



ITMO UNIVERSITY

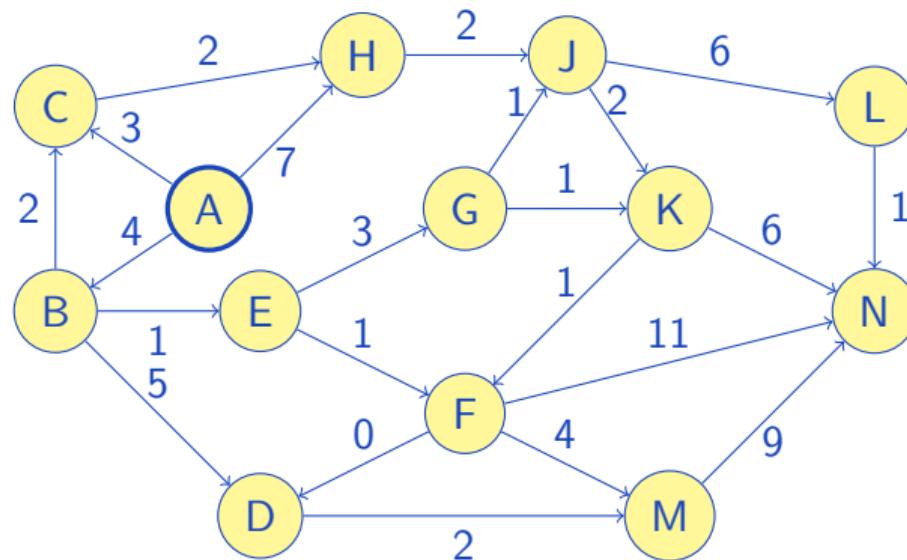
How to Win Coding Competitions: Secrets of Champions

Week 6: Algorithms on Graphs 2
Lecture 4: Single Source Shortest Paths

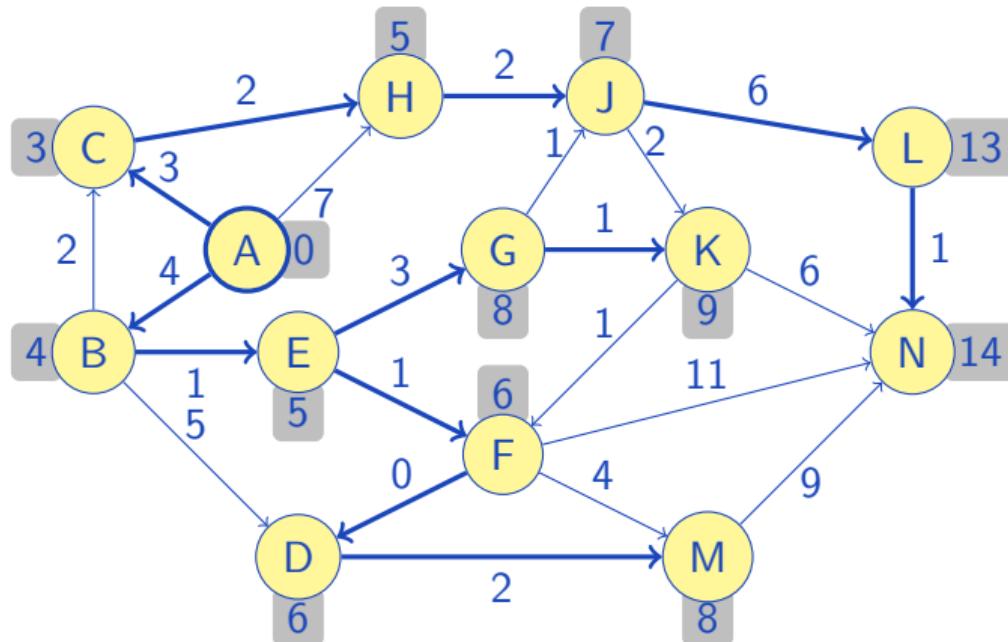
Maxim Buzdalov
Saint Petersburg 2016

Problem: for **every** vertex determine a **shortest path** from v_0

Problem: for **every** vertex determine a **shortest path** from v_0



Problem: for **every** vertex determine a **shortest path** from v_0



Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate

Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

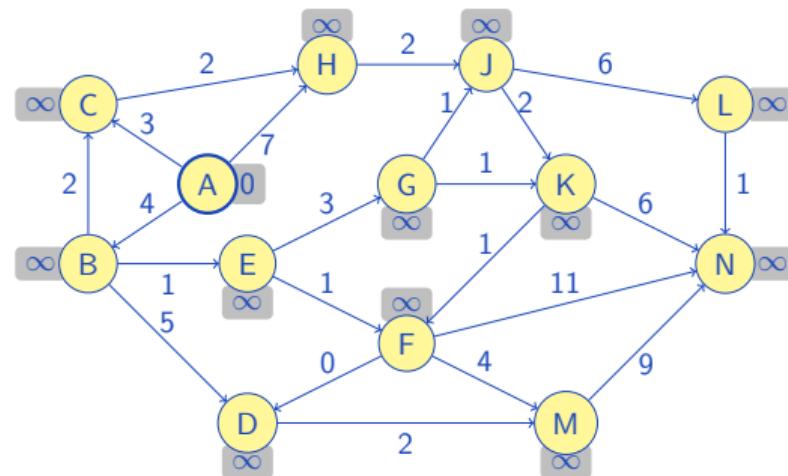
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example.



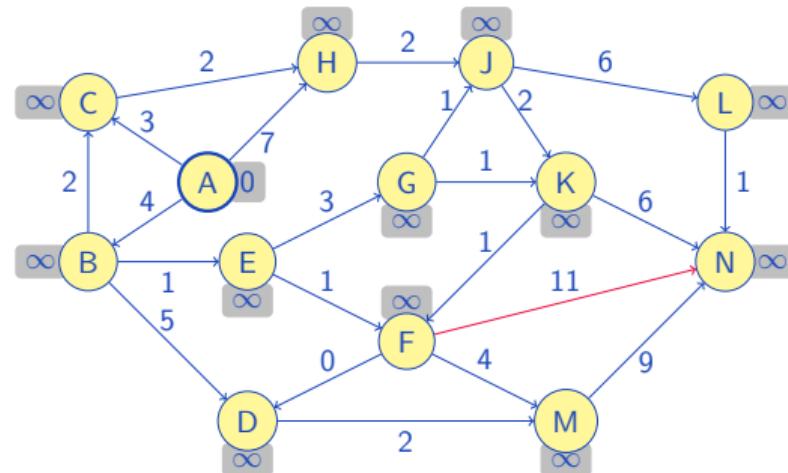
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



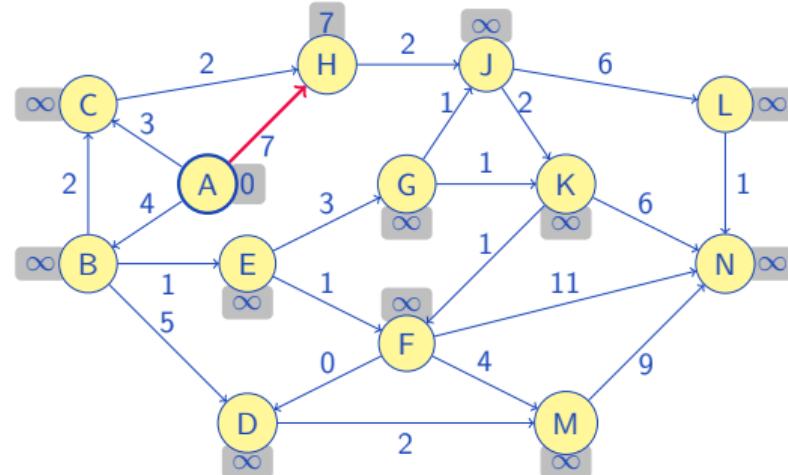
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



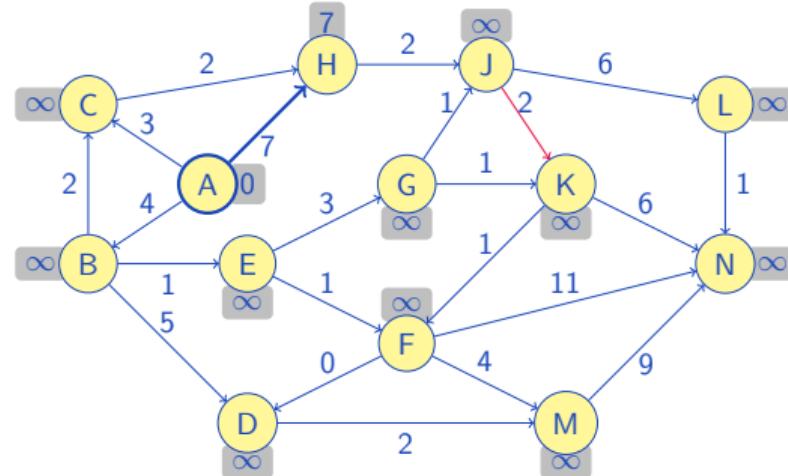
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



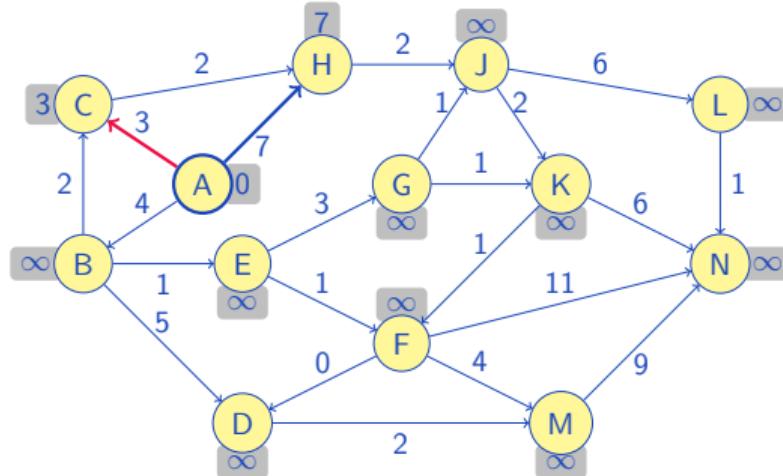
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



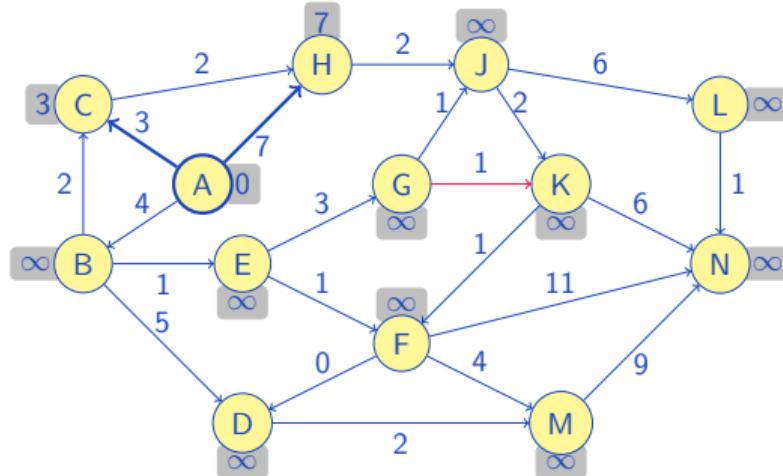
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



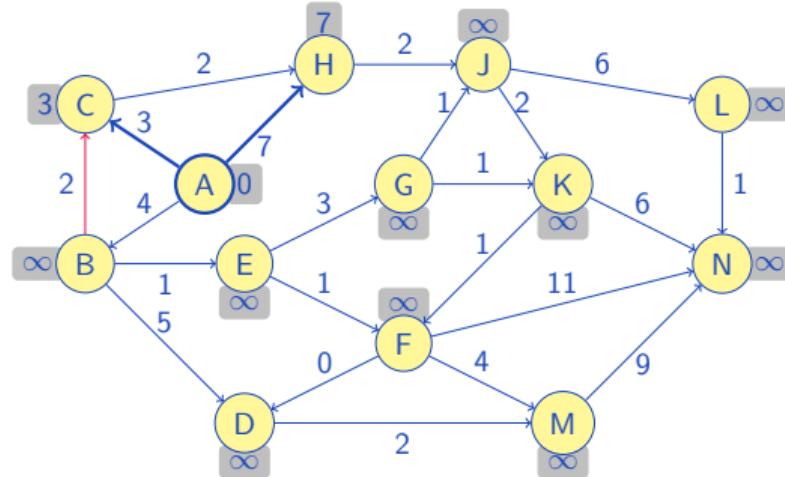
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



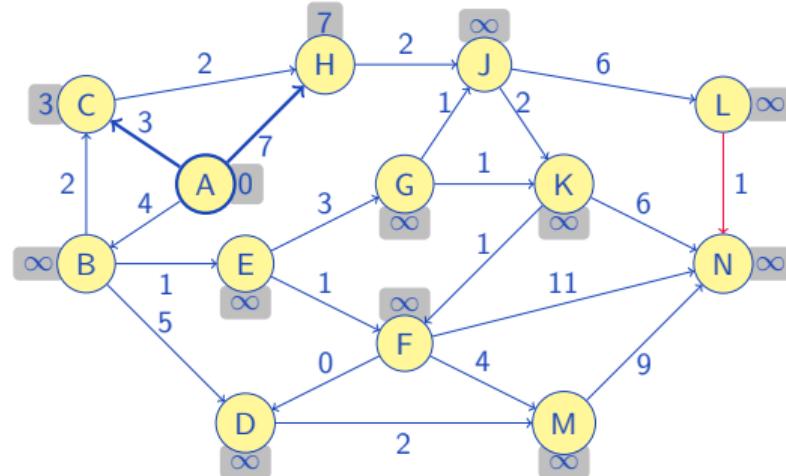
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



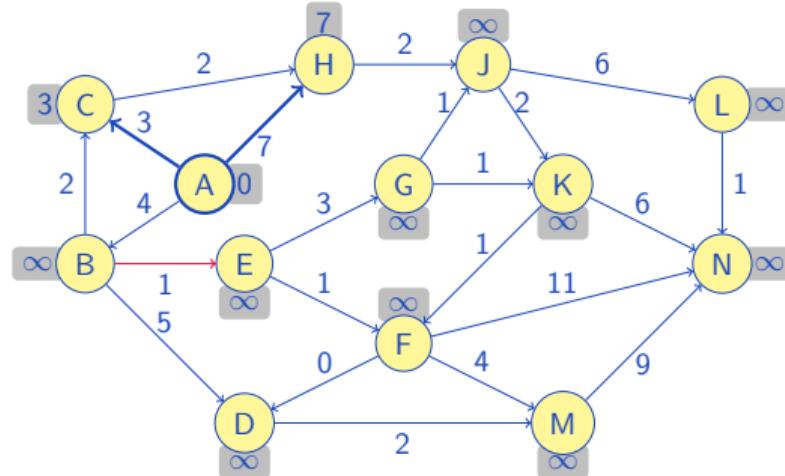
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



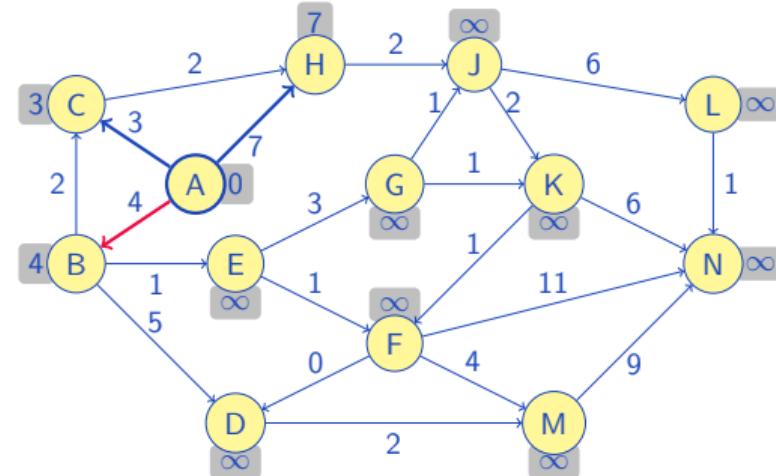
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



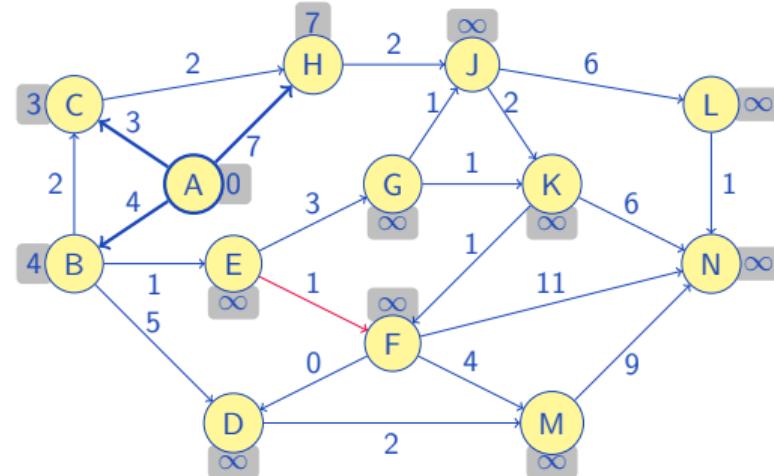
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



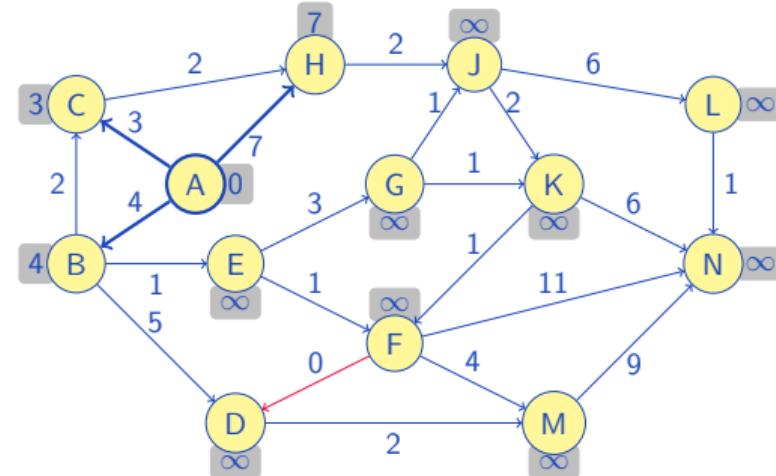
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



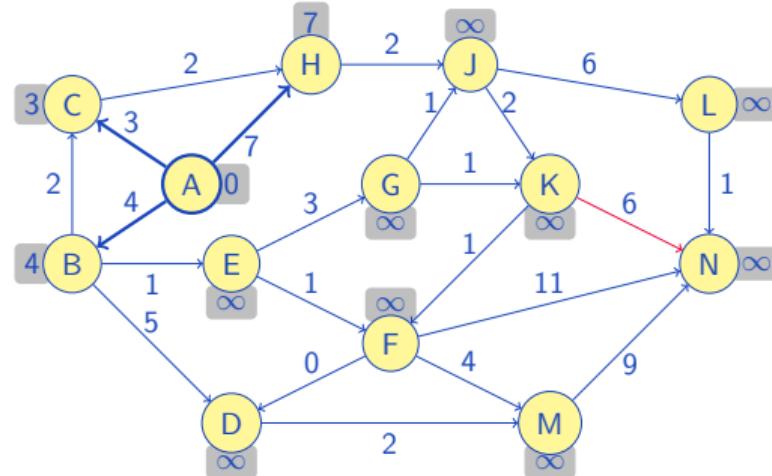
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



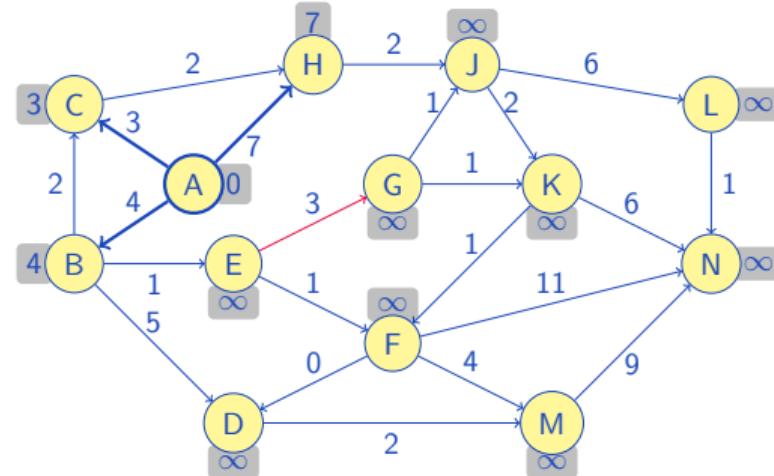
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



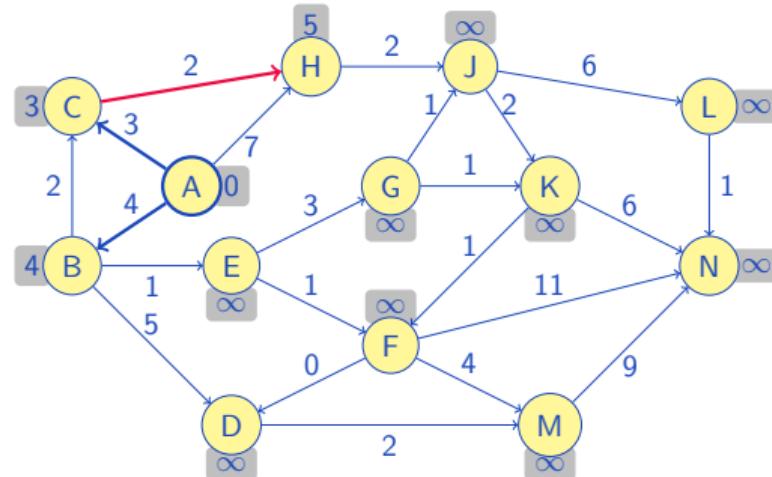
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



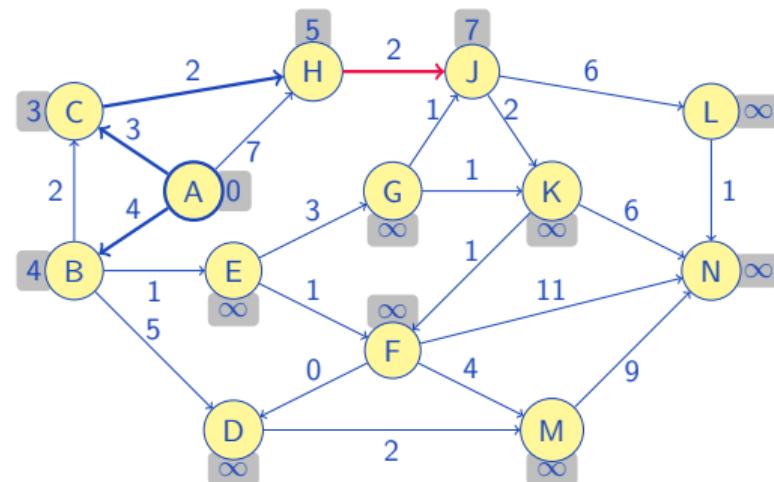
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



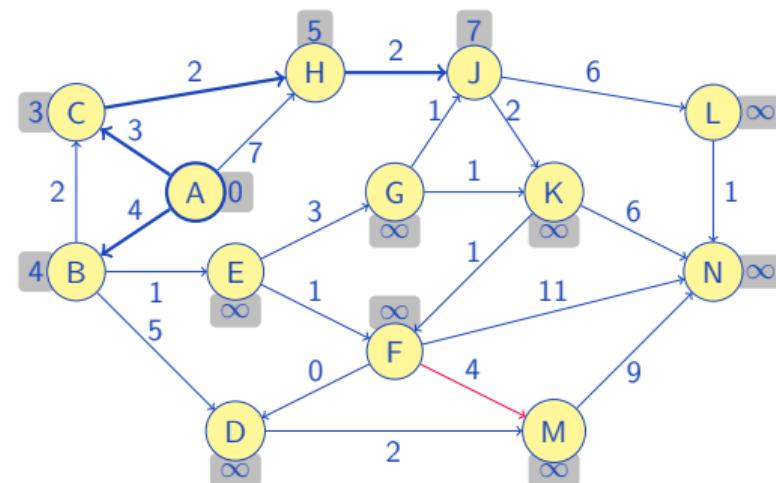
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



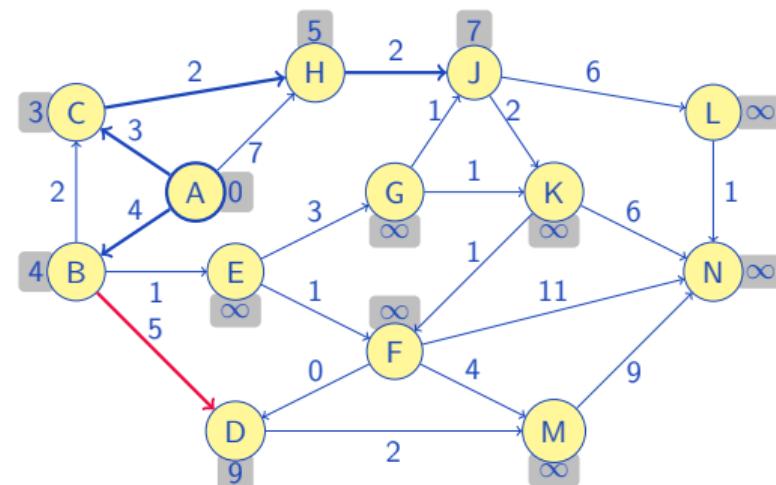
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



