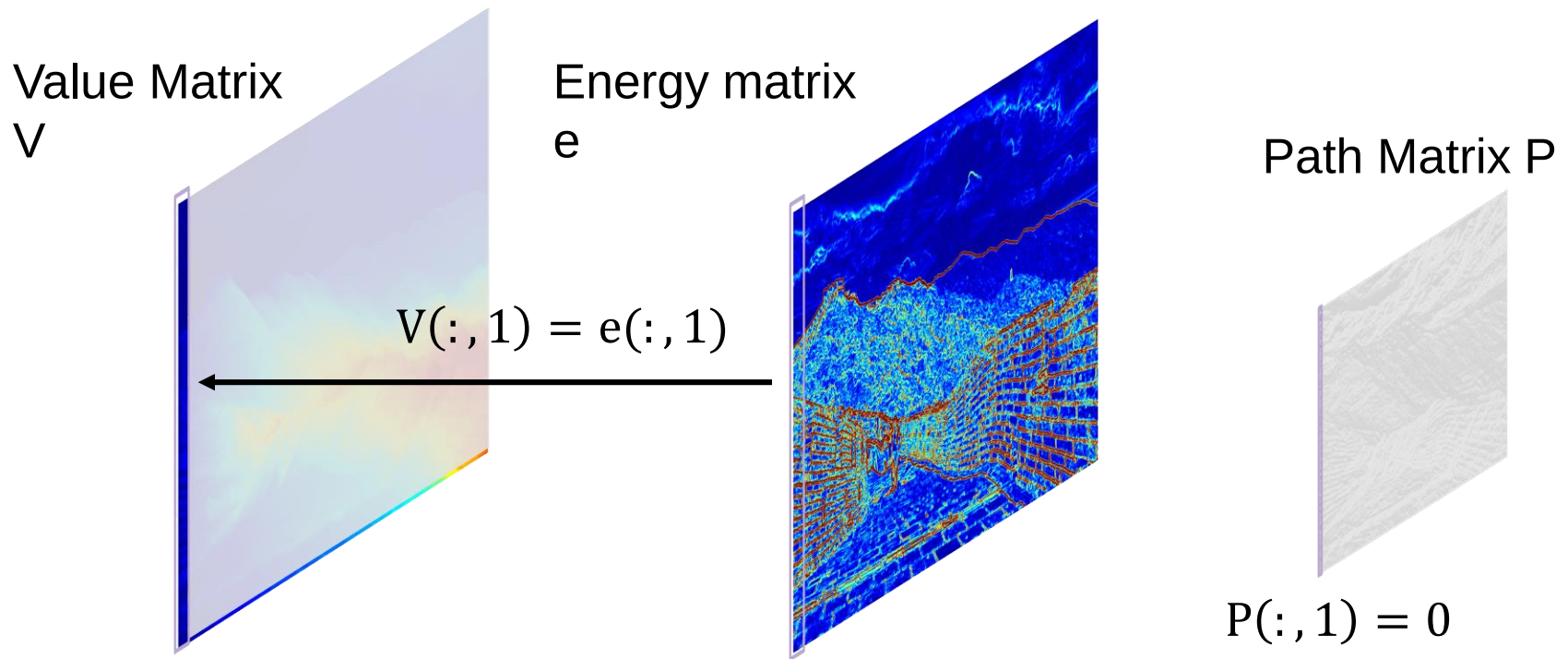
- Transform a color image into gray, $I_m = \text{rgb2gray}(I_m)$
- Calculate image gradients
- Use the L1 norm of the gradients for the energy function

$$\begin{array}{c}
 \text{abs}(\\
 \text{abs}(
 \end{array}
 \begin{array}{c}
 \text{img} \\
 \text{img}
 \end{array}
 \otimes
 \begin{array}{c}
 \begin{bmatrix}
 0 & 1 & 2 & 3 \\
 1 & 1 & 1 & 0 \\
 2 & 1 & 1 & 0 \\
 3 & 0 & 0 & 0
 \end{bmatrix} \\
 \begin{bmatrix}
 0 & 1 & 2 & 3 \\
 1 & 1 & 1 & 0 \\
 2 & 1 & 1 & 0 \\
 3 & 0 & 0 & 0
 \end{bmatrix}
 \end{array}
) + =
 \begin{array}{c}
 \text{Energy matrix} \\
 e
 \end{array}
 \begin{array}{c}
 \text{img_e} \\
 \text{img_e}
 \end{array}$$

