Data Analysis: Statistical Modeling and Computation in Applications

Time Series Analysis: Statistical Models and Fitting

- Statistical models
- Time series regression
- Fitting statistical models
- Forecasting

Recap

- **Time series:** collection of observations x_1, \ldots, x_n indexed by time (fixed time intervals)
- realizations of a collection of random variables X_1, \ldots, X_n

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- Autocovariance / Autocorrelation:

$$\gamma_X(s,t) = \operatorname{cov}(X_s, X_t)$$

 $\rho_X(h) = \gamma_X(h)/\gamma_X(0) \quad \text{for } -n < h < n$

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- stationary
- checking for white noise: for white noise, $\hat{\rho}(h)$ is approximately $\mathcal{N}(0, \frac{1}{n})$, under mild conditions.

Models 2: Autoregressive AR(p)

• Autoregressive: $X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + W_t$

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source: R.H. Shumway, D.S. Stoffer. Time Series Analysis and its Applications, with Examples in R. Springer, 2011.

Stefanie Jegelka (and Caroline Uhler)

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + W_t$$

• Can we model seasonality with this?

$$X_{ijun2i} = X_{jun2o} + W_{ijun2i}$$
$$X_{ijun2i} = X_{ijun2i} + W_{ijun2i}$$

Models 2: Autoregressive AR(p)

$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + W_t$$

0

$$X_{t} = 1.5X_{t-1} - 0.75X_{t-2} + W_{t}$$

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• autocorrelation decays exponentially (never zero)

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$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + W_t$$

- autocorrelation decays exponentially (never zero)
- stationary only under conditions (later)



Models 3: Random Walk (with drift)

 $\chi_{t} = \chi_{t-1} + W_{t} + S$ o 70

Models 3: Random Walk (with drift)



Random Walk: properties

$$X_{t} = X_{t-1} + W_{t} + \delta$$

= $X_{t-2} + W_{t-1} + W_{t} + 2\delta$
= $X_{0} + W_{1} + W_{2} + ... + W_{t} + t \cdot \delta$

$$X_t = X_{t-1} + W_t$$
$$= X_0 + W_1 + \ldots + W_t$$

$$X_t = X_{t-1} + W_t$$

= $X_0 + W_1 + \ldots + W_t$

(assume $X_0 = 0$ fixed)

• Random Walk with drift: $X_t = \delta + X_{t-1} + W_t = t\delta + X_0 + \sum_{s=0}^t W_s$

$$X_t = X_{t-1} + W_t$$
$$= X_0 + \underbrace{W_1 + \ldots + W_t}_{t-1}$$

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•
$$\mathbb{E}[X_t] = X_t + \bigcup_{t \in S}$$

$$X_t = X_{t-1} + W_t$$

= $X_0 + W_1 + \ldots + W_t$

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$$\mathbb{E}[X_t] = t\delta + X_0$$

• without drift: $var(X_t) = t\sigma_w^2$

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Autocovariance for Random Walk

Random Walk: $X_t = X_{t-1} + W_t$ $= \underbrace{X_0}_{0} + W_1 + \ldots + W_t$ $\operatorname{Cov}(X_{5}^{'}, X_{t}) = \operatorname{Cov}(\sum_{i=1}^{s} W_{i}^{'}, \sum_{j=1}^{t} W_{j}^{'})$ $= \mathbf{W} \sum_{i=1}^{S} \sum_{j=1}^{L} \operatorname{cov} (W_{i,j}^{*} W_{j}^{*})$ = min (s,t) · 6^2

Random Walk: properties

• Random Walk:

$$X_t = X_{t-1} + W_t$$

= $X_0 + W_1 + \ldots + W_t$

(assume $X_0 = 0$ fixed)

• Random Walk with drift: $X_t = \delta + X_{t-1} + W_t = t\delta + X_0 + \sum_{s=0}^t W_s$