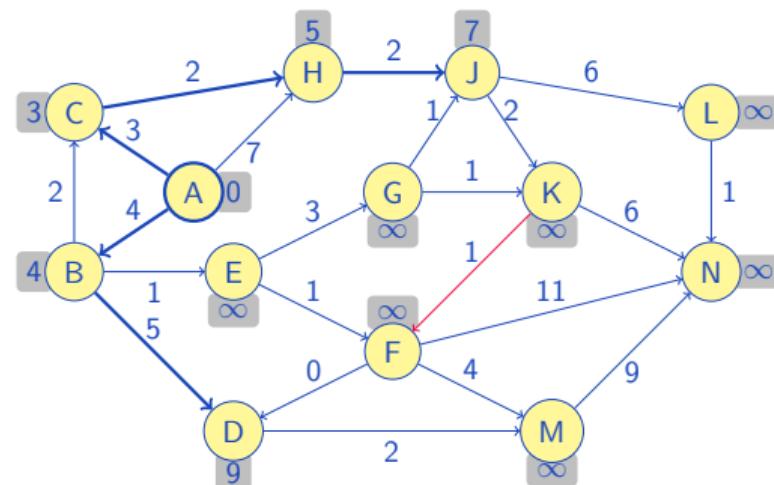
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



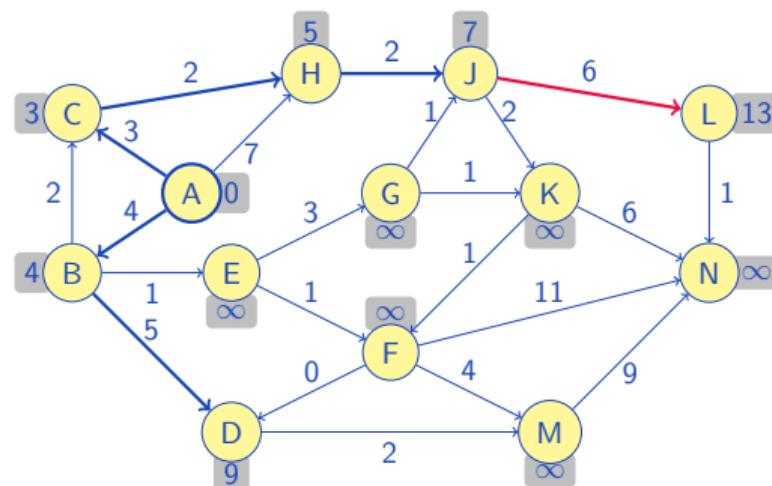
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



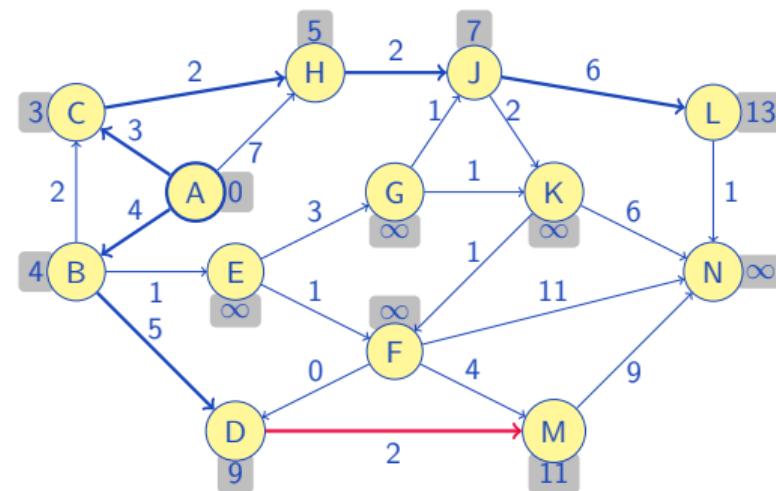
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



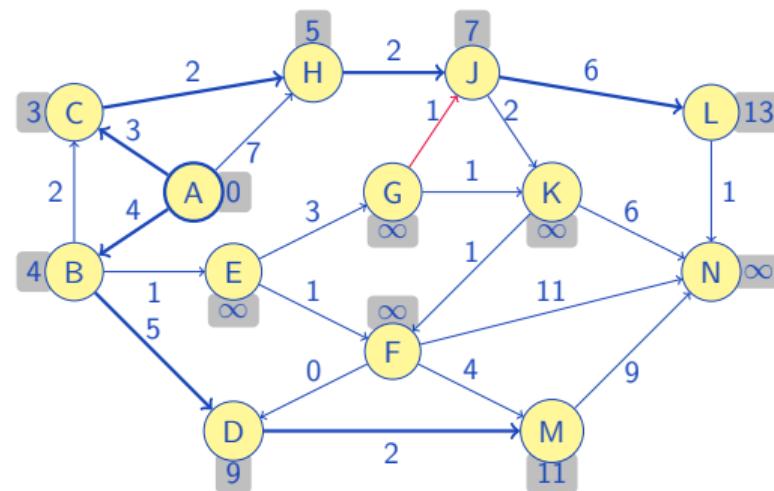
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



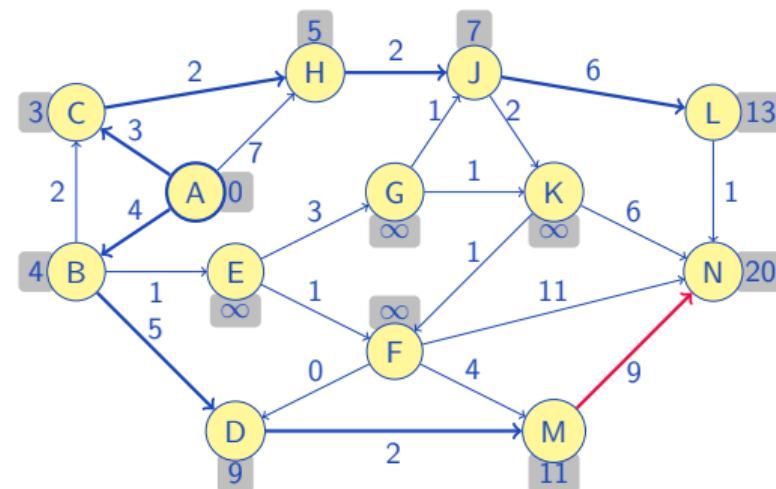
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 1



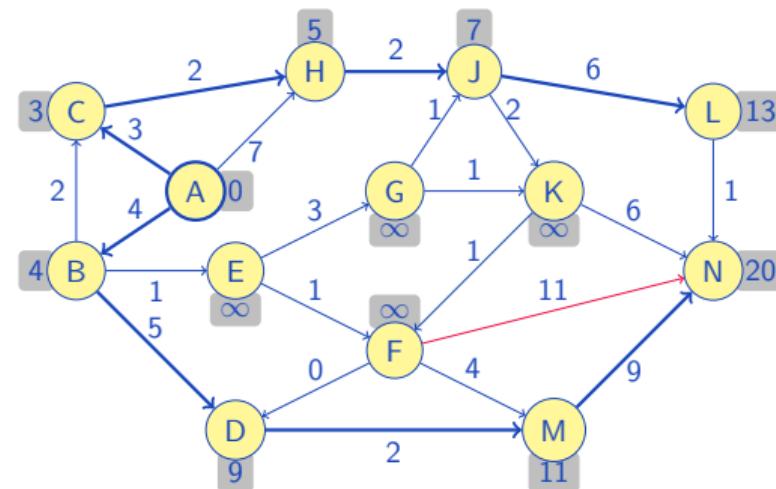
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



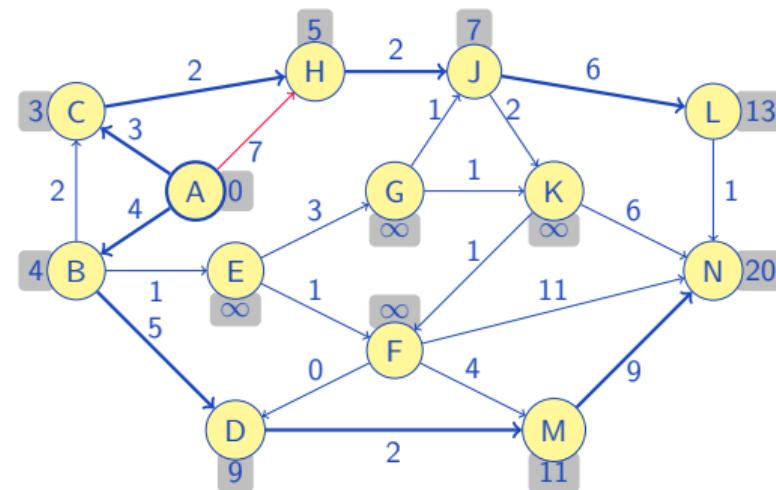
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



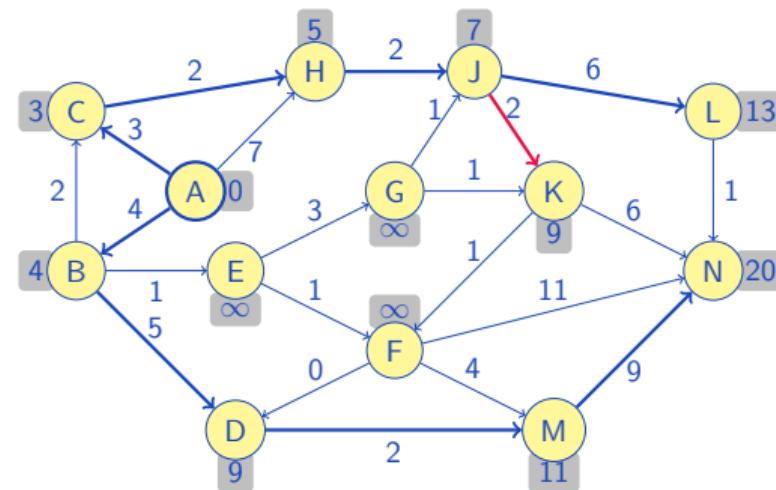
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



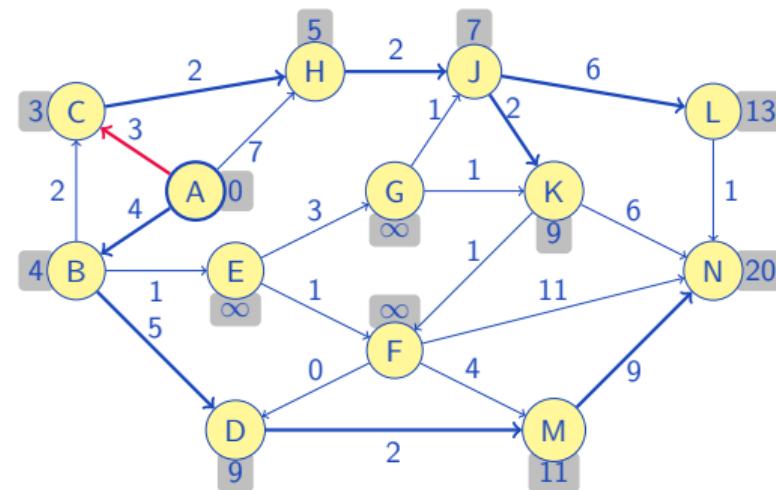
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



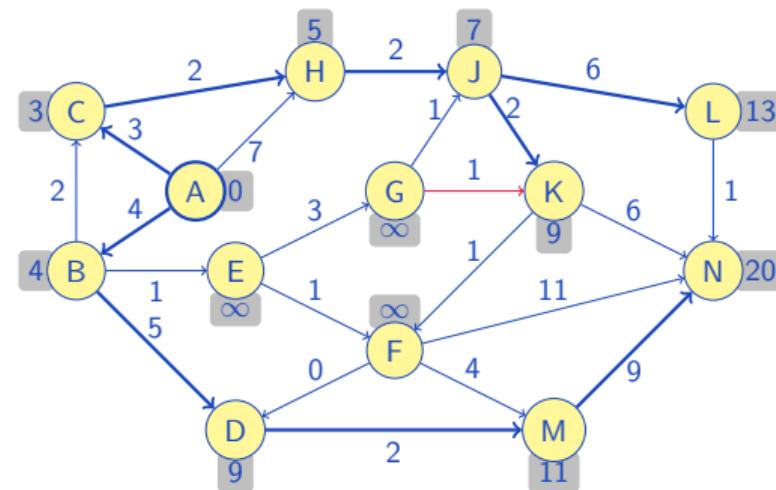
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



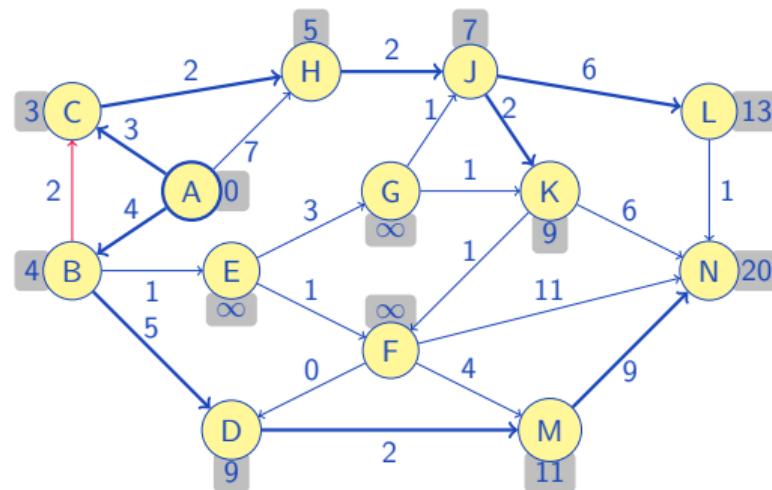
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



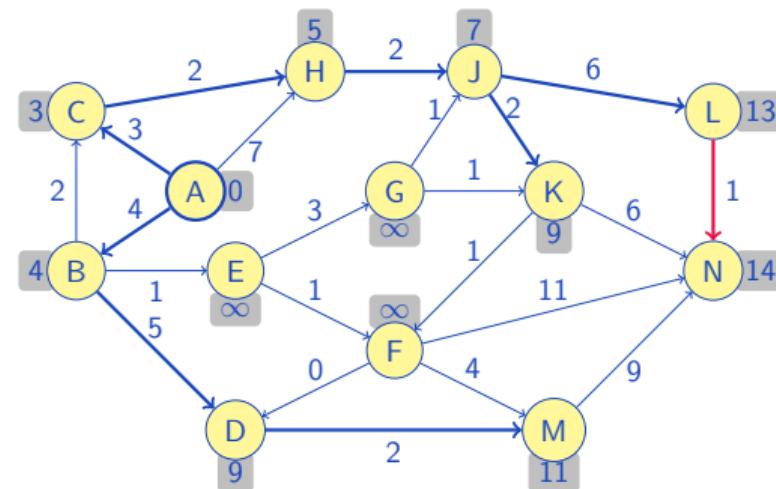
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



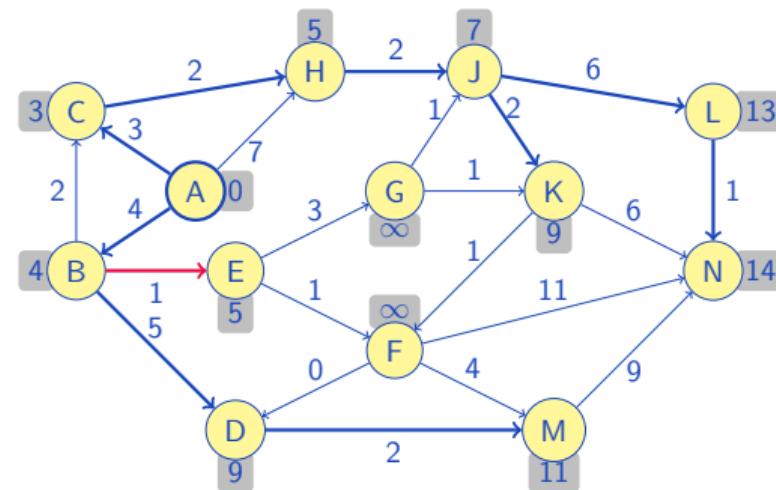
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



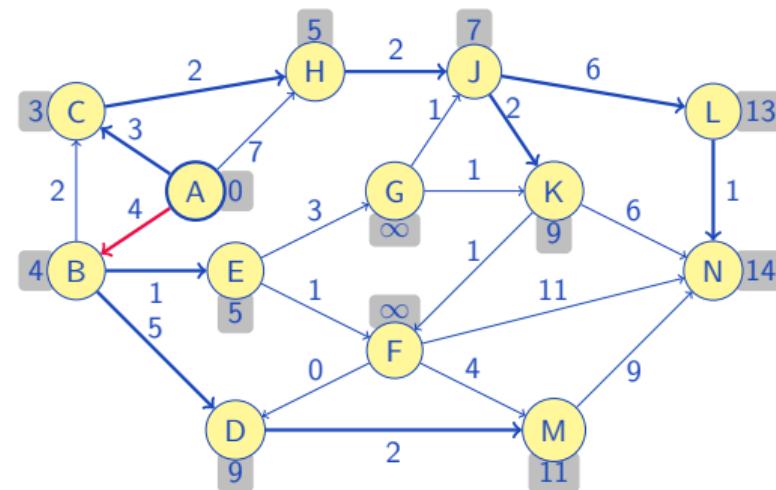
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



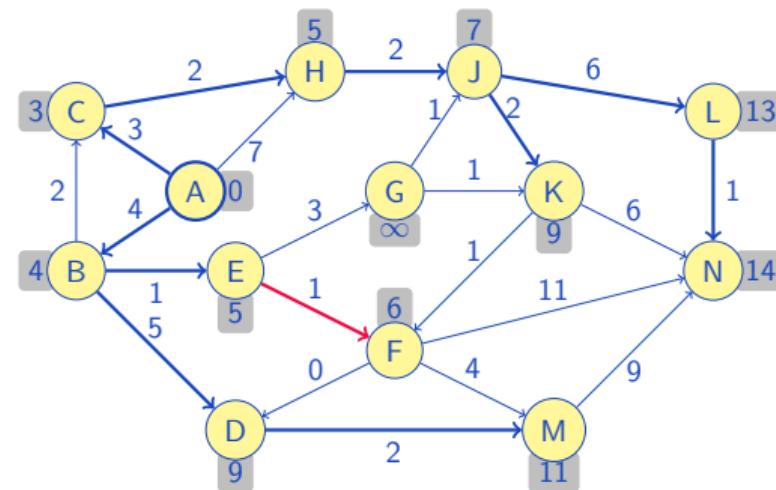
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



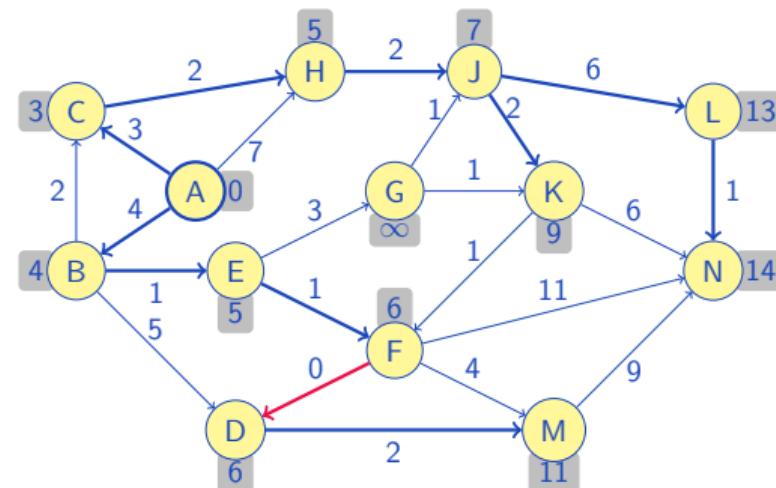
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



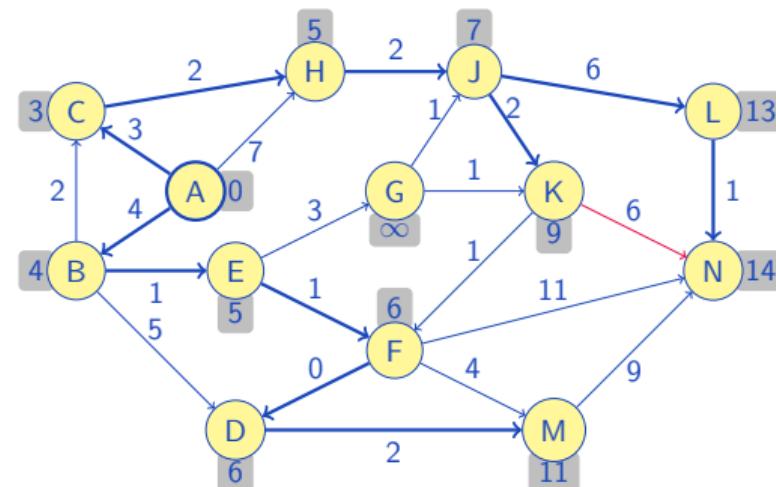
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



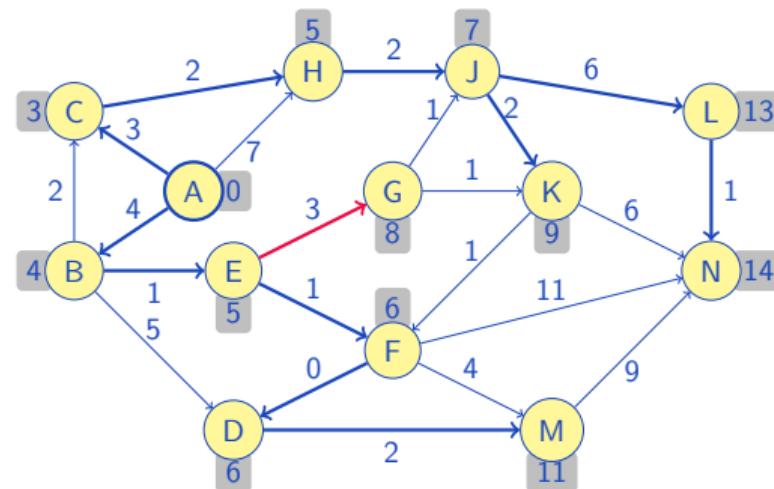
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



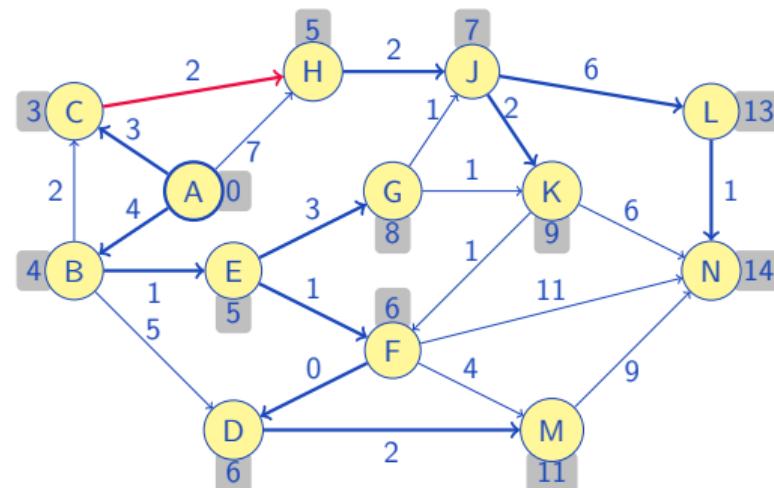
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



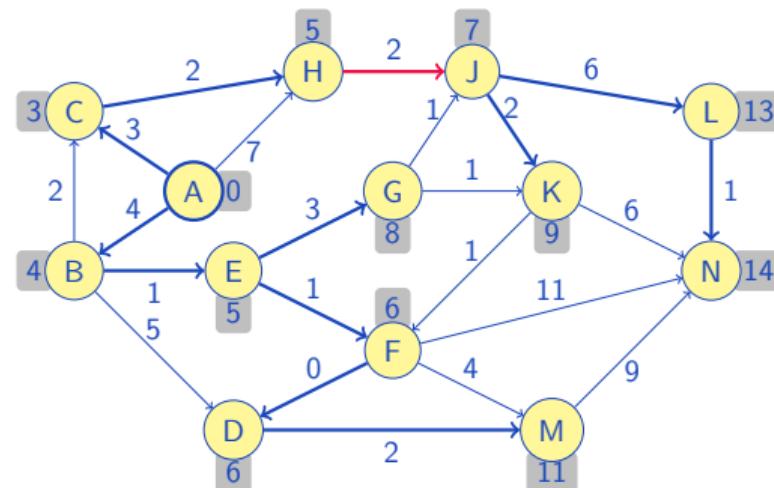
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