The diagram illustrates the calculation of the energy matrix e . It shows two grayscale images of the Great Wall of China. The first image is processed by the function $\text{abs}(\text{img} \otimes \text{kernel}_1)$, where kernel_1 is a 4x4 matrix. The second image is processed by the function $\text{abs}(\text{img} \otimes \text{kernel}_2)$, where kernel_2 is another 4x4 matrix. The results of these two operations are then added together to produce the final energy matrix e , which is visualized as a heatmap where red and yellow areas indicate high energy (edges) and blue areas indicate low energy.

Step 0: prepare the energy function

- Transform a color image into gray, $\text{Im} = \text{rgb2gray}(\text{Im})$
- Calculate the gradients
- Use the L1 norm of the gradients for the energy function

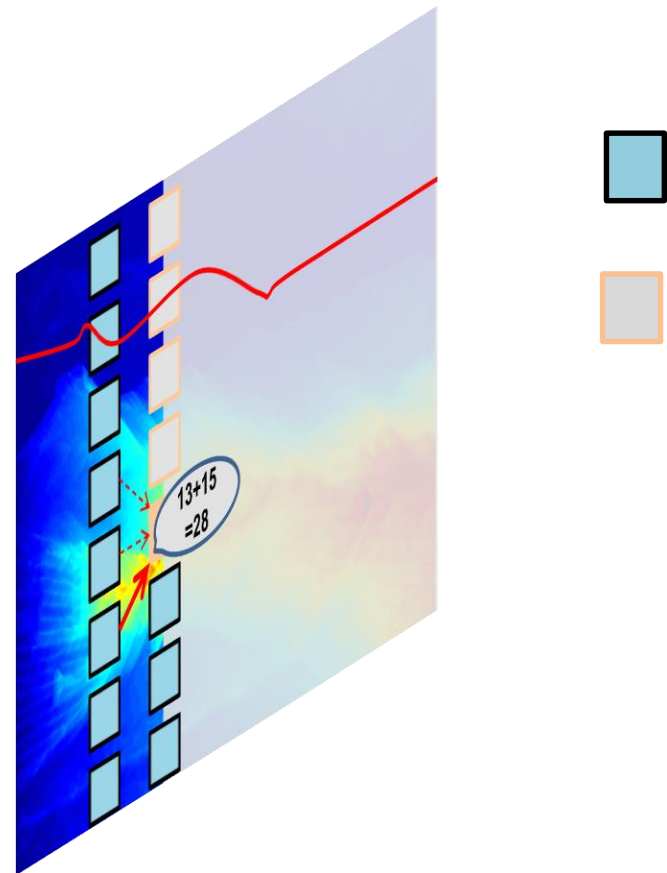
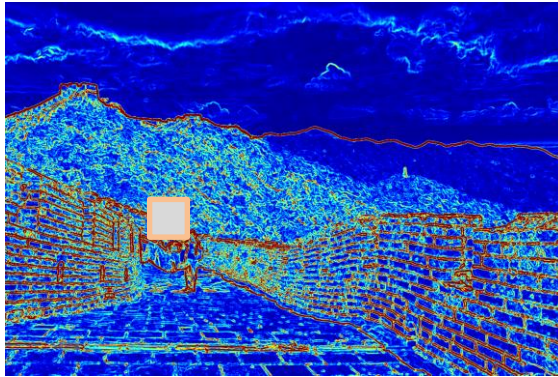


Step 1: Initializing two matrices

- Set value and path matrix the same size as the energy matrix
- Initialize the **first column** of value matrix with that of the energy matrix
- Initialize the **first column** of path matrix to zero