 $\nabla X = X_{L-1}$

 $= W_{\perp}$

•
$$\mathbb{E}[X_t] = t\delta + X_0$$

- without drift: $var(X_t) = t\sigma_w^2$
- without drift: $\gamma_X(s,t) = \min\{s,t\}\sigma_w^2$
- not stationary, but ∇X_t is stationary

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Models 4: Moving Average MA(q)

Wt-1 Wt W1+1 ... $X_{t} = W_{t} + \Theta_{1} W_{t-1} + \Theta_{1} W_{t-2} \cdots \Theta_{q} W_{t-q}$ (2)Wi+2 WLtI W1-1 Wf 9=1 X1+2

Models 4: Moving Average



$$X_t = W_t + \theta_1 W_{t-1} + \theta_2 W_{t-2} + \ldots + \theta_q W_{t-q}$$

• $\mathbb{E}[X_t] =$

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- $\mathbb{E}[X_t] = 0$
- autocovariance?

Autocovariance for Moving Average MA(q)

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$$cov(X_{t}, X_{t-3}) = 0$$

$$h > 9$$

q=2

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• autocovariance γ depends only on |s-t|

• reflects order:
$$\gamma(s,t) = 0$$
 if $|s-t| > q$

$$X_t = W_t + \theta_1 W_{t-1} + \theta_2 W_{t-2} + \ldots + \theta_q W_{t-q}$$

• $\mathbb{E}[X_t] = 0$

- autocovariance γ depends only on $|s t| \Rightarrow$ stationary
- ACF reflects order: $\gamma(s, t) = 0$ if |s t| > q
- ACF distinguishes MA and AR models!

Autocorrelation to distinguish models



- Autoregressive: $X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + W_t$
- Moving Average: $X_t = W_t + \theta_1 W_{t-1} + \theta_2 W_{t-2} + \ldots + \theta_q W_{t-q}$

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- ARMA(p,q): autoregressive moving average:

$$X_{t} = \phi_{1}X_{t-1} + \phi_{2}X_{t-2} + \dots + \phi_{p}X_{t-p} + W_{t} + \theta_{1}W_{t-1} + \theta_{2}W_{t-2} + \dots + \theta_{q}W_{t-q}$$

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• ARIMA: ARMA after differencing

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- critical: linearity, stationarity, homogeneity of variances over time
- model: $X_t = \beta_1 z_{t_1} + \beta_2 z_{t_2} + \ldots + W_t = \beta^\top z_t + W_t$

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- Ex. 3: external regressors: $X_t = \beta_1 X_{t-1} + \beta_2 Y_t + W_t$

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- Remark: could also use nonlinearities.
- Which external variables? Order of the model?

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left: series; right: autocorrelation of residuals after fitting only a linear trend.



• 2 series: ${X_t}_{t=1}^n, {Y_s}_{s=1}^n$.



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- 2nd-order stationary: Cross-cov only a function of the lag h: cov(X_{t+h}, Y_t) = γ_{XY}(h)



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Example: fish and SOI













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Cross-covariance: $cov(X_{t+h}, Y_t) = \gamma_{XY}(h)$

CCF $\rho_{XY}(h)$ peaks negatively at h = -6 (SOI X_t 6 months before).

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Cross-covariance: $cov(X_{t+h}, Y_t) = \gamma_{XY}(h)$

CCF $\rho_{XY}(h)$ peaks negatively at h = -6 (SOI X_t 6 months before).

Possible regression model: $Y_t = \beta_1 + \beta_2 X_{t-6} + W_t$

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Fitting AR(p):

- compute PACF to get order
- **e**stimate coefficients ϕ_k and noise variance σ_w^2 via Yule-Walker equations
- Ocompute residuals, test for white noise

Fitting MA(q):

- compute ACF to get order
- estimate coefficients via maximum likelihood (won't cover, see Shumway & Stoffer Ch. 3)
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Fitting ARMA(p,q):

- attempt to fit an AR model, compute residuals
- 2 attempt to fit an MA model to residuals (or orig. data)
- fit ARMA(p,q) using p, q determined in Steps 1,2 (max. likelihood) (won't cover, see Shumway & Stoffer)
- compute residuals, test for white noise

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$$X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + \dots + \phi_p X_{t-p} + W_t$$

Estimate parameters $\hat{\phi}_1, \ldots, \hat{\phi}_p, \hat{\sigma}_w^2$?