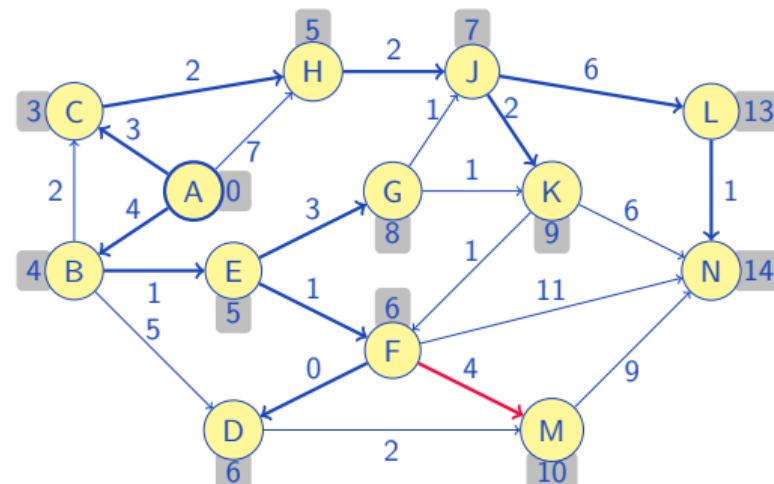
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



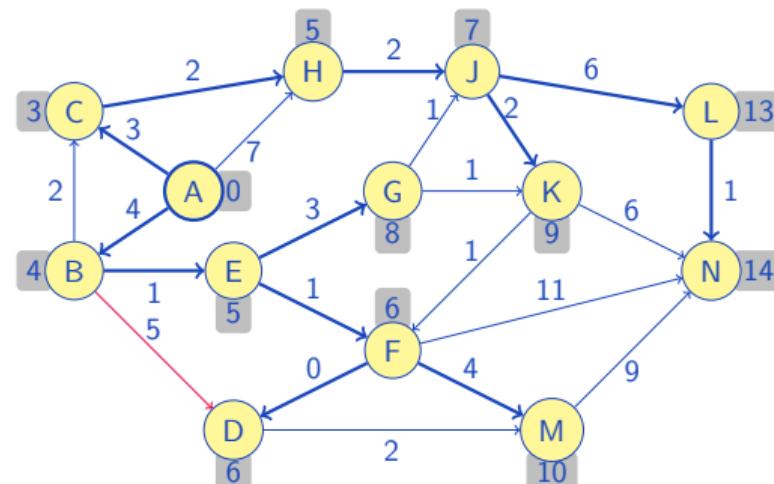
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



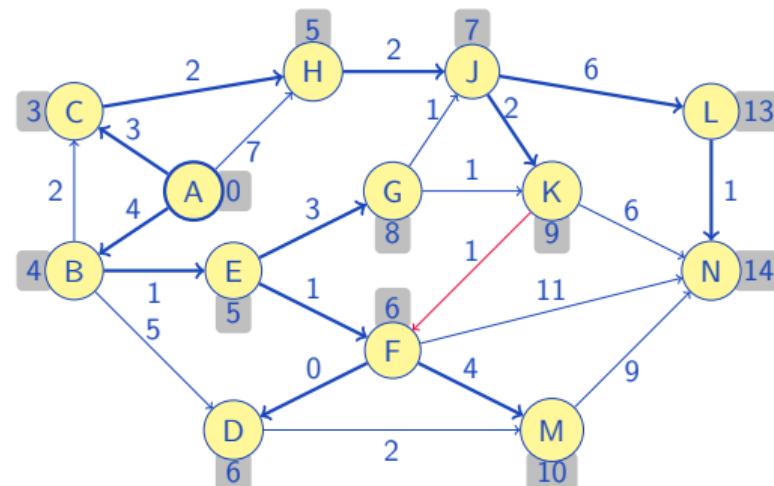
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



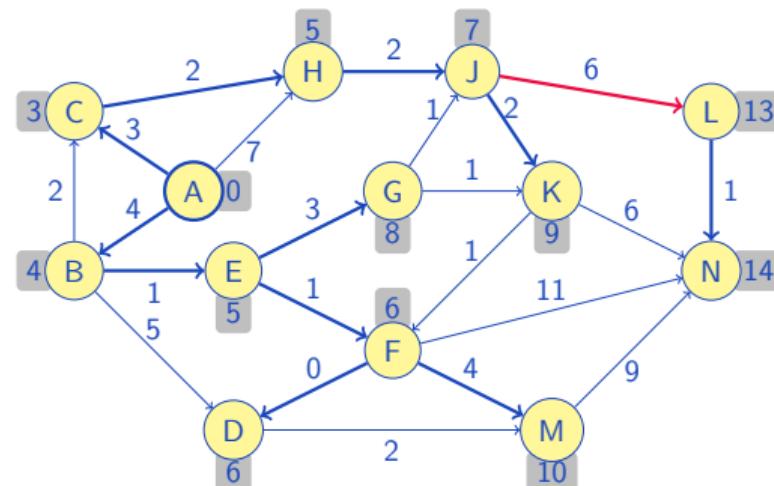
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



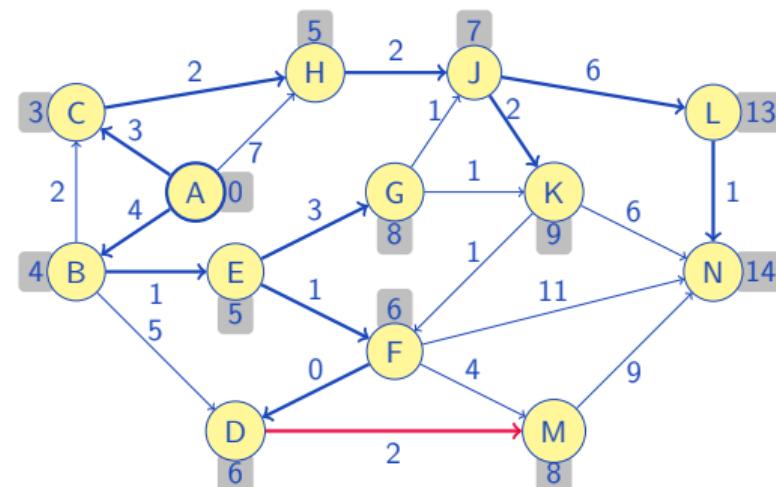
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



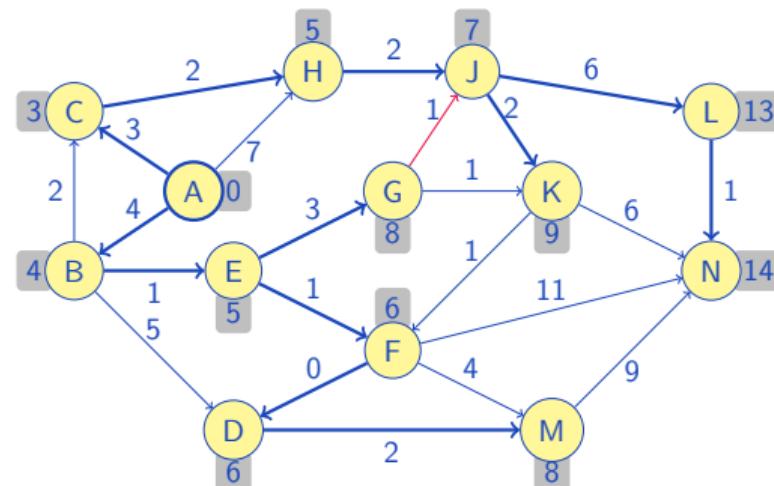
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



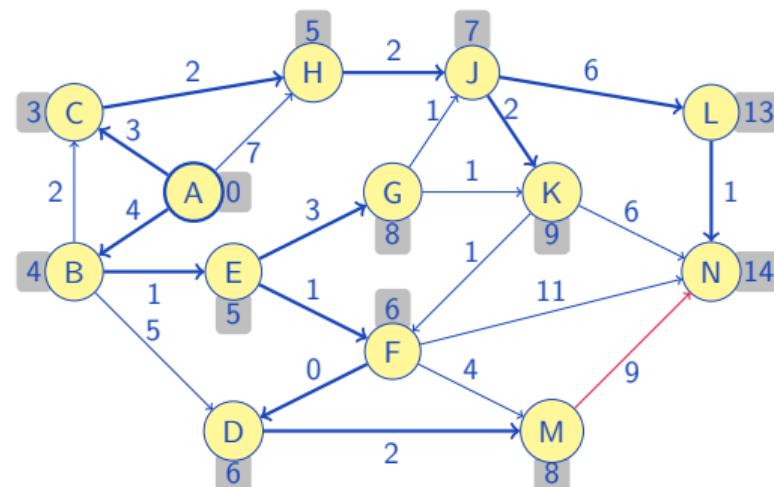
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 2



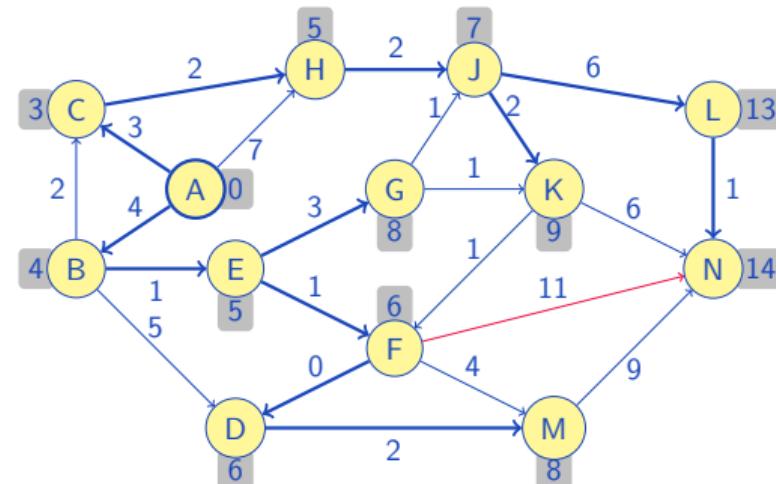
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



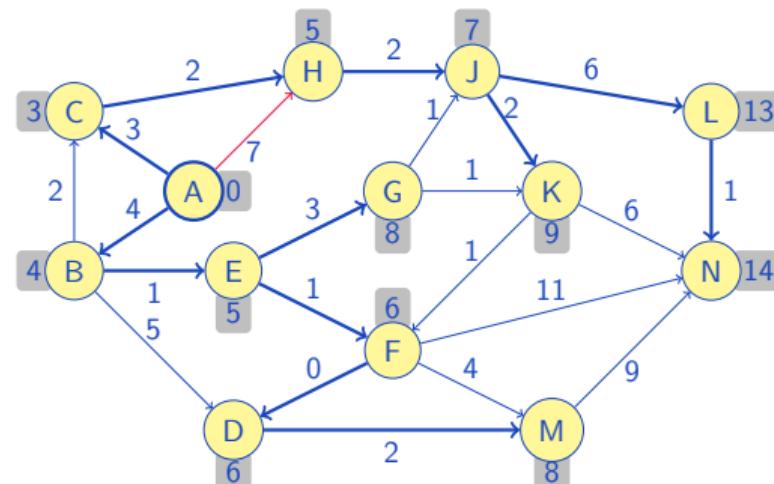
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



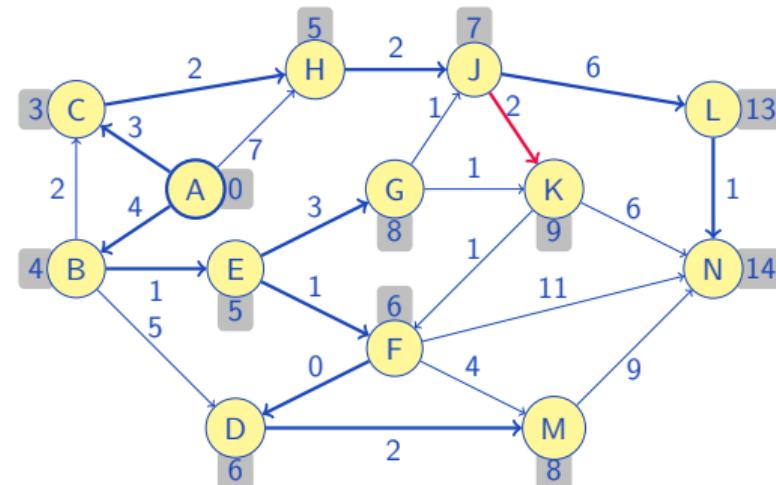
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



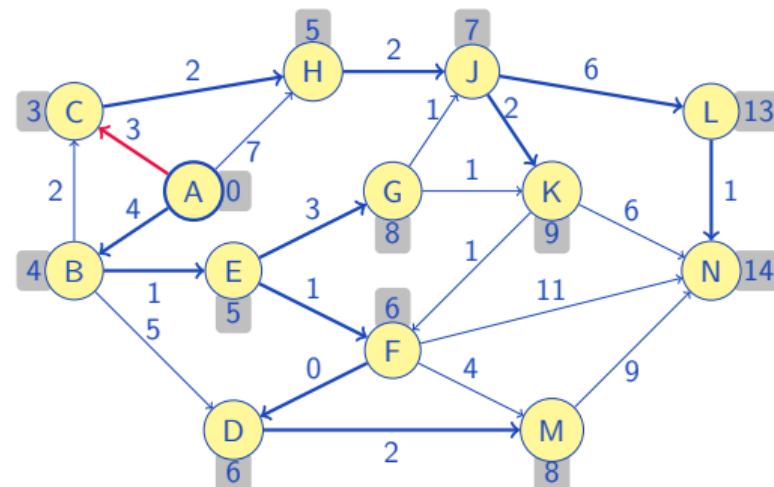
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



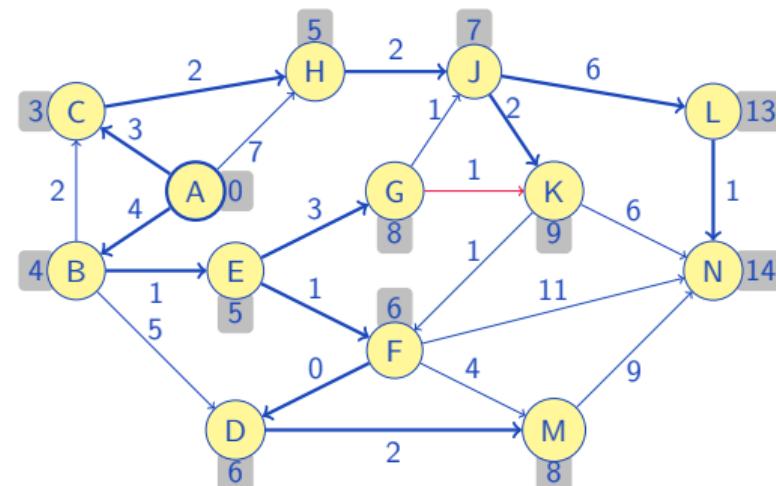
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



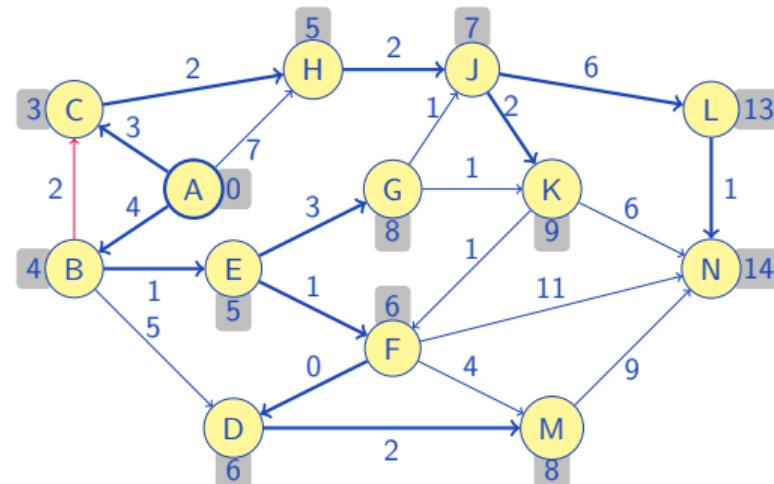
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



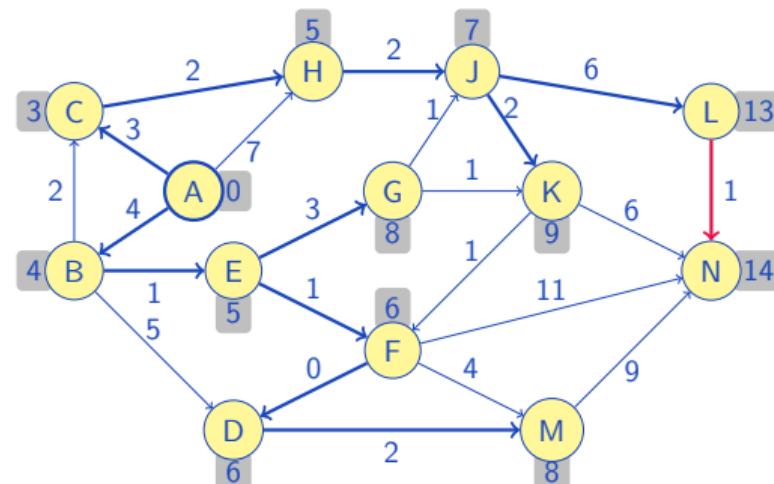
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



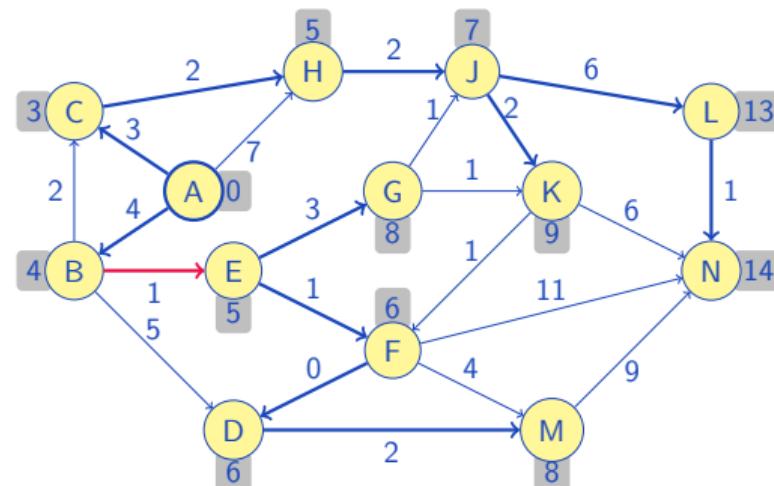
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



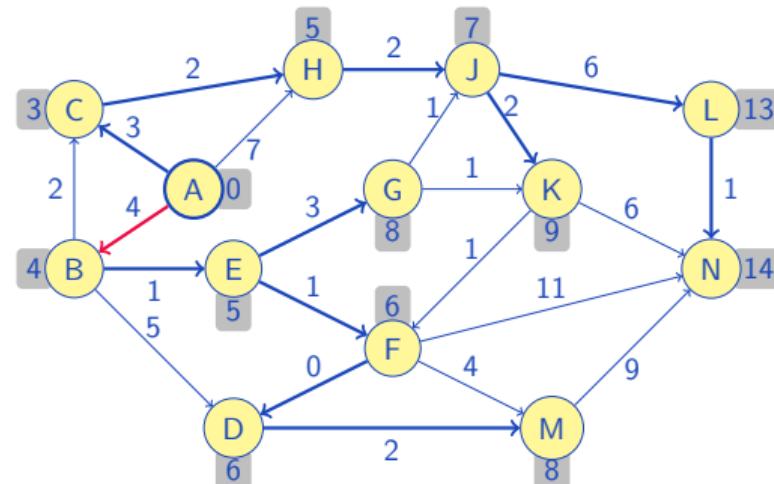
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



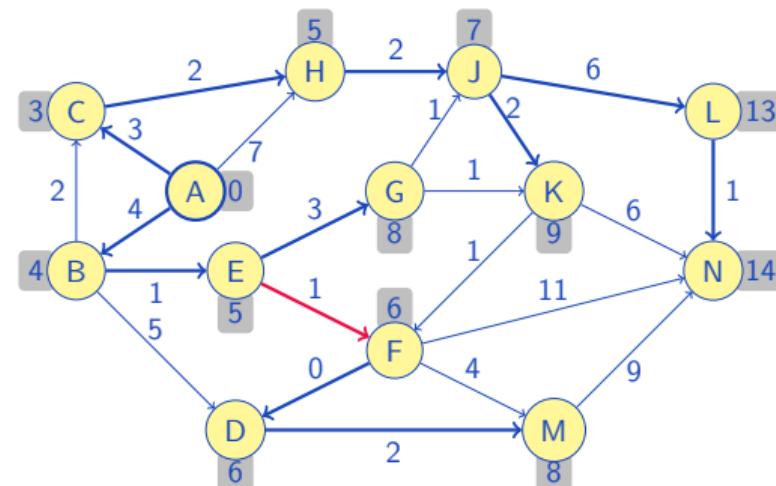
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



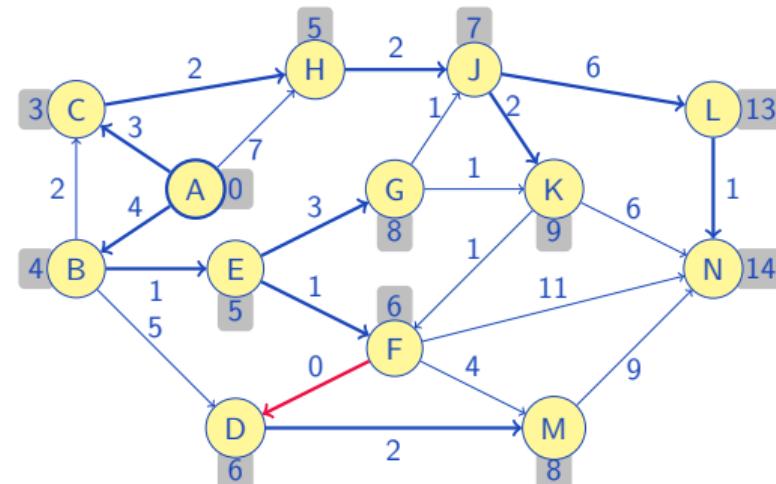
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



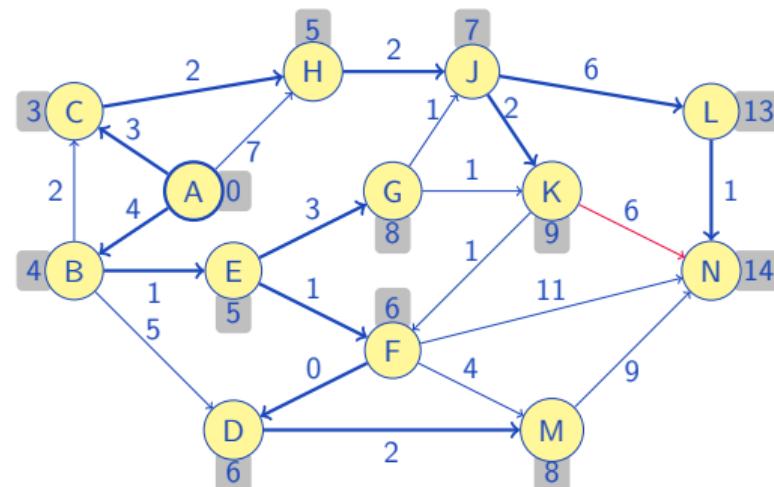
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



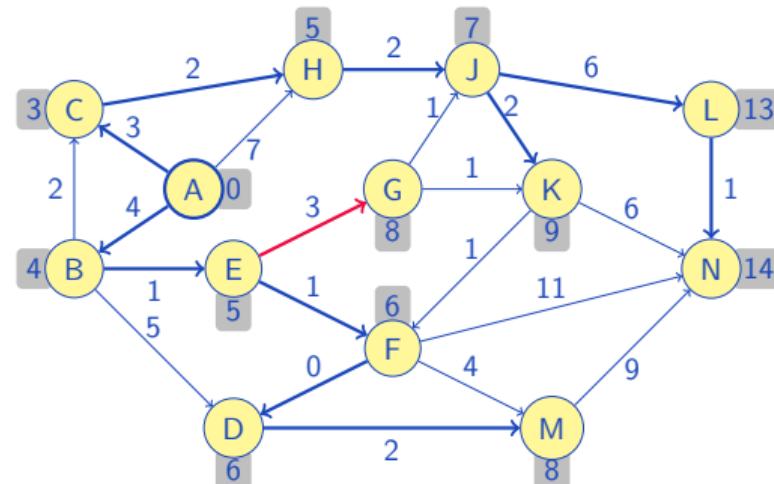
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