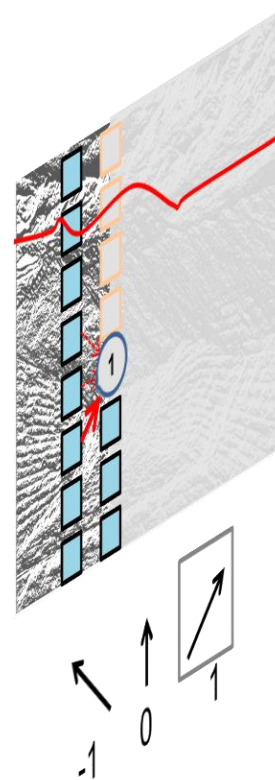
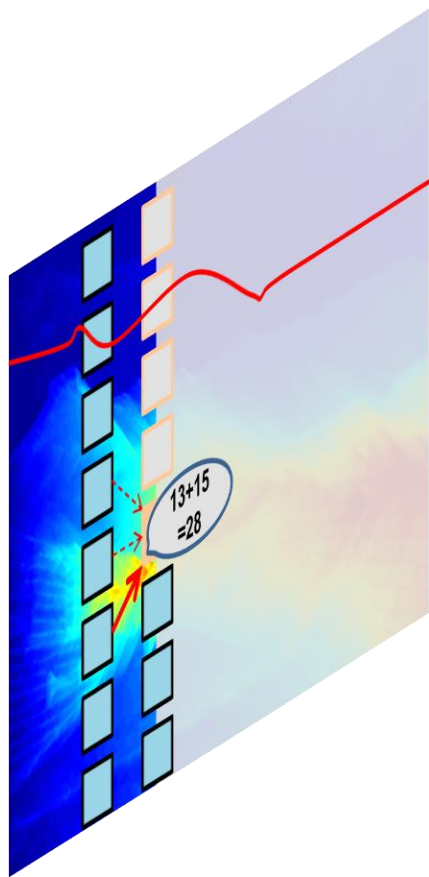
$$\min \begin{pmatrix} V(i-1, j-1) \\ V(i, j-1) \\ V(i+1, j-1) \end{pmatrix} + e(i, j)$$

38
24
13 ✓
15



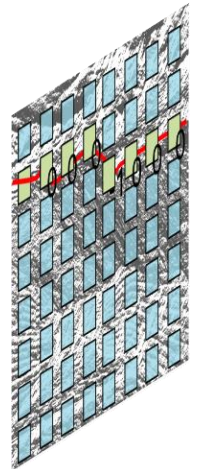
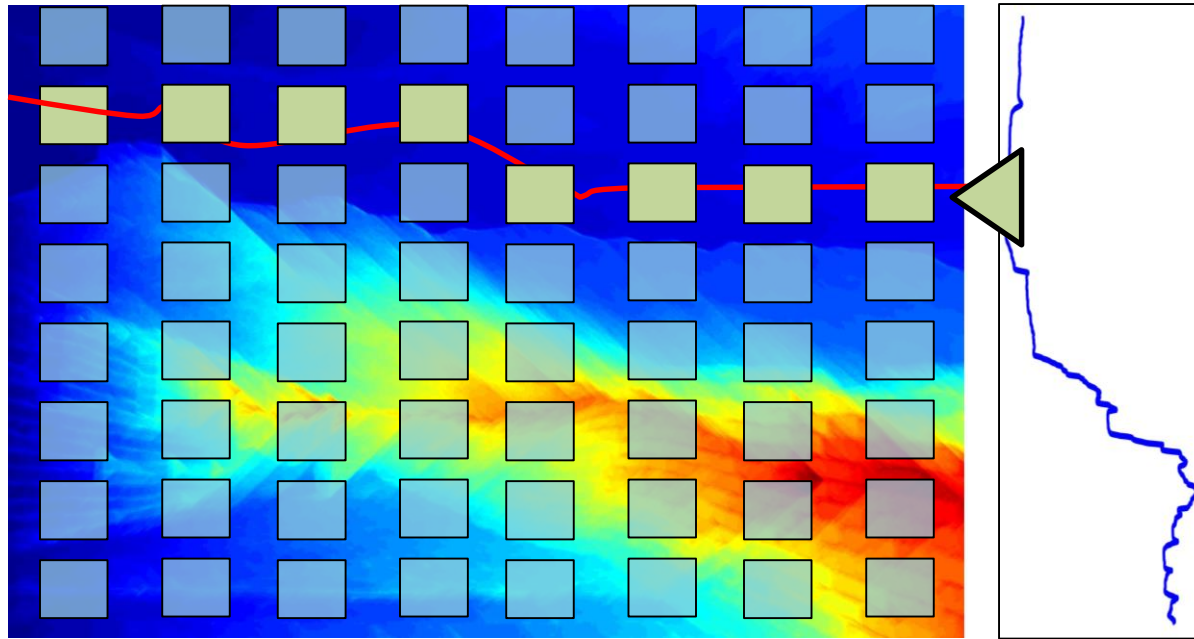
Step 2: Propagation