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$$\begin{split} \gamma(h) &= \phi_1 \gamma(h-1) + \phi_2 \gamma(h-2) + \ldots + \phi_p \gamma(h-p) \\ \gamma_p &= \mathbf{\Gamma}_p \phi \quad \Leftrightarrow \quad \phi = \mathbf{\Gamma}_p^{-1} \gamma_p \\ \sigma_w^2 &= \gamma(0) - \phi_1 \gamma(1) - \phi_2 \gamma(2) - \ldots - \phi_p \gamma(p) \\ &= \gamma(0) - \gamma_p^\top \mathbf{\Gamma}_p^{-1} \gamma_p. \end{split}$$

Least squares regression with AR(p)

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• assume $\mu_X = 0$, and predict X_t as:

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• find $\hat{\phi}_k$ to minimize $\mathbb{E}[(\hat{X}_t - X_t)^2]$.

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 $\mathbb{E}[(\hat{X}_t - X_t)] = 0$ $\mathbb{E}[(\hat{X}_t - X_t)X_{t-k}] = 0 \text{ for } k = 1, \dots, p$

• Now plug in $\hat{X}_t = \hat{\phi}_1 X_{t-1} + \hat{\phi}_2 X_{t-2} + \ldots + \hat{\phi}_p X_{t-p}$.

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 and $k = 2$ $\rho = 2$

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$$\Leftrightarrow \quad \mathbb{E}\big[\left(\hat{\phi}_1 X_{t-1} + \hat{\phi}_2 X_{t-2} - X_t\right) X_{t-2}\big] = 0$$

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$$\Rightarrow \mathbb{E}\hat{\phi}_{1}X_{t-1}X_{t-2} + \mathbb{E}\hat{\phi}_{2}X_{t-2}X_{t-2} - \mathbb{E}X_{t}X_{t-2} = 0 \hat{p}_{1}^{*}\chi(1) + \hat{p}_{1}^{*}\chi(0) - \chi(2) = 0 \Rightarrow \chi(2) = \hat{\phi}_{1}^{*}\chi(2-1) + \hat{\phi}_{2}^{*}(2-2) \chi(h) = \hat{\phi}_{1}^{*}\chi(h-1) + \hat{\phi}_{2}^{*}\chi(h-2) \qquad p=2$$

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- predict X_{n+m} based on observed $x_n, x_{n-1}, \ldots x_1$.
- \bullet estimate coefficients $\hat{\phi}_1,\ldots,\hat{\phi}_{\it P}$ and plug in

$$\hat{X}_{n+1} = \hat{\Phi}_{1} X_{n} + \hat{\Phi}_{2} X_{n-1} + \dots + \hat{\Phi}_{p} X_{n-p+1}$$

$$\hat{X}_{n+2} = \hat{\Phi}_{1} \hat{X}_{n+1} + \hat{\Phi}_{2} X_{n+1} + \dots + \hat{\Phi}_{p} X_{n-p+2}$$

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- general: $\hat{x}_{n+m} = \hat{\phi}_1 \hat{x}_{n+m-1} + \hat{\phi}_2 \hat{x}_{n+m-2} + \dots \hat{\phi}_p \hat{x}_{n+m-p}$ where we use x_t instead of \hat{x}_t if x_t is available.
- always a linear combination of last p observations x_n, \ldots, x_{n-p+1}
Forecasting with AR(p)

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- **Caution:** only for short horizons *m*. For long horizons, converges to mean.

Forecasting with AR(p)

• \hat{x}_{n+m} is always a linear combination of last p observations x_n, \ldots, x_{n-p+1}

Caution: Fine for short term, but converges to mean for long horizons



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- Forecasting: mostly for short-term

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