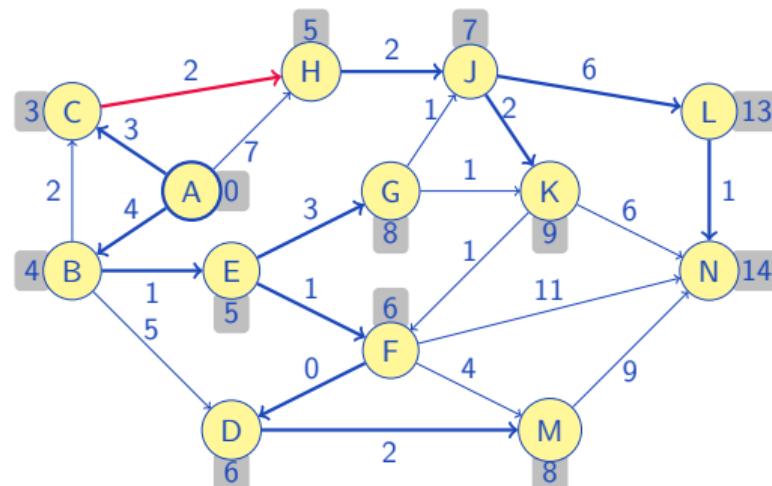
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



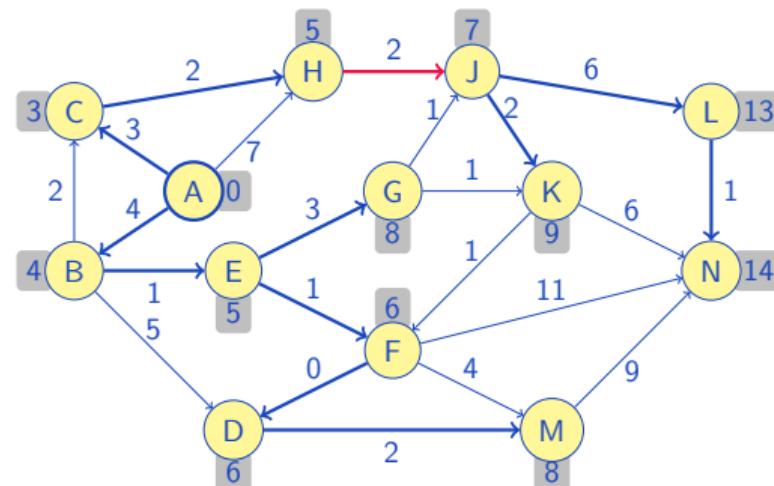
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



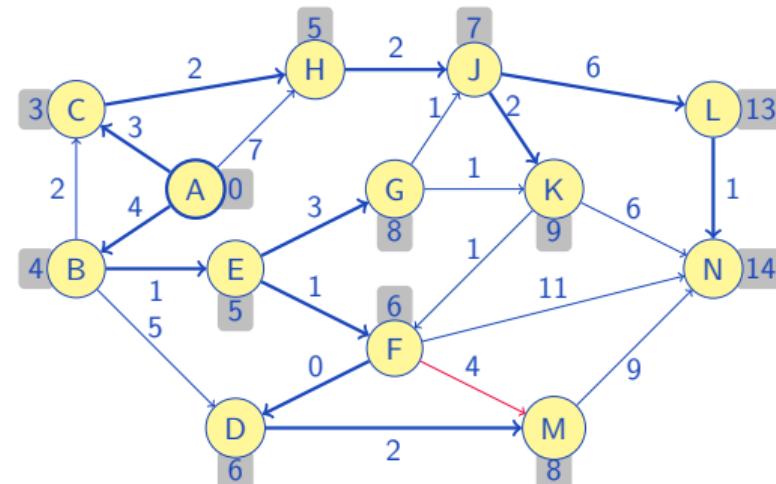
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



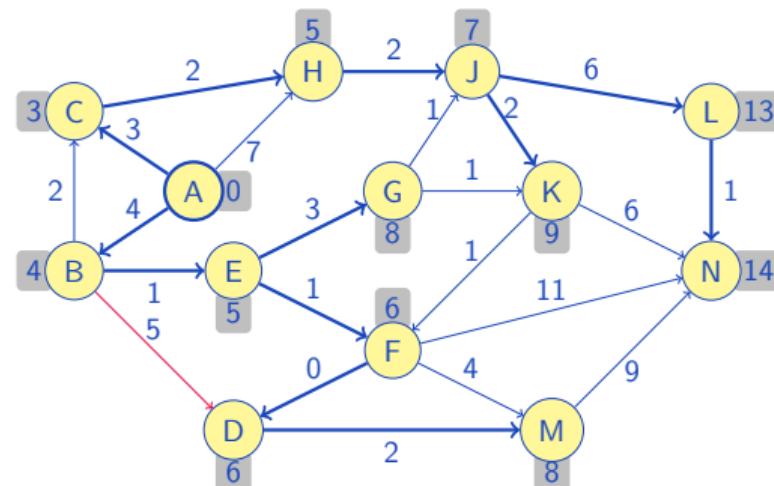
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



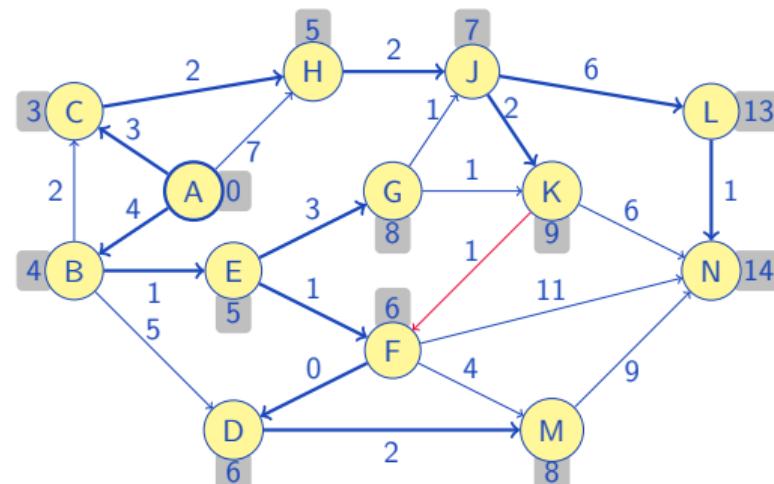
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



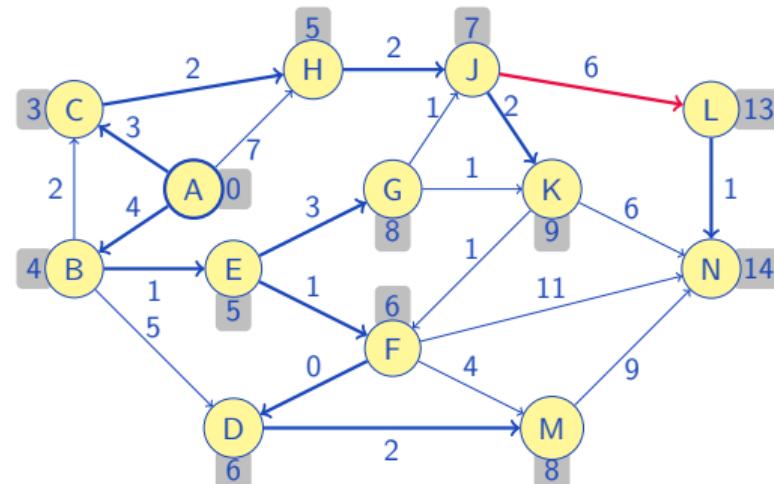
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



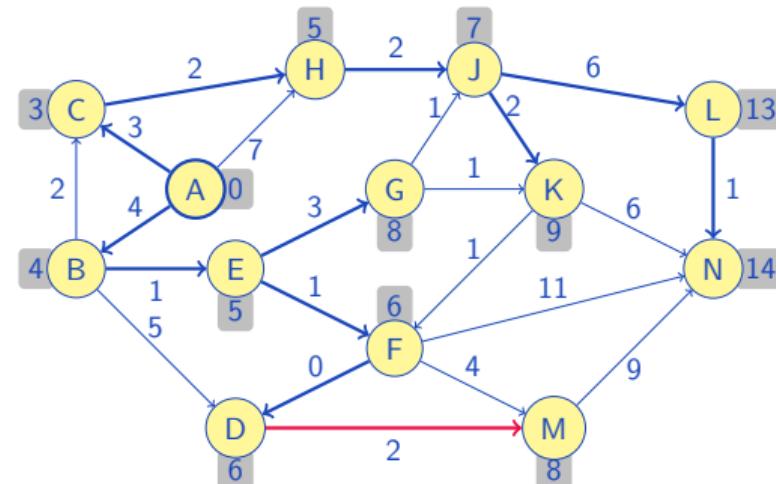
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



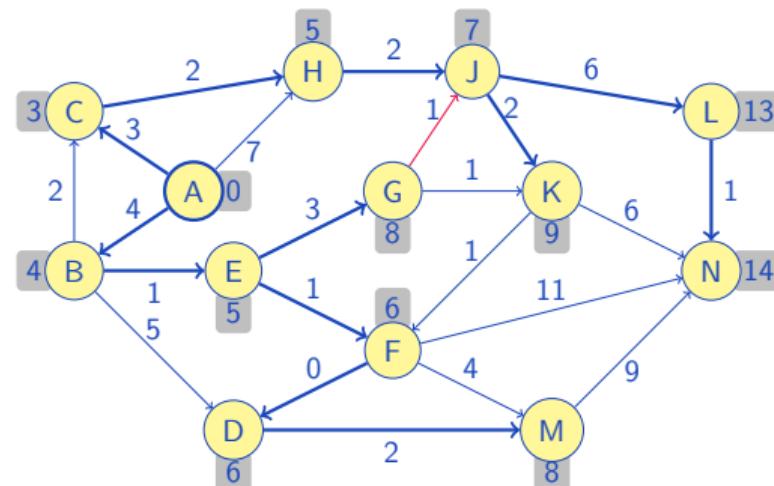
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



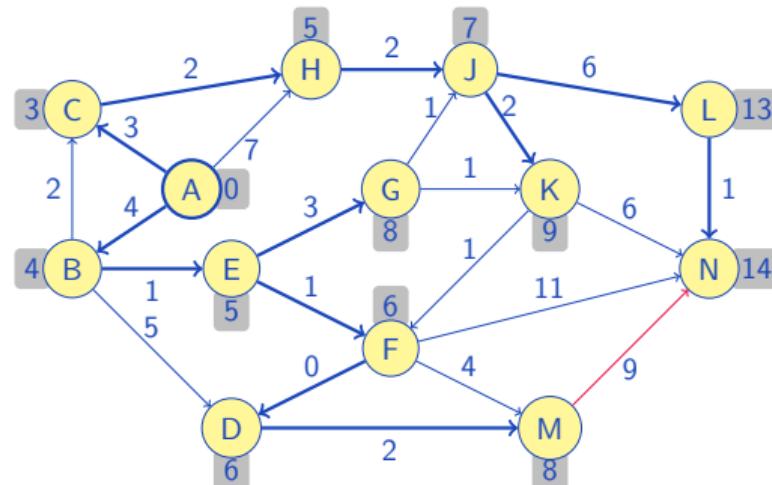
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3



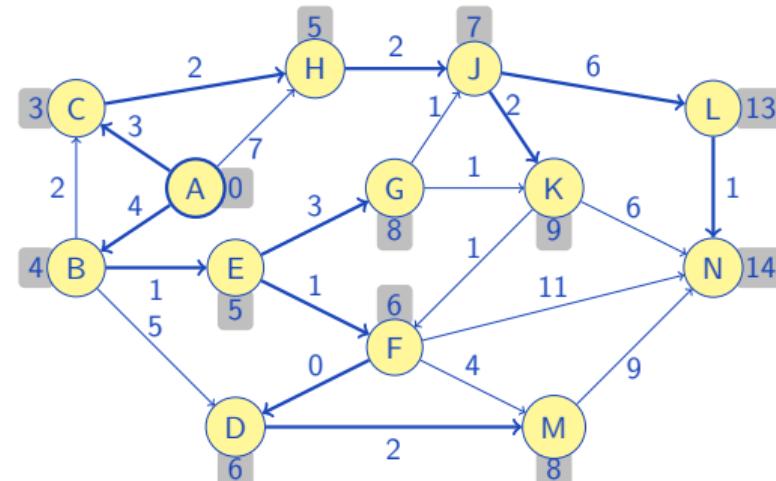
Bellman-Ford algorithm:

- ▶ Do $|V| - 1$ times:
 - ▶ Visit all edges
 - ▶ For (u, v) , update shortest distance to v
 - ▶ If nothing updated, terminate
- ▶ Running time: $O(|V| \cdot |E|)$

Why does it work?

- ▶ First k iterations build first k segments in every shortest path

Example. Iteration 3. Nothing changed. We may stop



A **negative cycle** is a cycle of total negative length

- ▶ If any vertex of the negative cycle is reachable, then there is **no shortest distance** to any vertex of this cycle, and any vertex reachable from it

A **negative cycle** is a cycle of total negative length

- ▶ If any vertex of the negative cycle is reachable, then there is **no shortest distance** to any vertex of this cycle, and any vertex reachable from it

The Bellman-Ford algorithm can detect negative cycles. How?

- ▶ Update shortest distances along all edges once more
- ▶ If a shortest distance to v changes, then v is reachable from a negative cycle

An efficient algorithm for **non-negative** edge lengths

An efficient algorithm for **non-negative** edge lengths

- ▶ Idea: Maintain a set of vertices S with determined shortest distance from v_0
 - ▶ Initially, $S = \{v_0\}$
 - ▶ For all $v \notin S$, maintain shortest distance estimation: $D'[v] = \min_{u \in S} D[u] + L(u, v)$

An efficient algorithm for **non-negative** edge lengths

- ▶ Idea: Maintain a set of vertices S with determined shortest distance from v_0
 - ▶ Initially, $S = \{v_0\}$
 - ▶ For all $v \notin S$, maintain shortest distance estimation: $D'[v] = \min_{u \in S} D[u] + L(u, v)$
- ▶ Lemma: For a $v \notin S$ with the smallest $D'[v]$, the shortest distance is $D'[v]$

An efficient algorithm for **non-negative** edge lengths

- ▶ Idea: Maintain a set of vertices S with determined shortest distance from v_0
 - ▶ Initially, $S = \{v_0\}$
 - ▶ For all $v \notin S$, maintain shortest distance estimation: $D'[v] = \min_{u \in S} D[u] + L(u, v)$
- ▶ Lemma: For a $v \notin S$ with the smallest $D'[v]$, the shortest distance is $D'[v]$
 - ▶ Assume it is not true
 - ▶ There is another path which yields a distance **strictly smaller** than $D'[v]$

An efficient algorithm for **non-negative** edge lengths

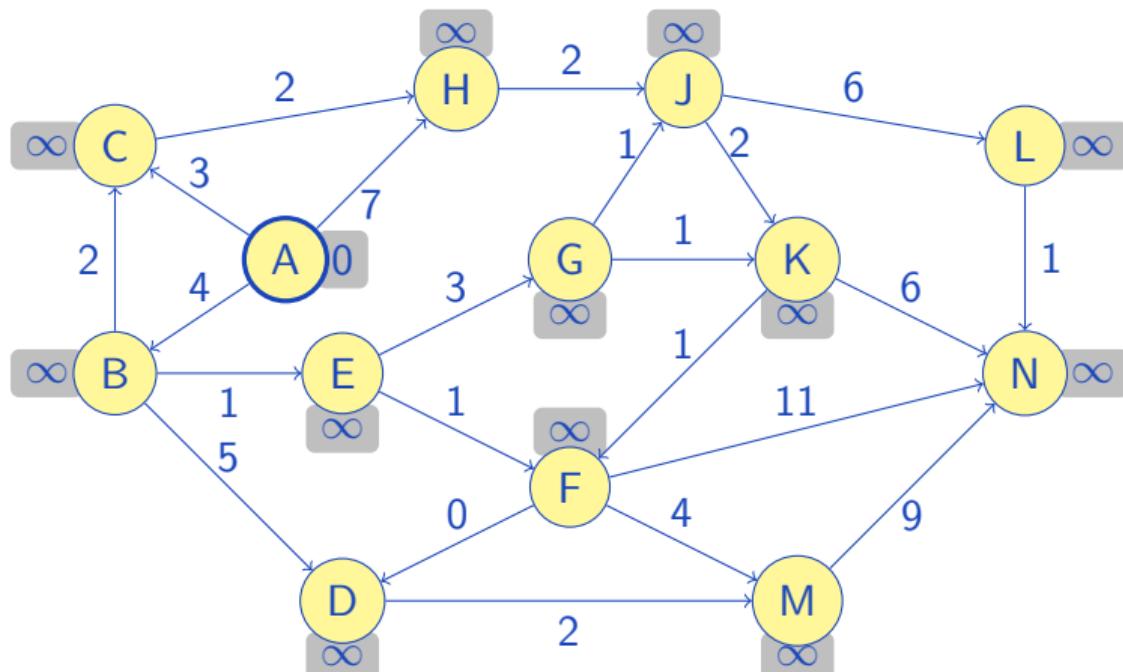
- ▶ Idea: Maintain a set of vertices S with determined shortest distance from v_0
 - ▶ Initially, $S = \{v_0\}$
 - ▶ For all $v \notin S$, maintain shortest distance estimation: $D'[v] = \min_{u \in S} D[u] + L(u, v)$
- ▶ Lemma: For a $v \notin S$ with the smallest $D'[v]$, the shortest distance is $D'[v]$
 - ▶ Assume it is not true
 - ▶ There is another path which yields a distance **strictly smaller** than $D'[v]$
 - ▶ It should go through other $v' \notin S$

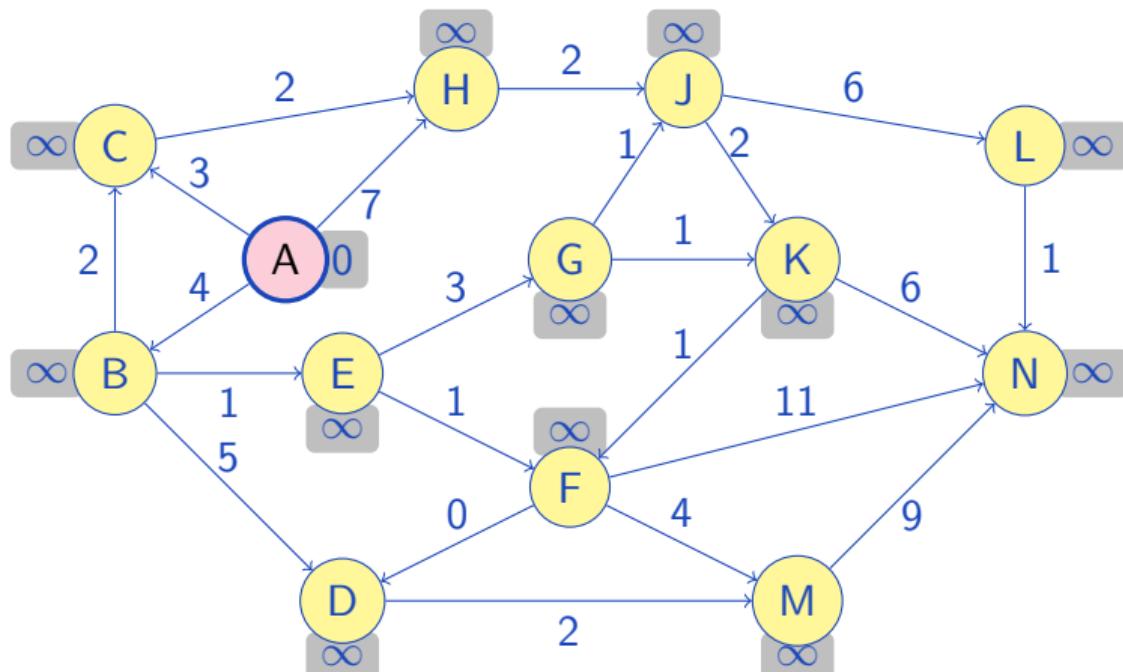
An efficient algorithm for **non-negative** edge lengths

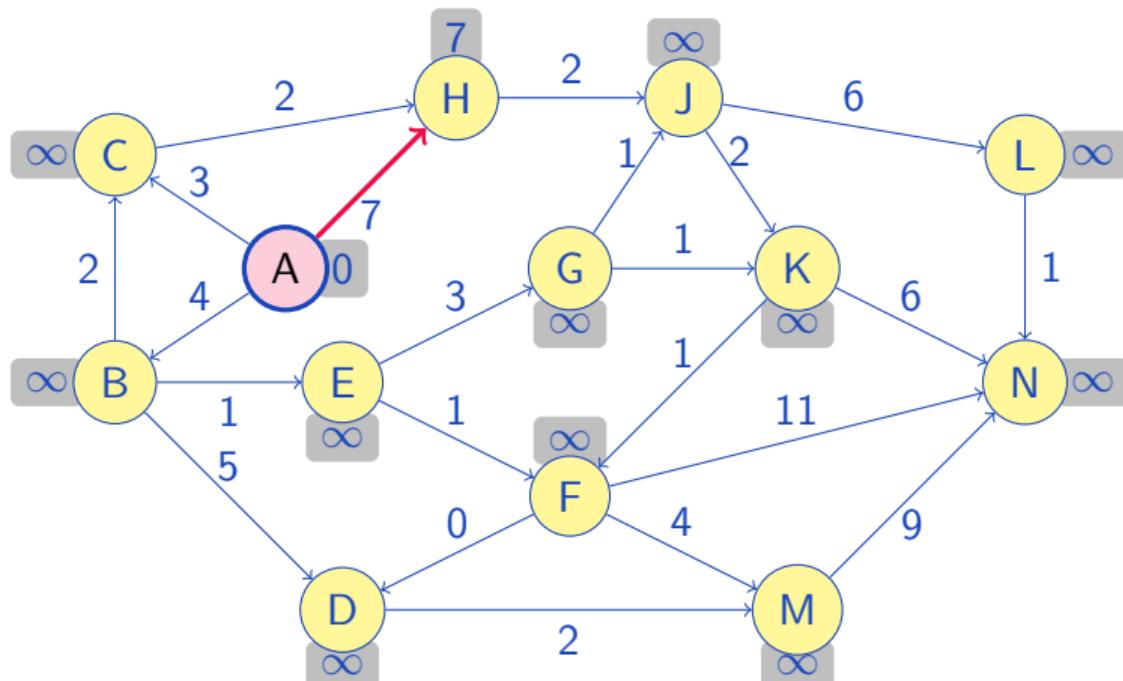
- ▶ Idea: Maintain a set of vertices S with determined shortest distance from v_0
 - ▶ Initially, $S = \{v_0\}$
 - ▶ For all $v \notin S$, maintain shortest distance estimation: $D'[v] = \min_{u \in S} D[u] + L(u, v)$
- ▶ Lemma: For a $v \notin S$ with the smallest $D'[v]$, the shortest distance is $D'[v]$
 - ▶ Assume it is not true
 - ▶ There is another path which yields a distance **strictly smaller** than $D'[v]$
 - ▶ It should go through other $v' \notin S$
 - ▶ But edge lengths are non-negative → **contradiction**

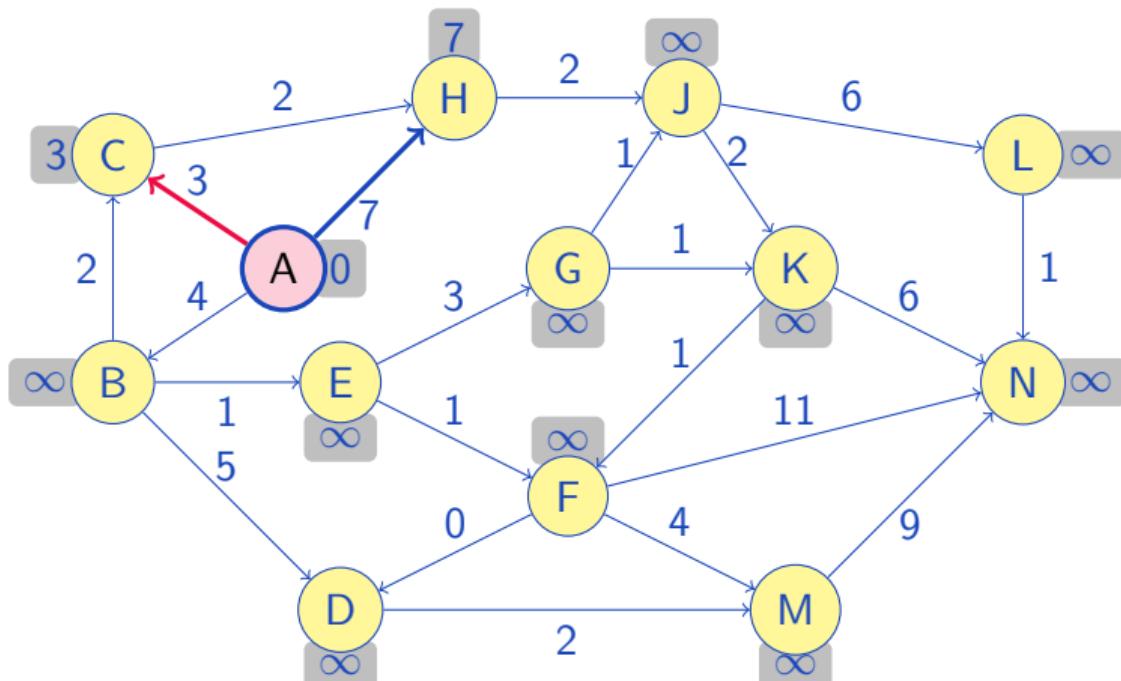
An efficient algorithm for **non-negative** edge lengths