- Start with 2nd column
- Find the **neighbors** of the pixel in the previous column
- Find the **minimum** among neighbors
- Add the **energy value** of the pixel with the minimum



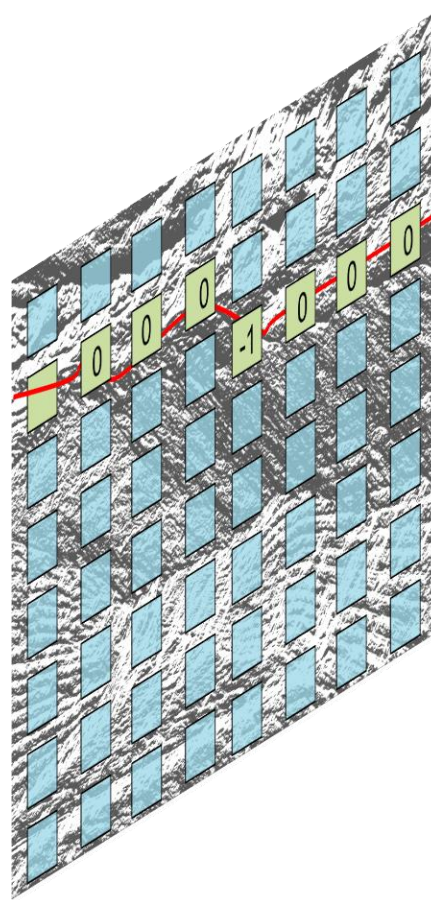
Step 2: Propagation

- Start with 2nd column
- Find the **neighbors** of the pixel in the previous column
- Find the **minimum** among neighbors
- Add the **energy value** of the pixel with the minimum
- Assign the **direction** of the minimum to path matrix



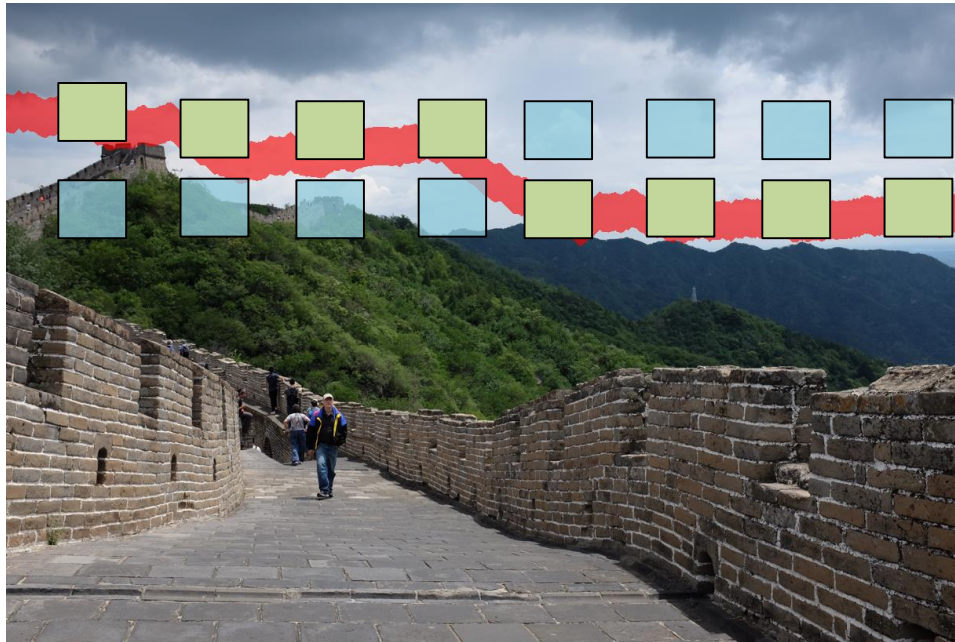
Step 3: Path Resolving

- Find the *minimum* of the last column of the Value matrix,
- Find the *predecessor* of that pixel, using Path matrix
- Trace back to complete the path using the Path matrix



Step3: Path Resolving

- Find the **minimum** of the last column of the Value matrix,
- Find the **predecessor** of that pixel, using Path matrix
- Trace back to complete the path using the Path matrix



Step 4: Eliminate the Seam