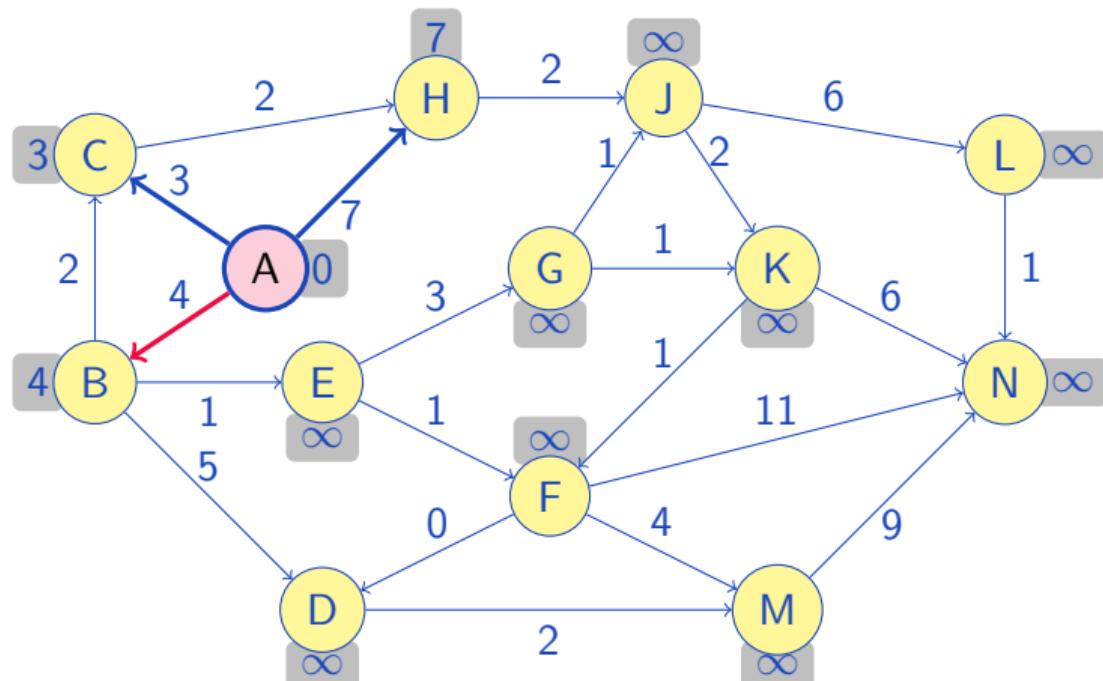
- ▶ Idea: Maintain a set of vertices S with determined shortest distance from v_0
 - ▶ Initially, $S = \{v_0\}$
 - ▶ For all $v \notin S$, maintain shortest distance estimation: $D'[v] = \min_{u \in S} D[u] + L(u, v)$
- ▶ Lemma: For a $v \notin S$ with the smallest $D'[v]$, the shortest distance is $D'[v]$
 - ▶ Assume it is not true
 - ▶ There is another path which yields a distance **strictly smaller** than $D'[v]$
 - ▶ It should go through other $v' \notin S$
 - ▶ But edge lengths are non-negative → **contradiction**
- ▶ How to update S :
 - ▶ Choose $v \notin S$ with the smallest $D'[v]$
 - ▶ Set $D[v] = D'[v]$
 - ▶ $S \leftarrow S \cup \{v\}$
 - ▶ For all edges $(v, v') \in E$, **update** $D'[v'] \leftarrow \min(D'[v'], D[v] + L(v, v'))$

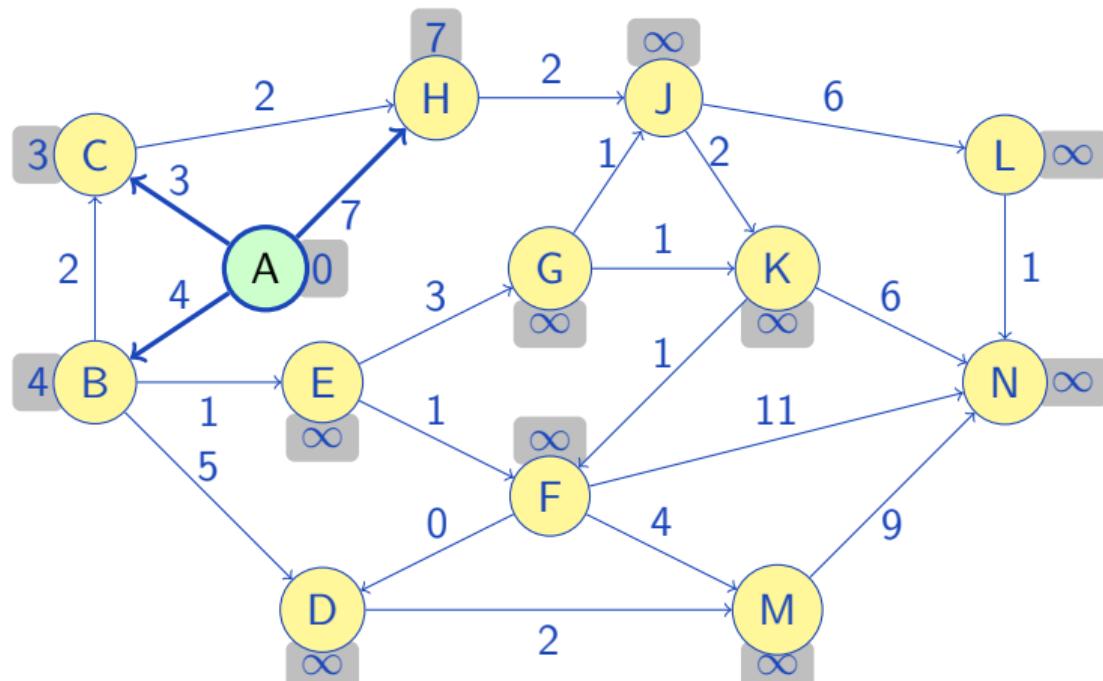


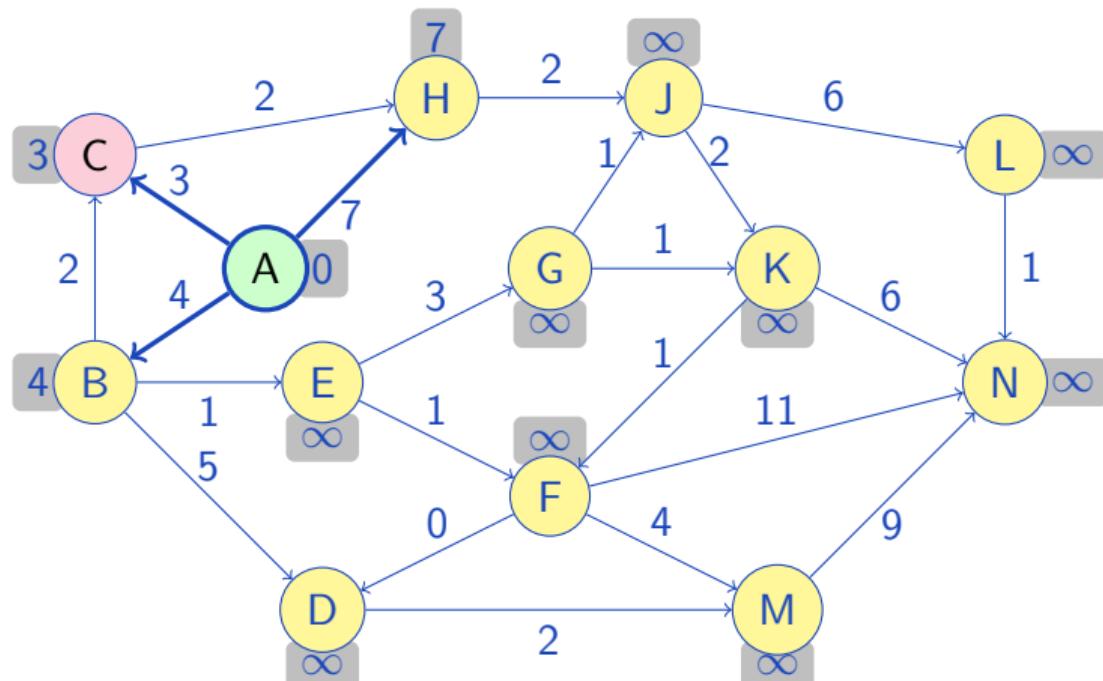


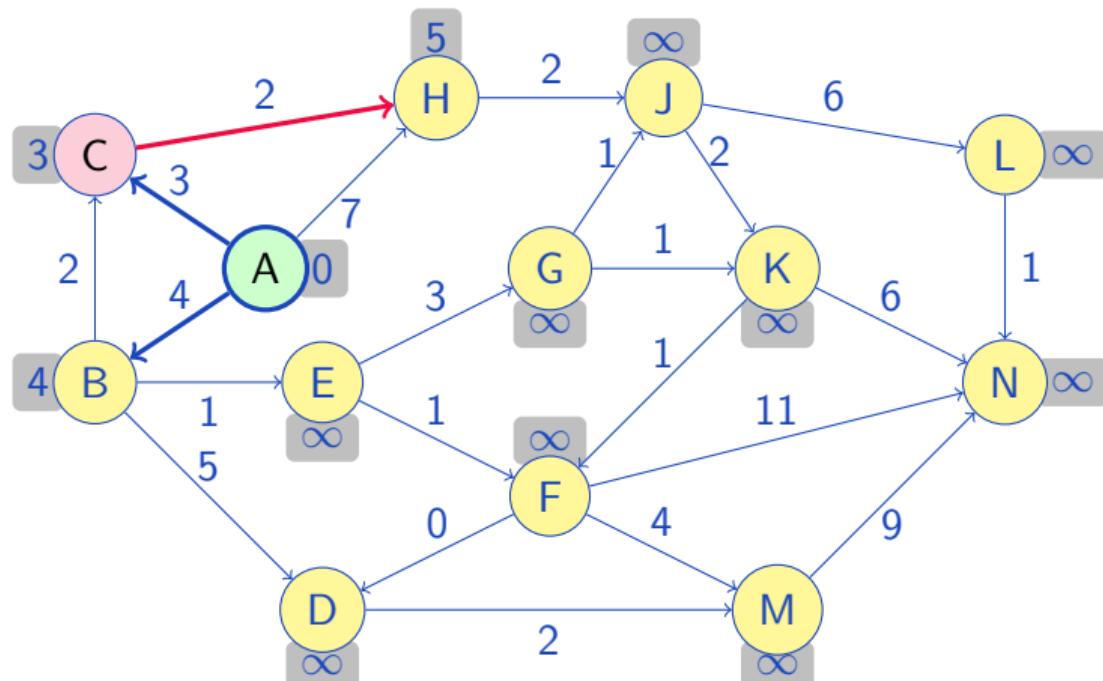


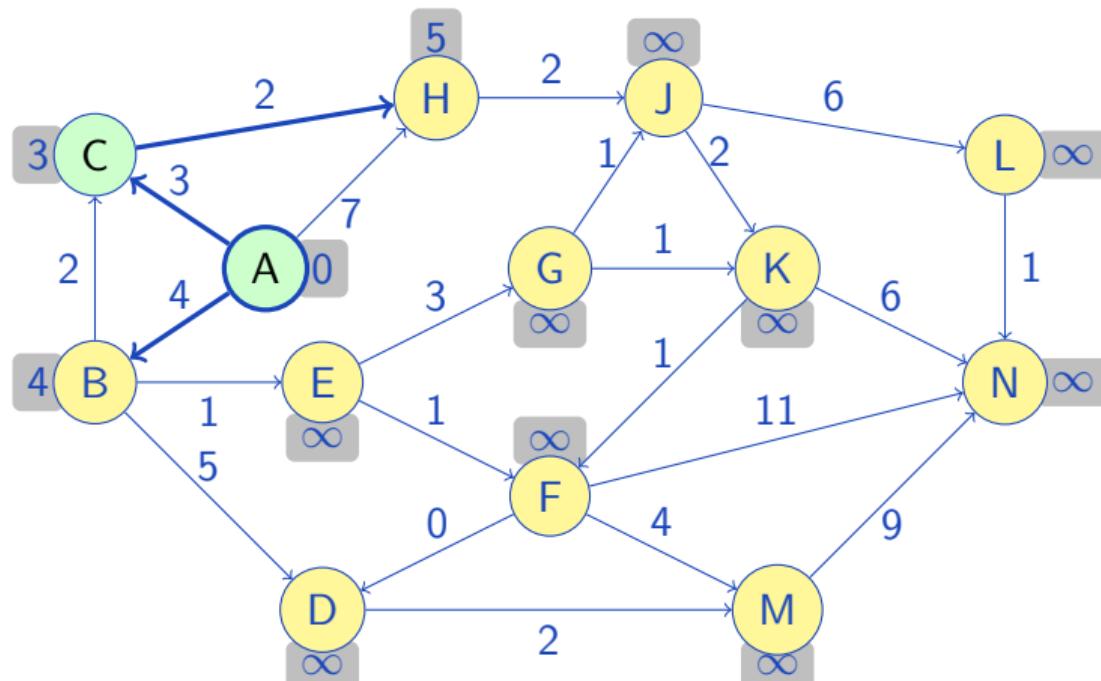


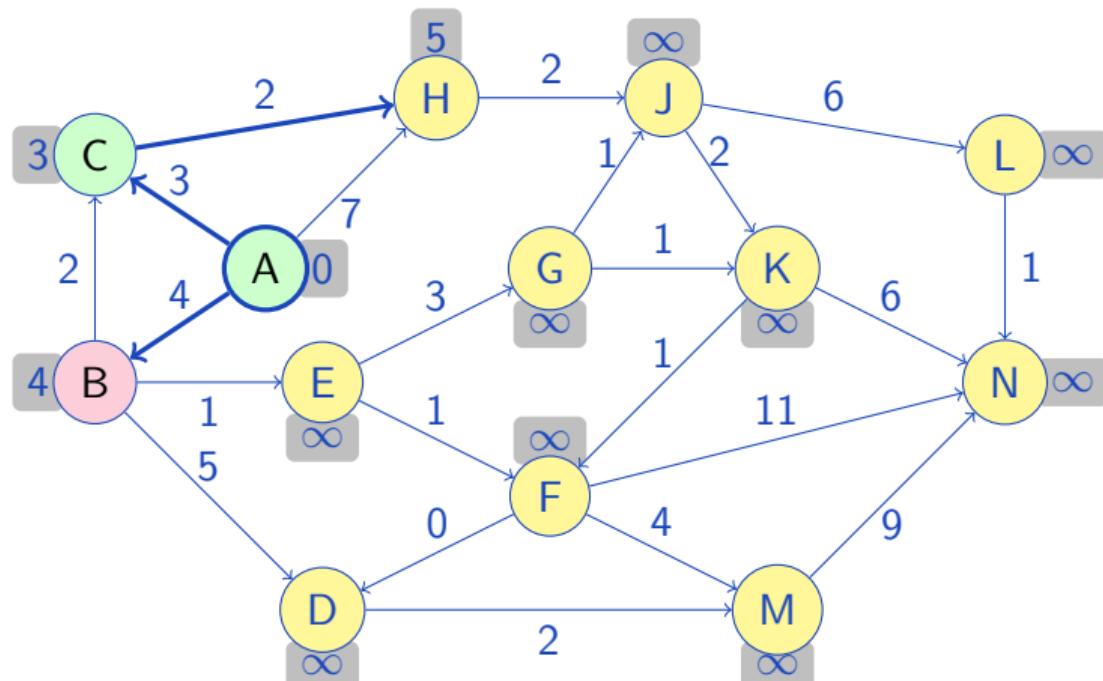


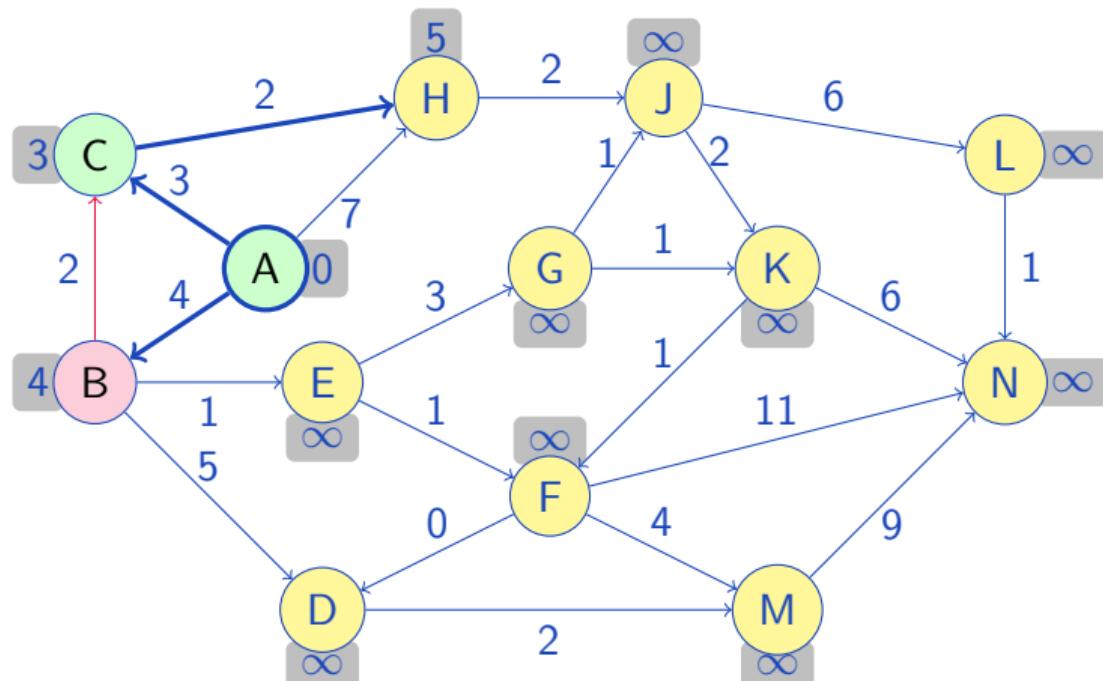


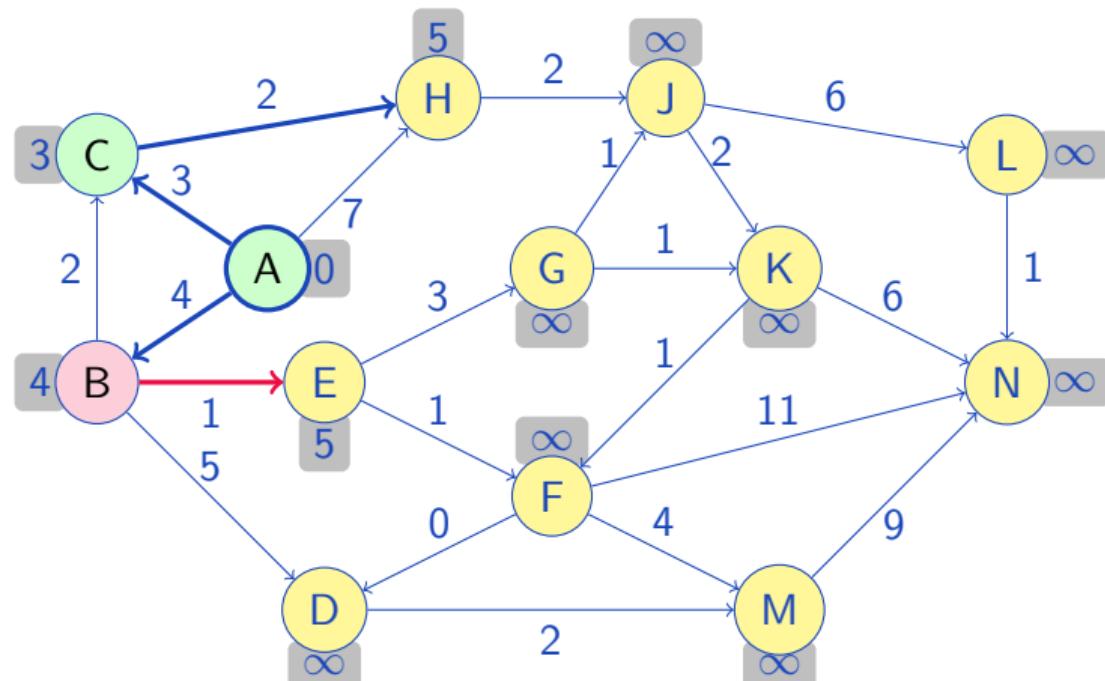


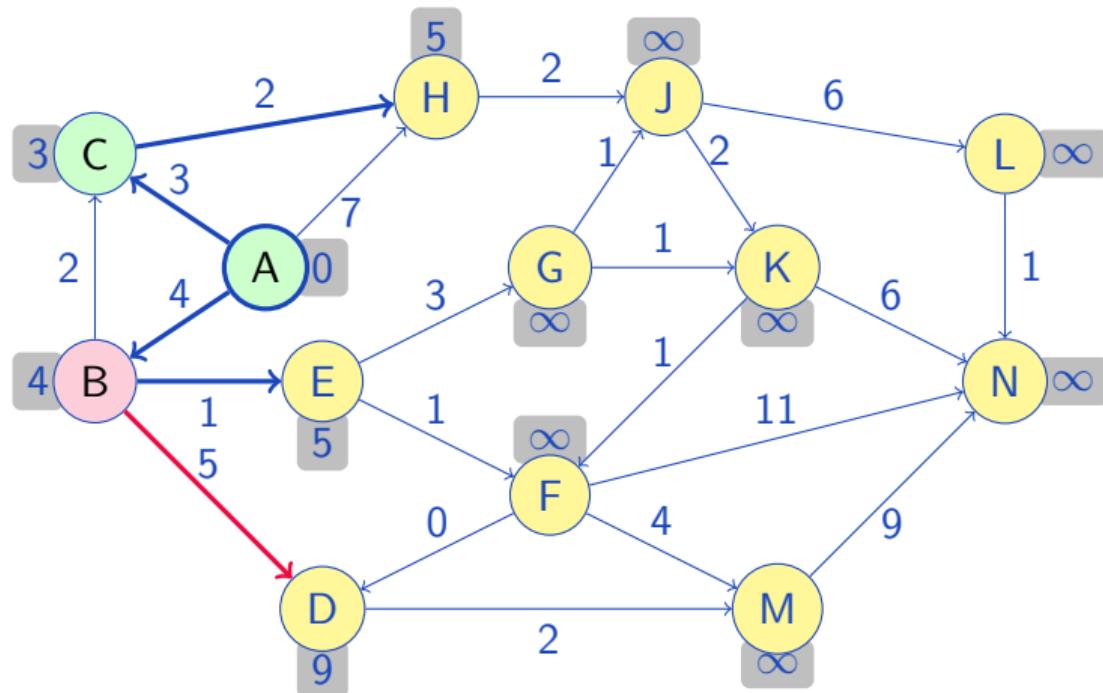


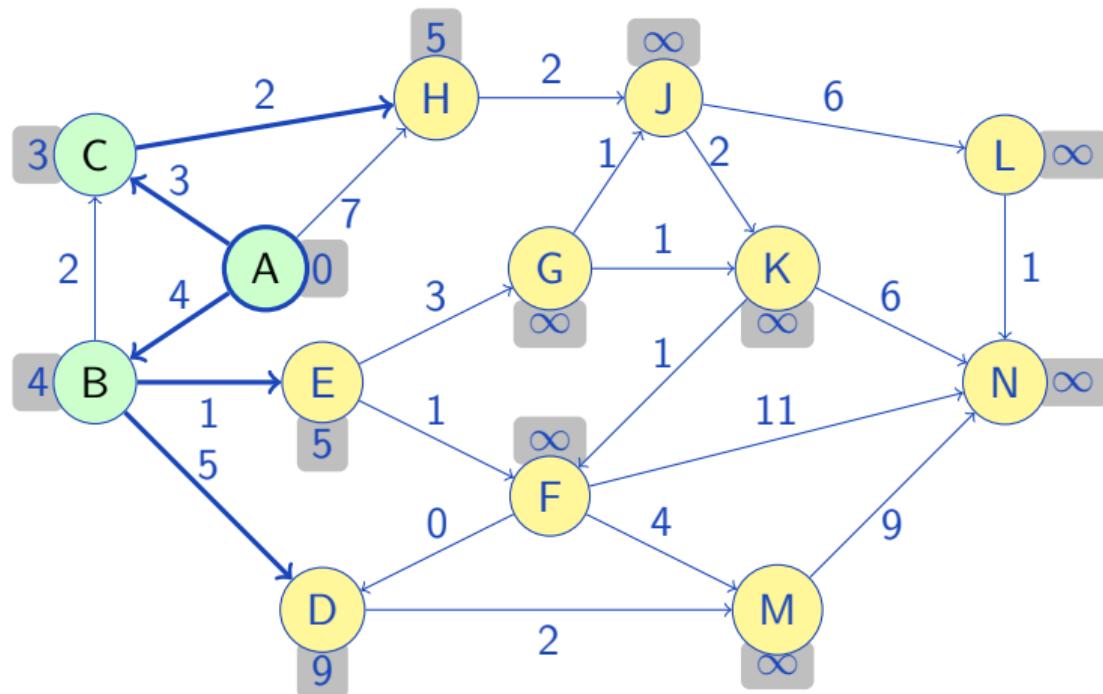


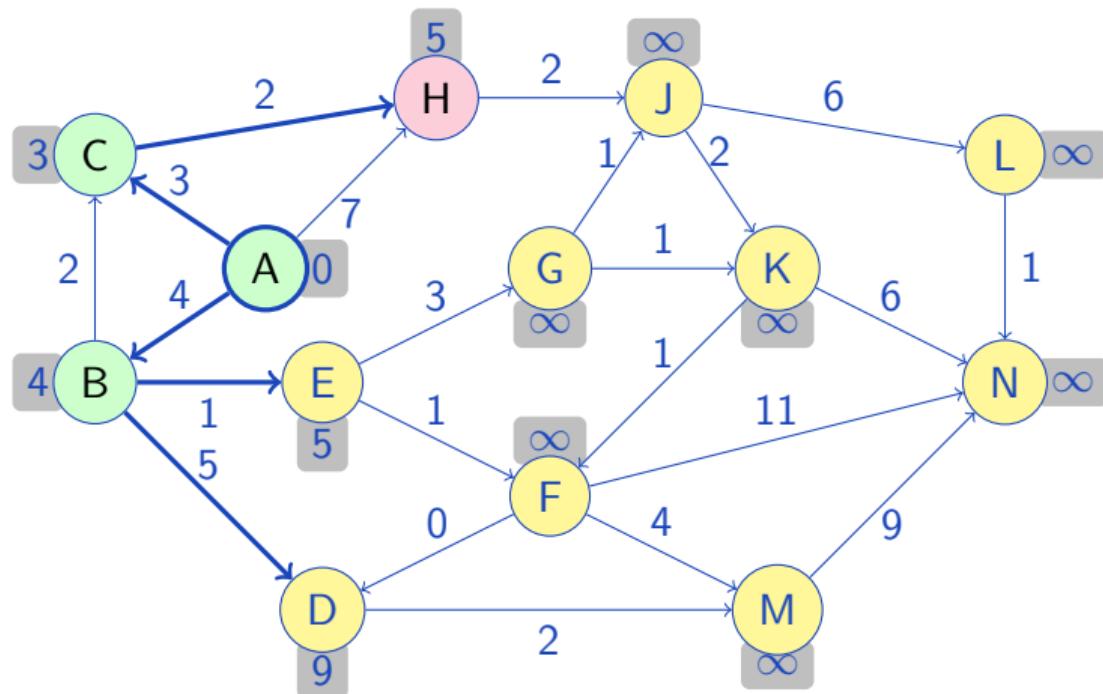


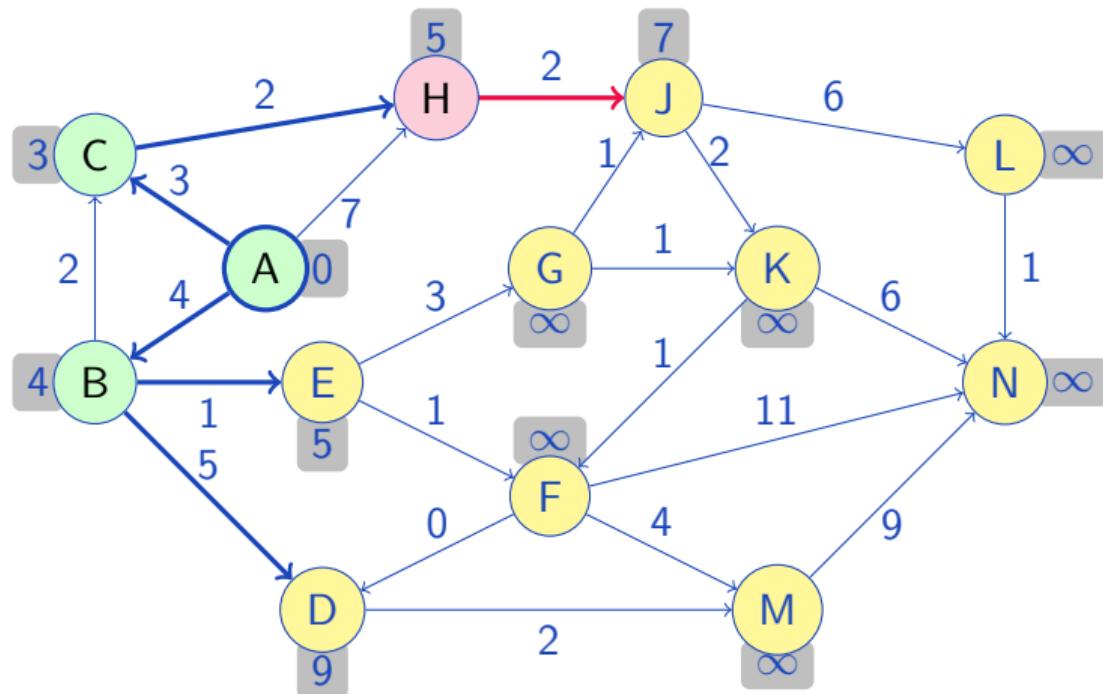


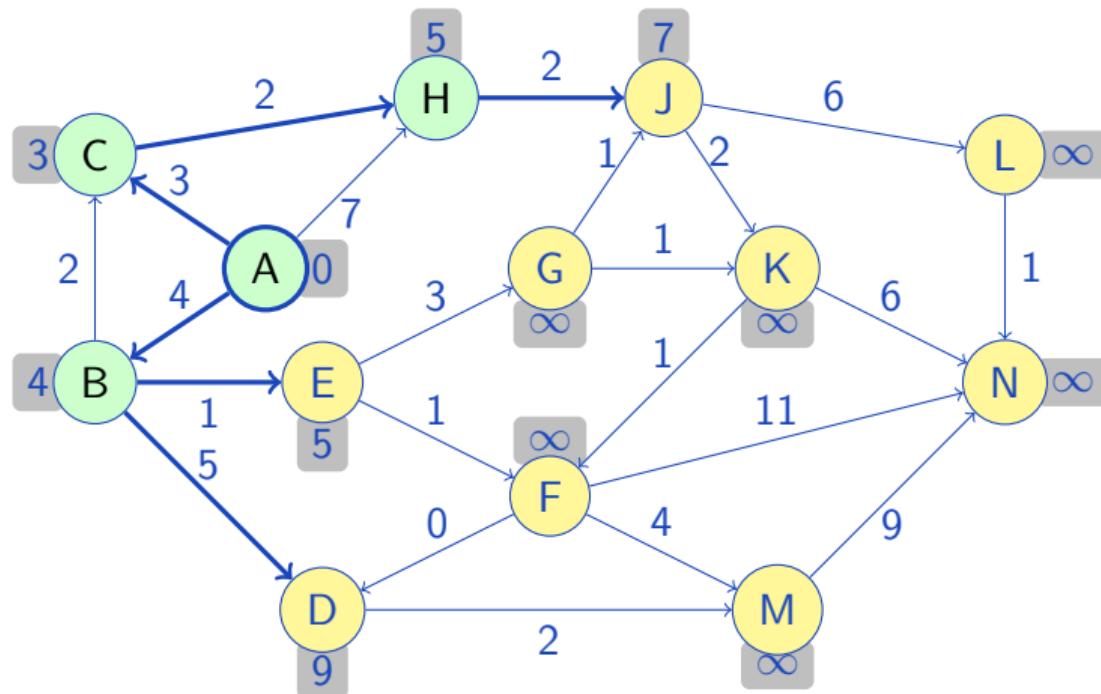


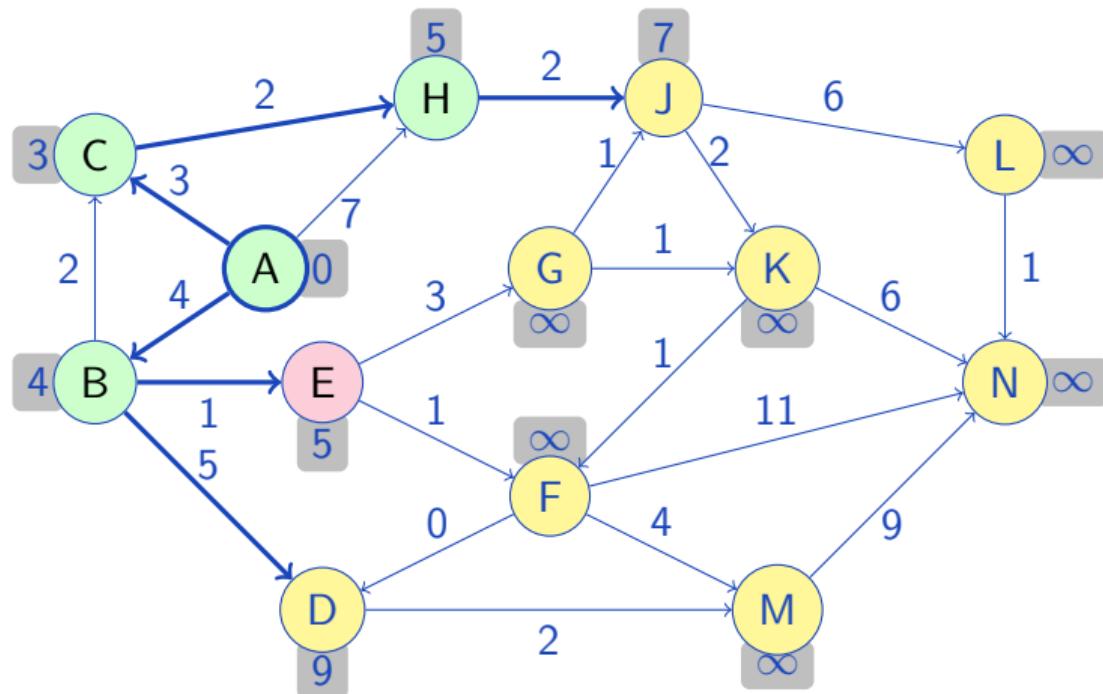


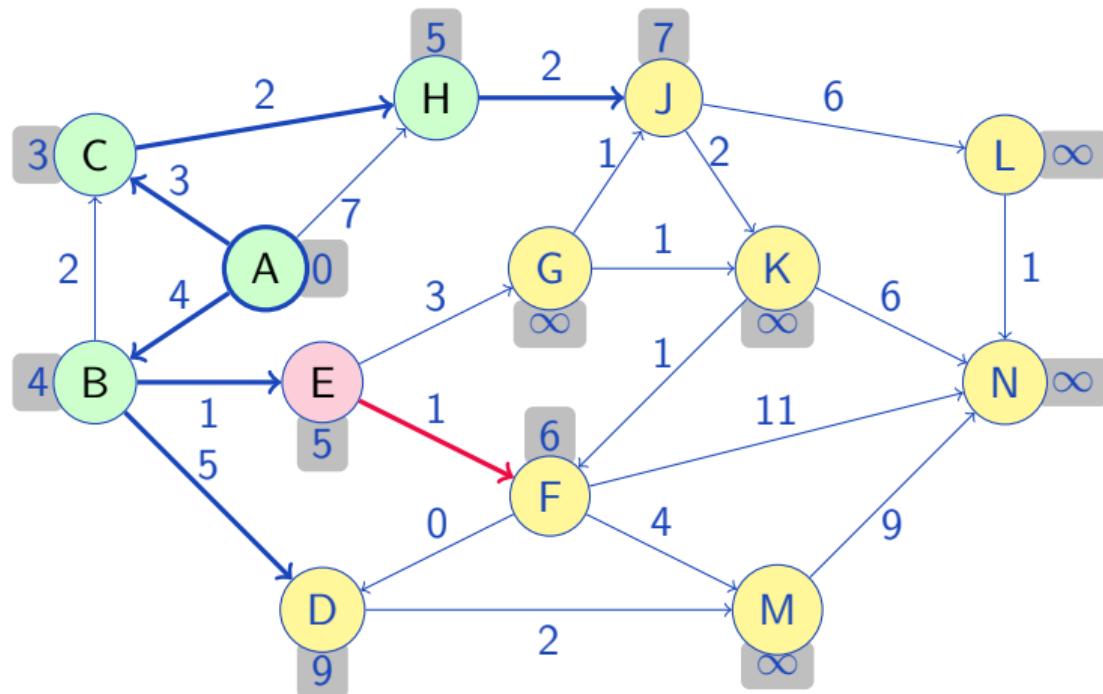


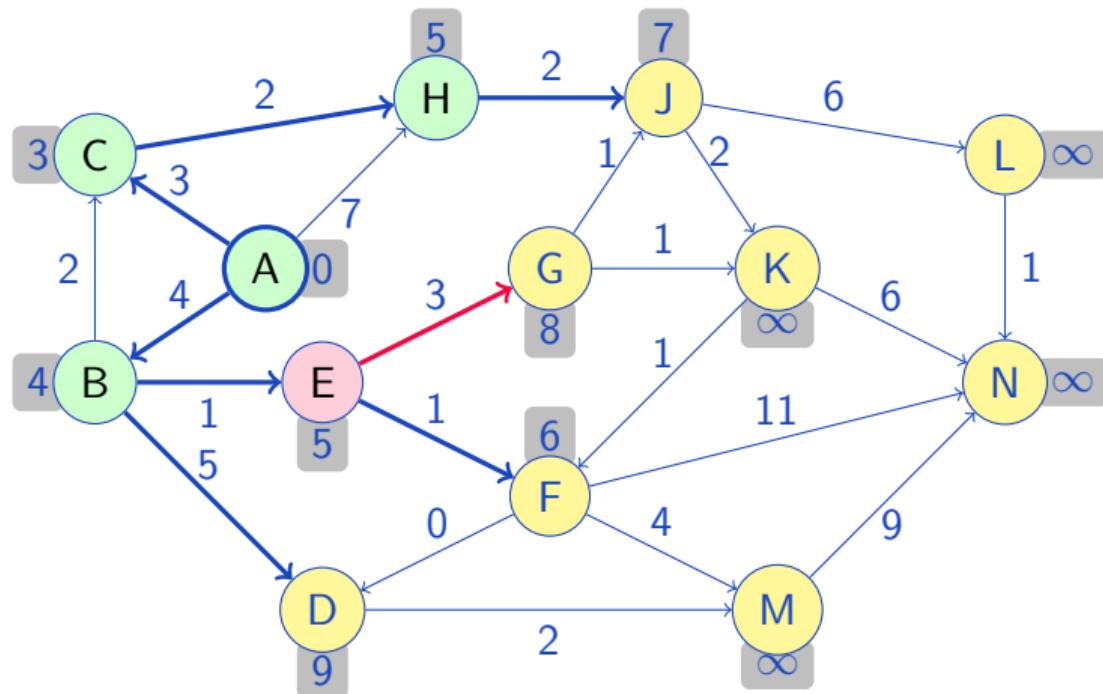


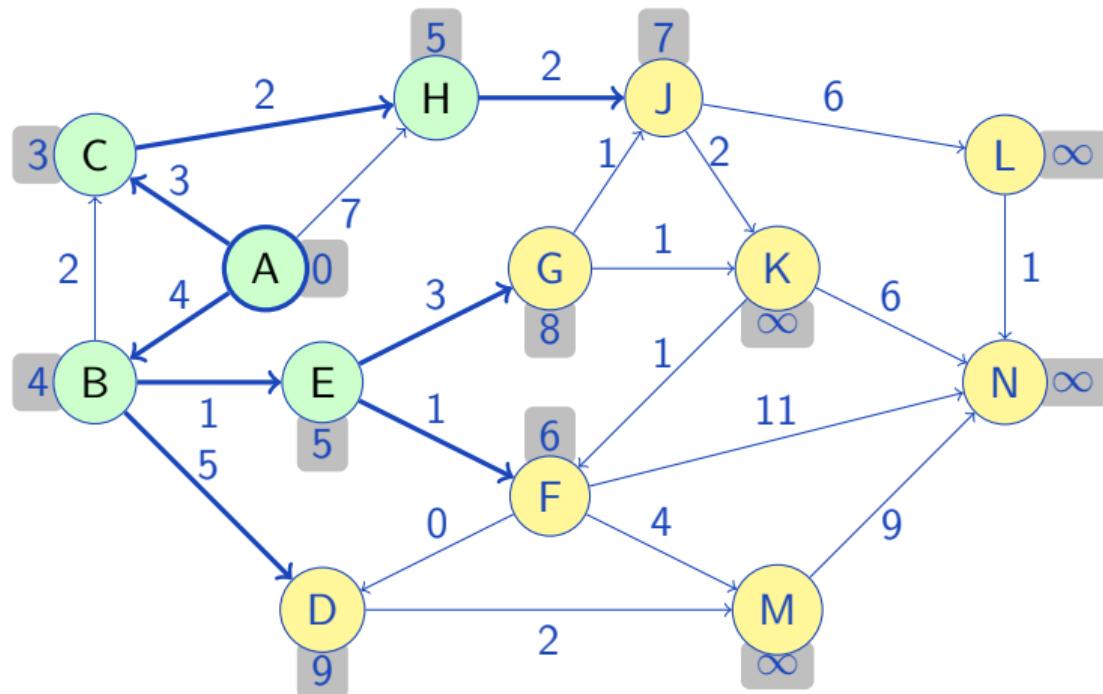


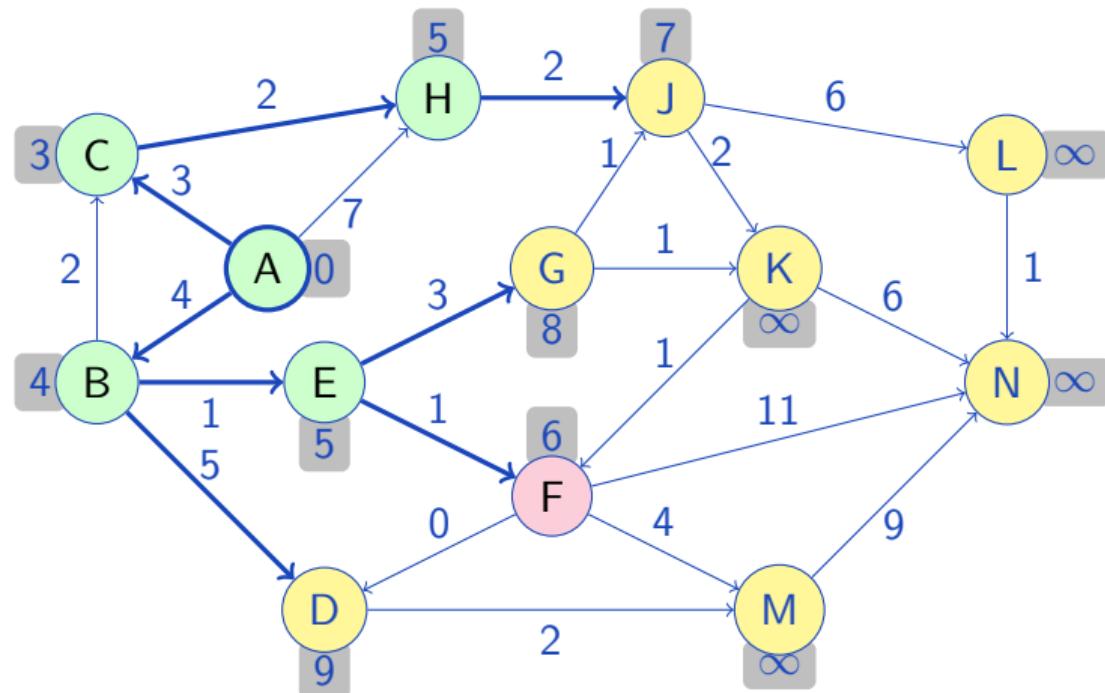


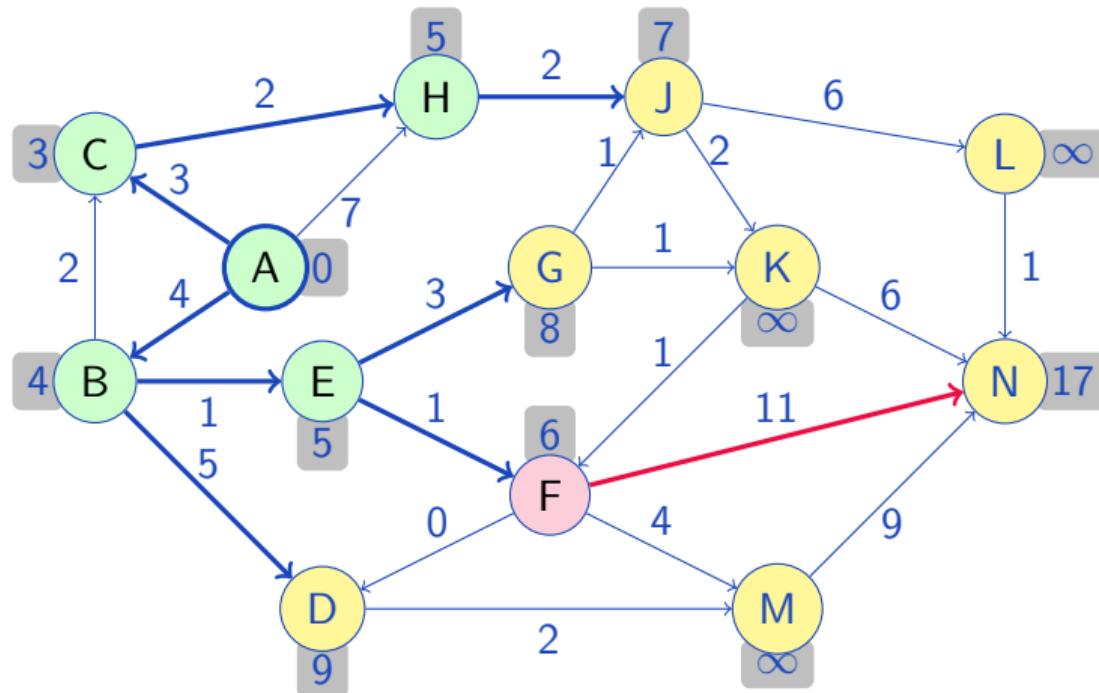


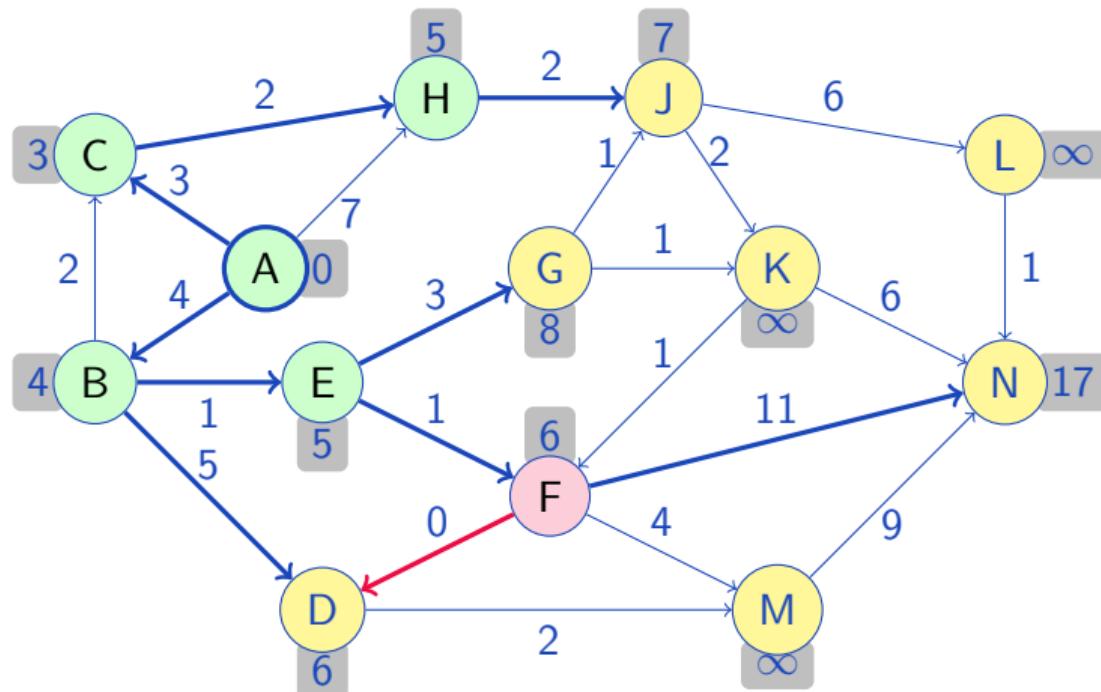


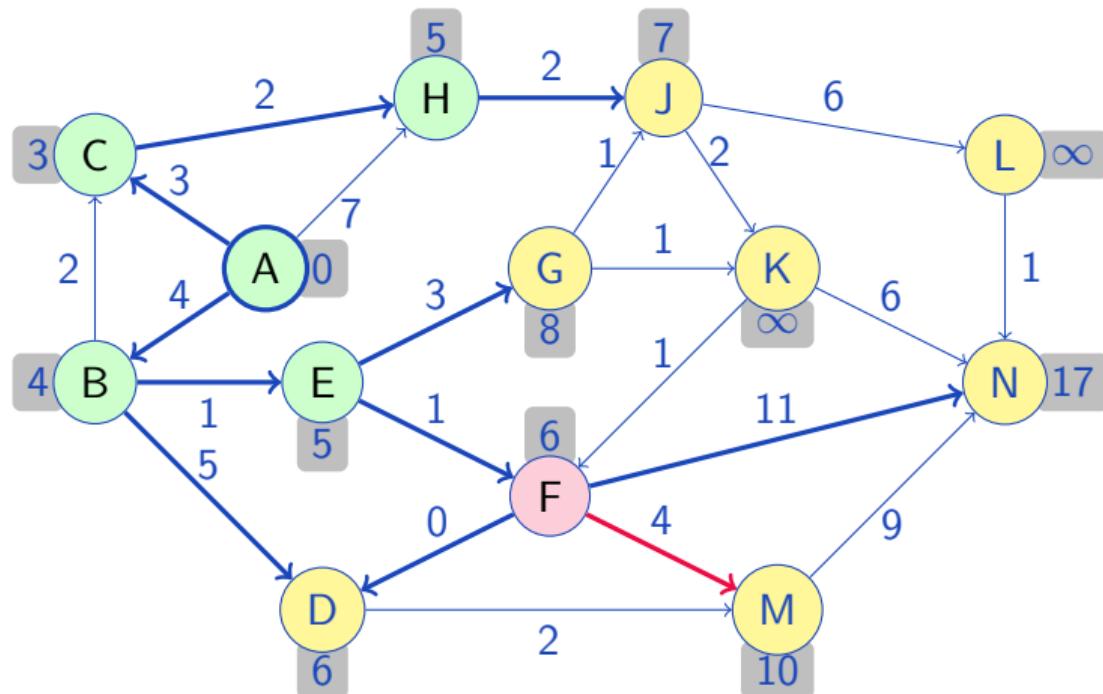


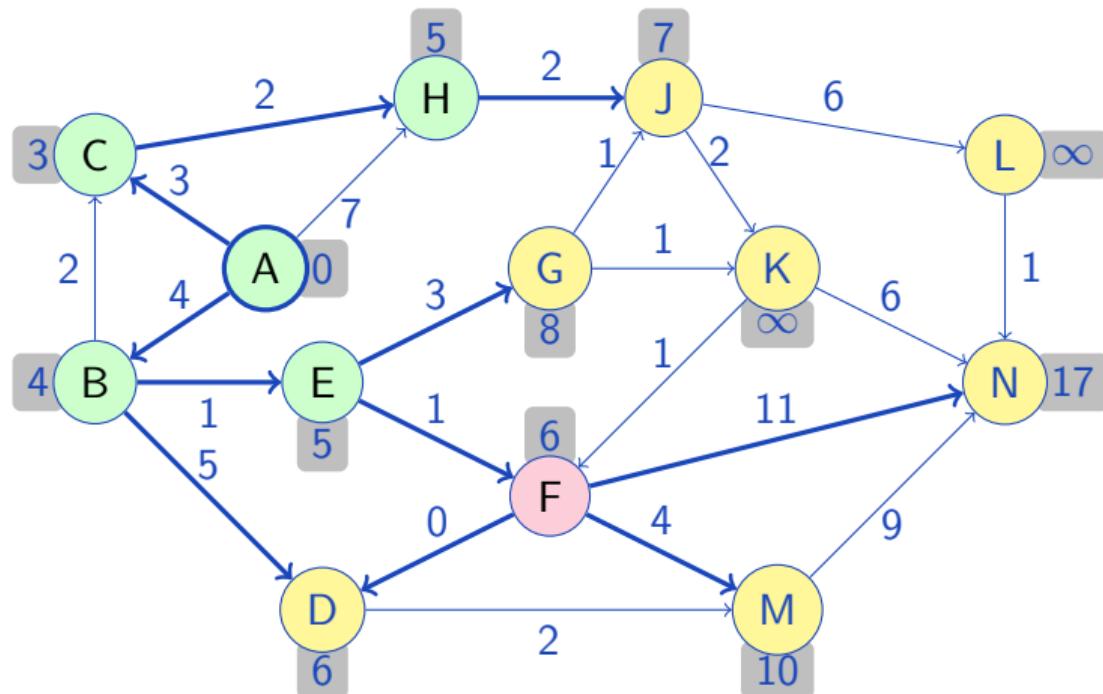


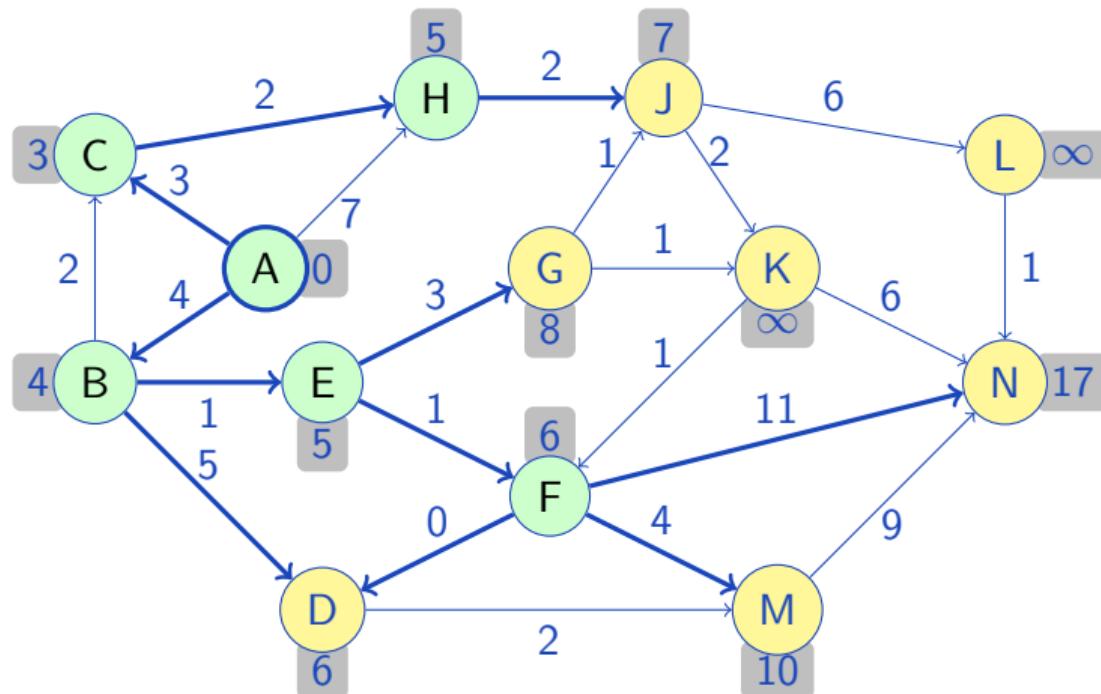


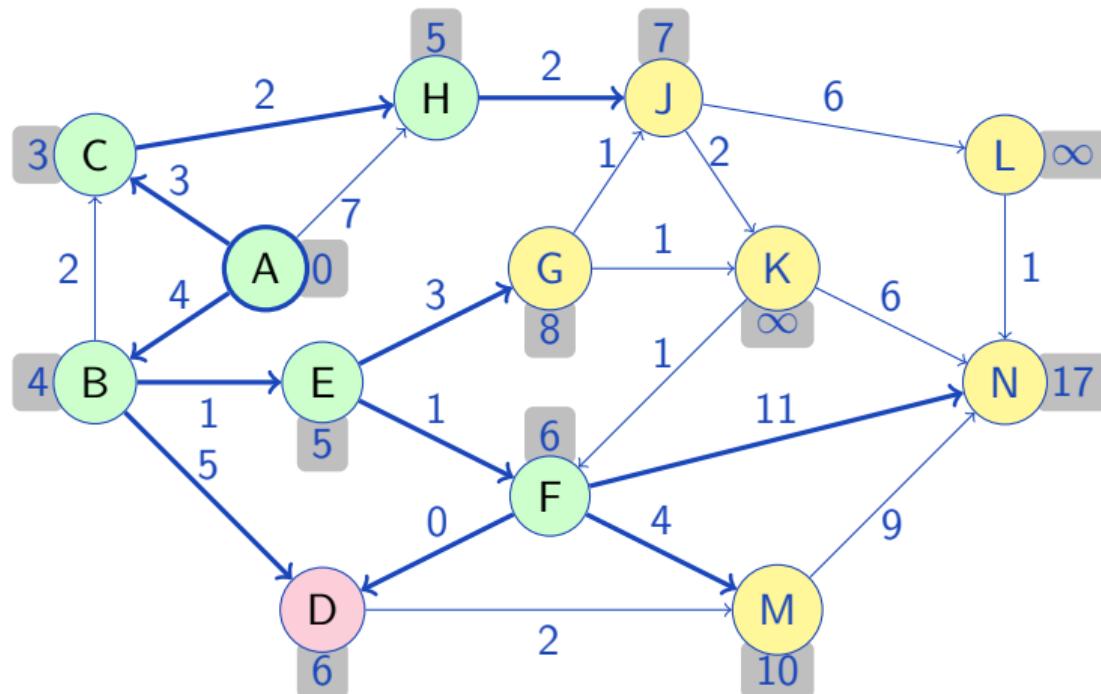


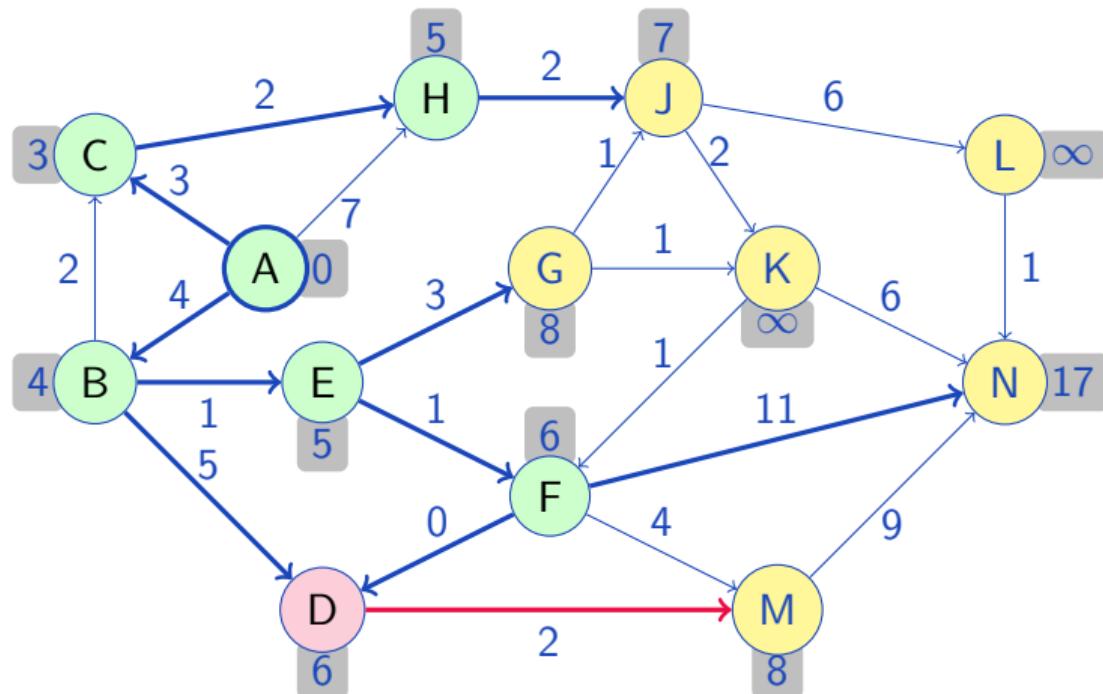


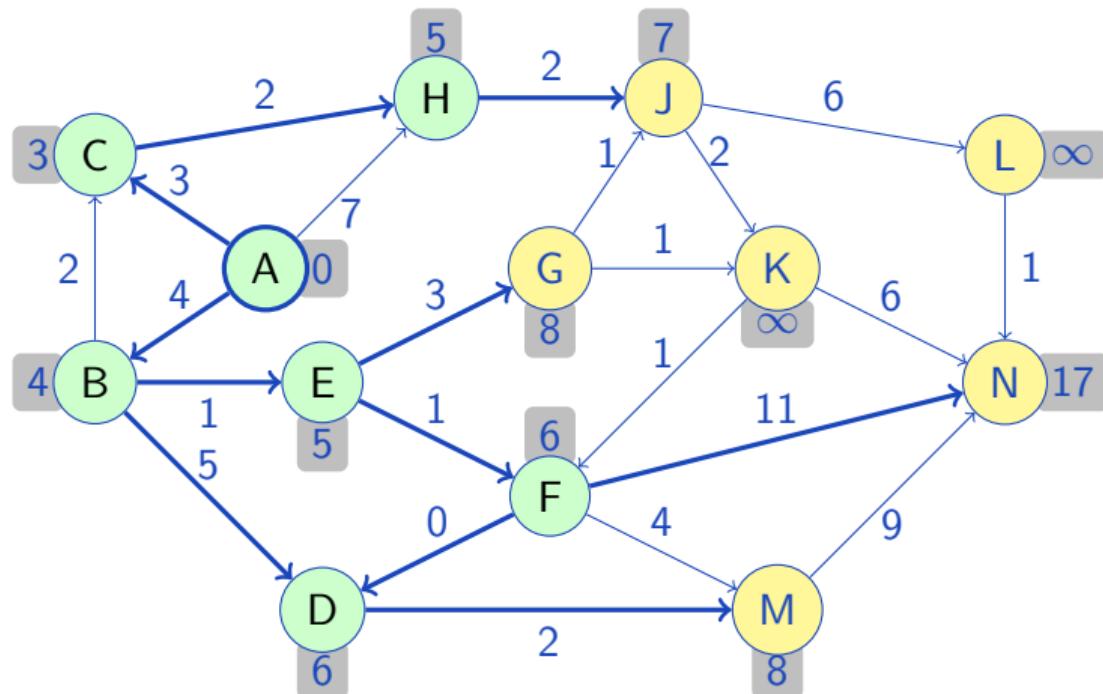


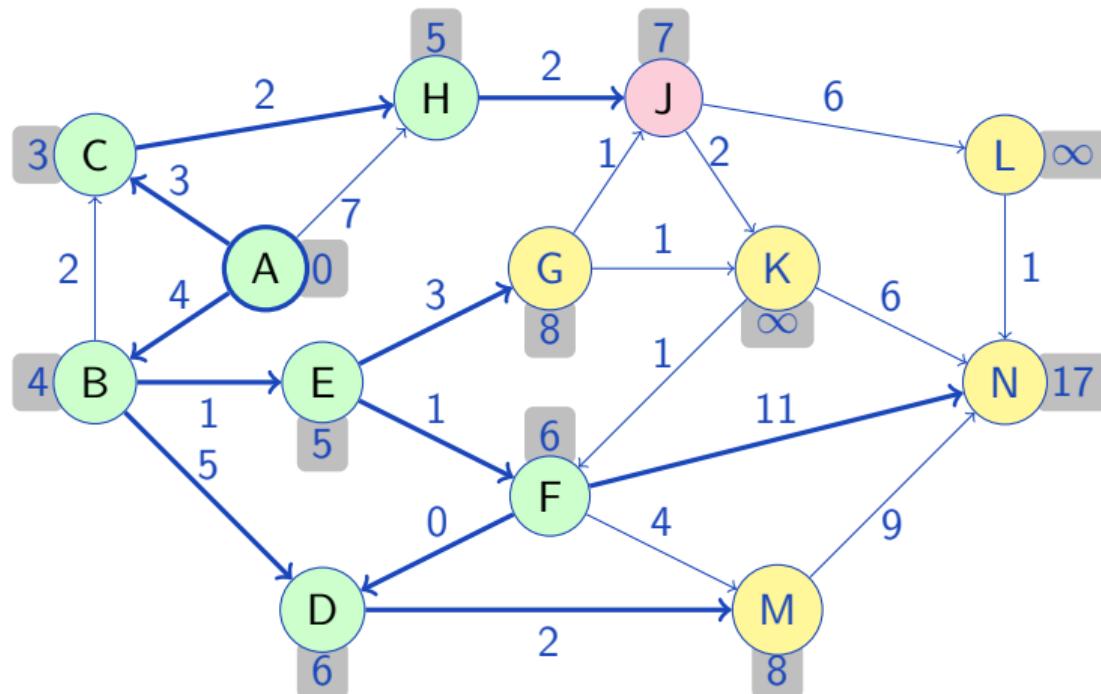


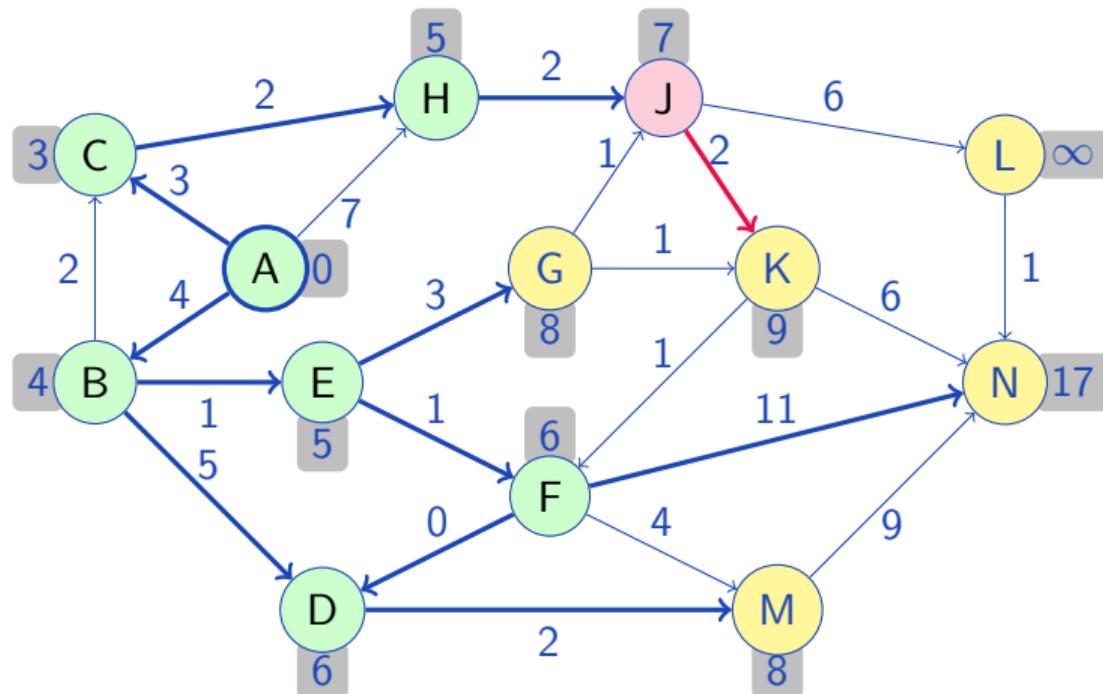


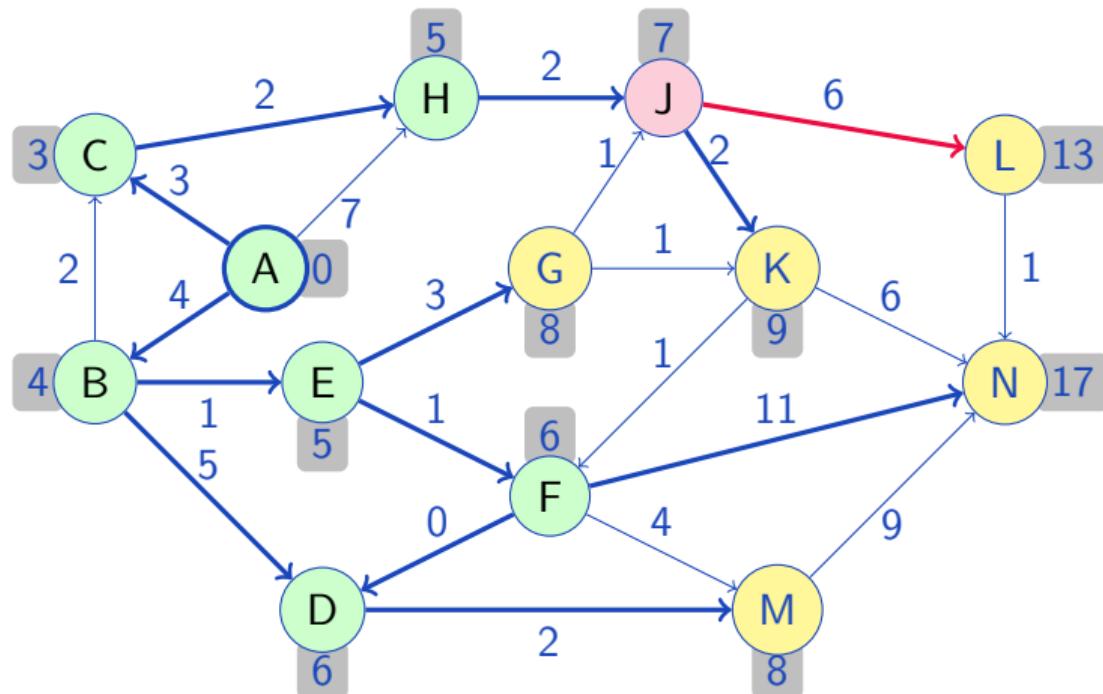


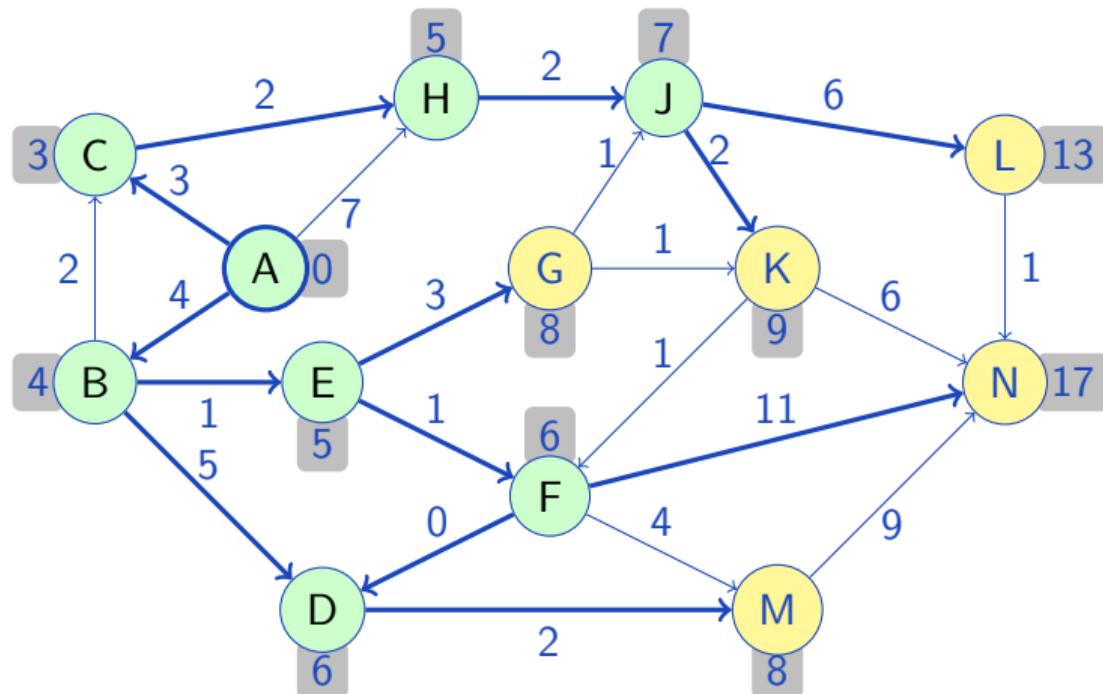


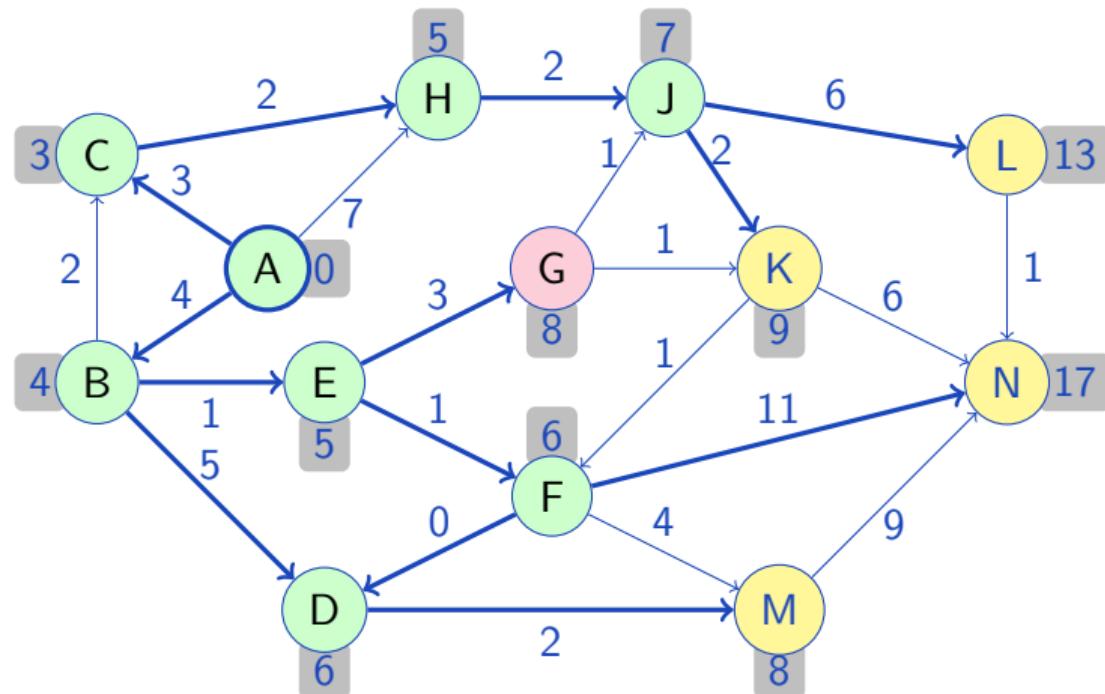


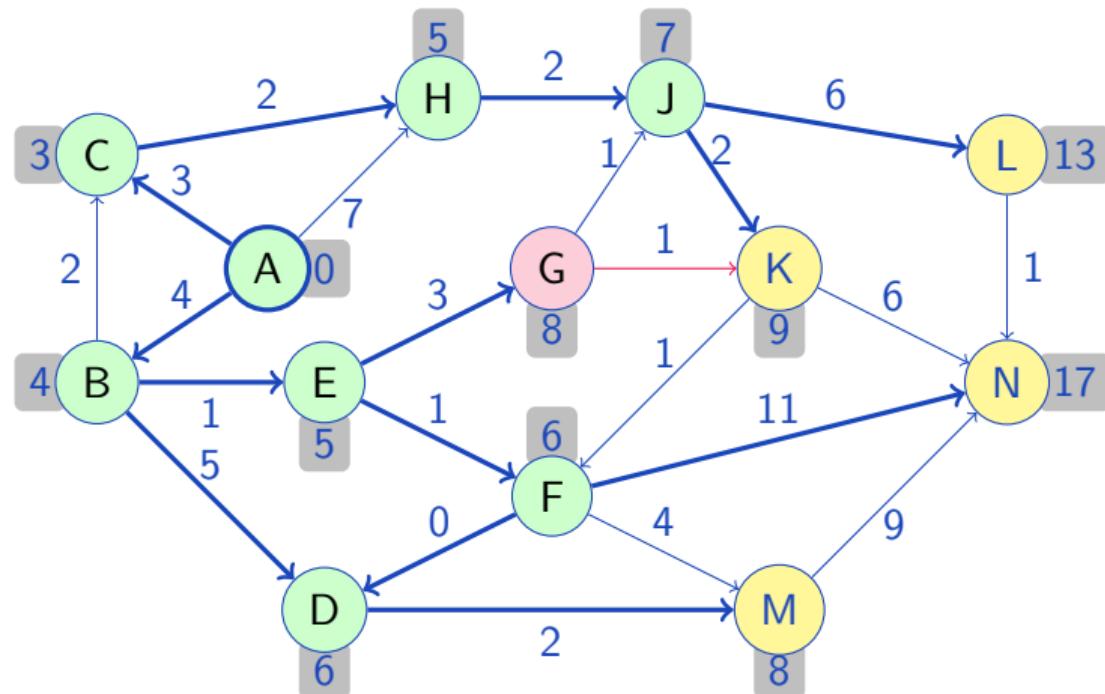


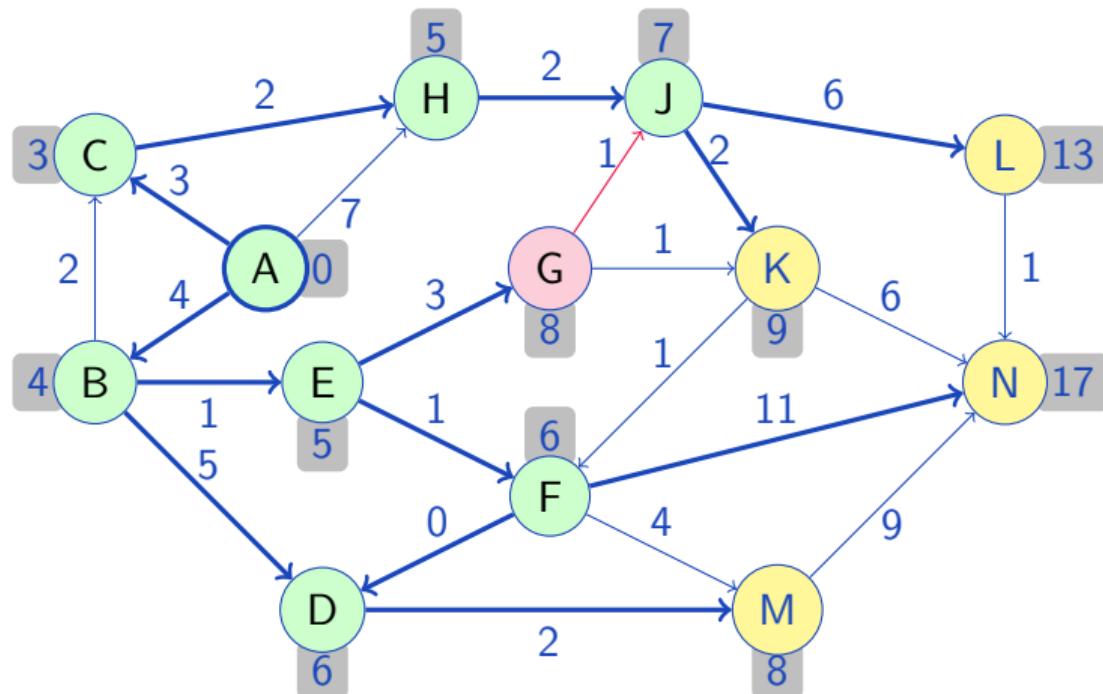


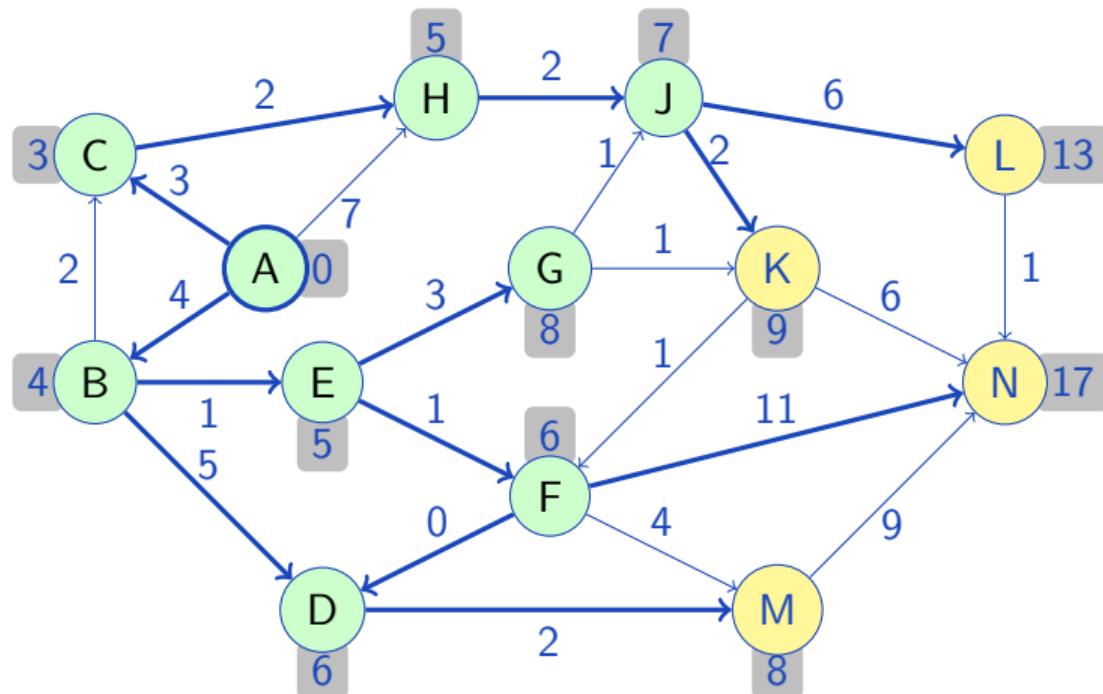


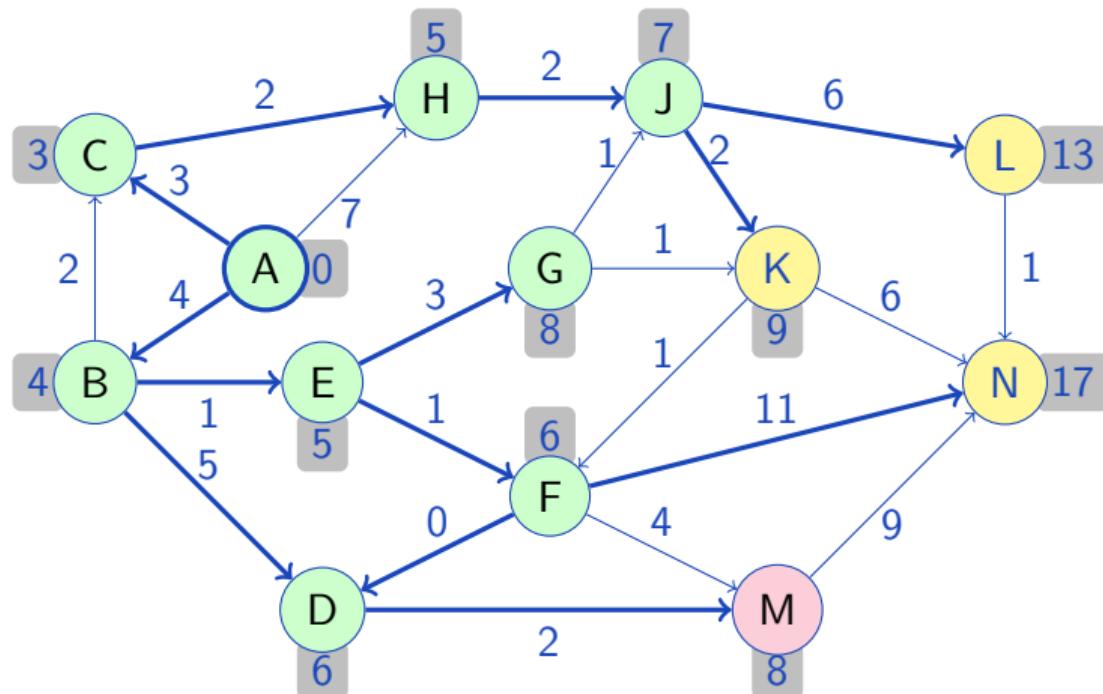


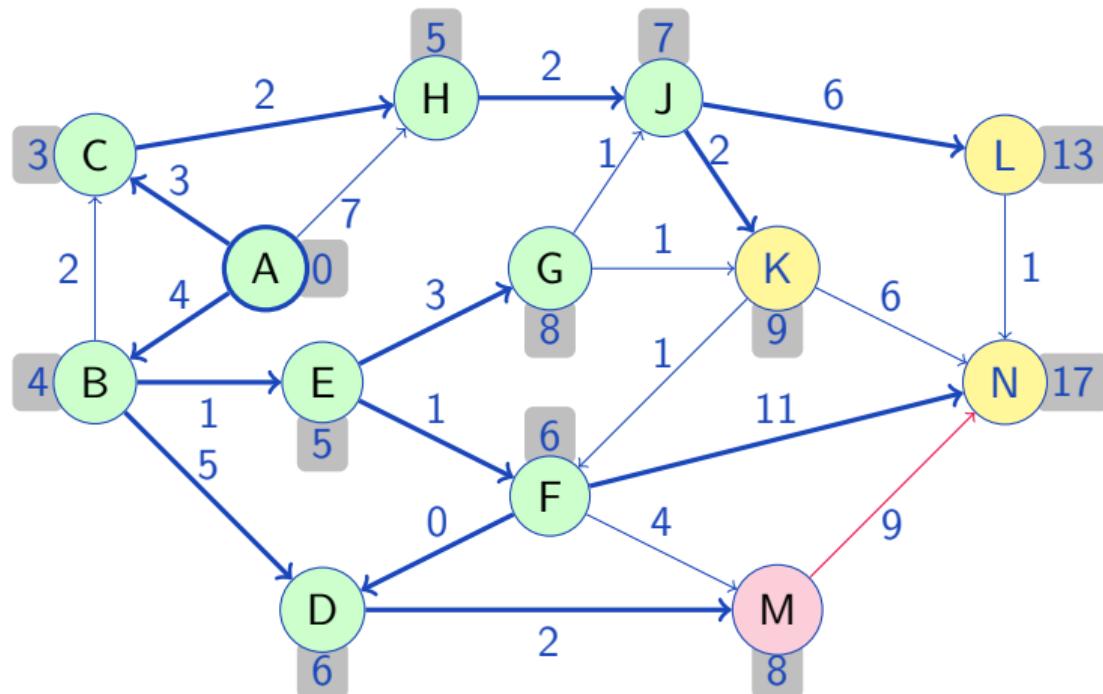


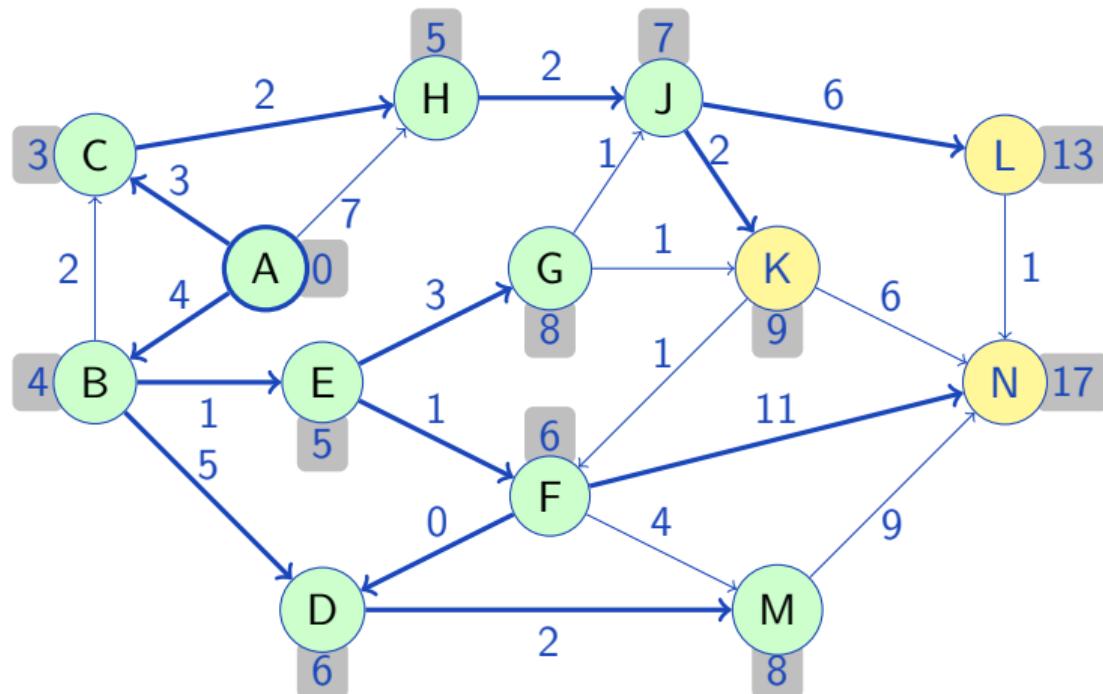


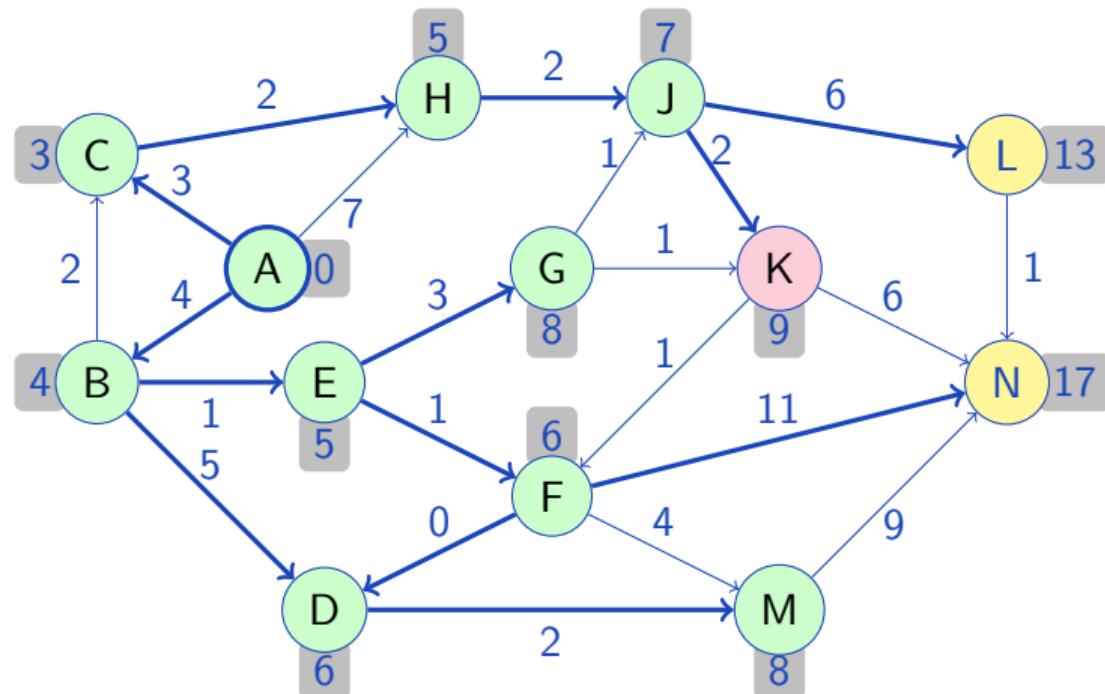


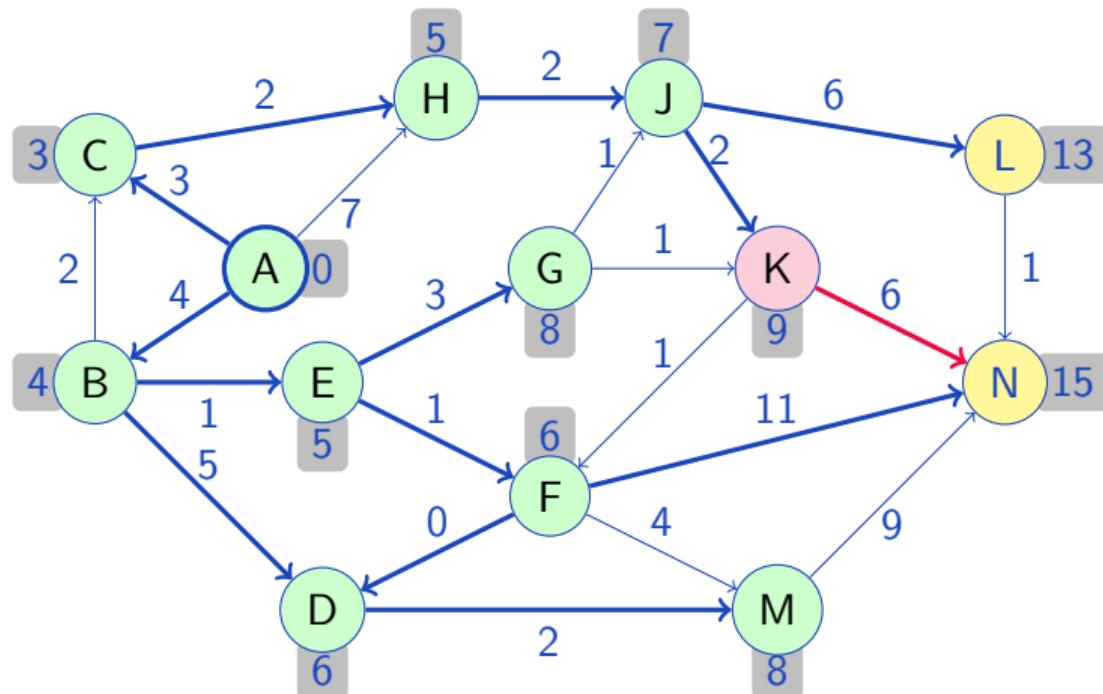


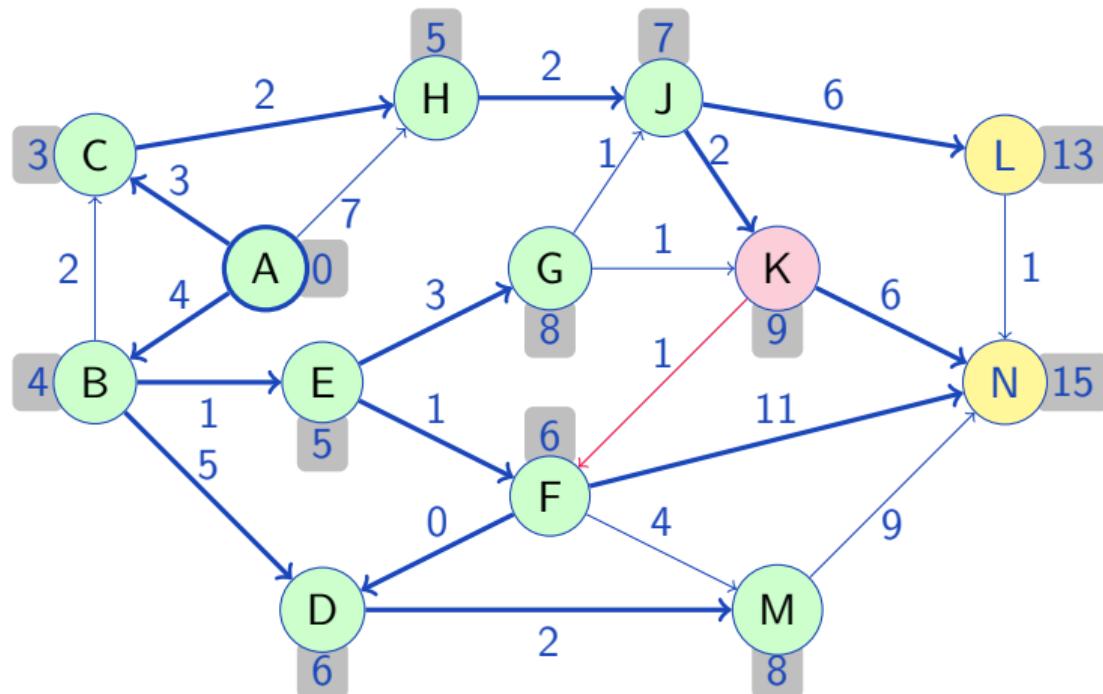


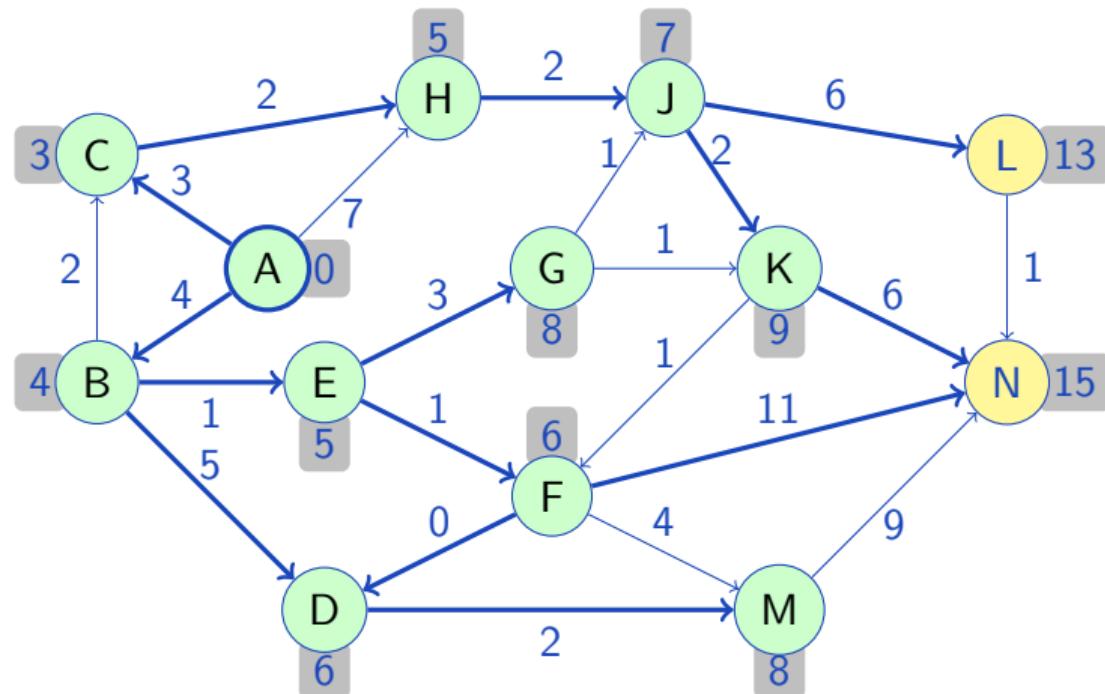


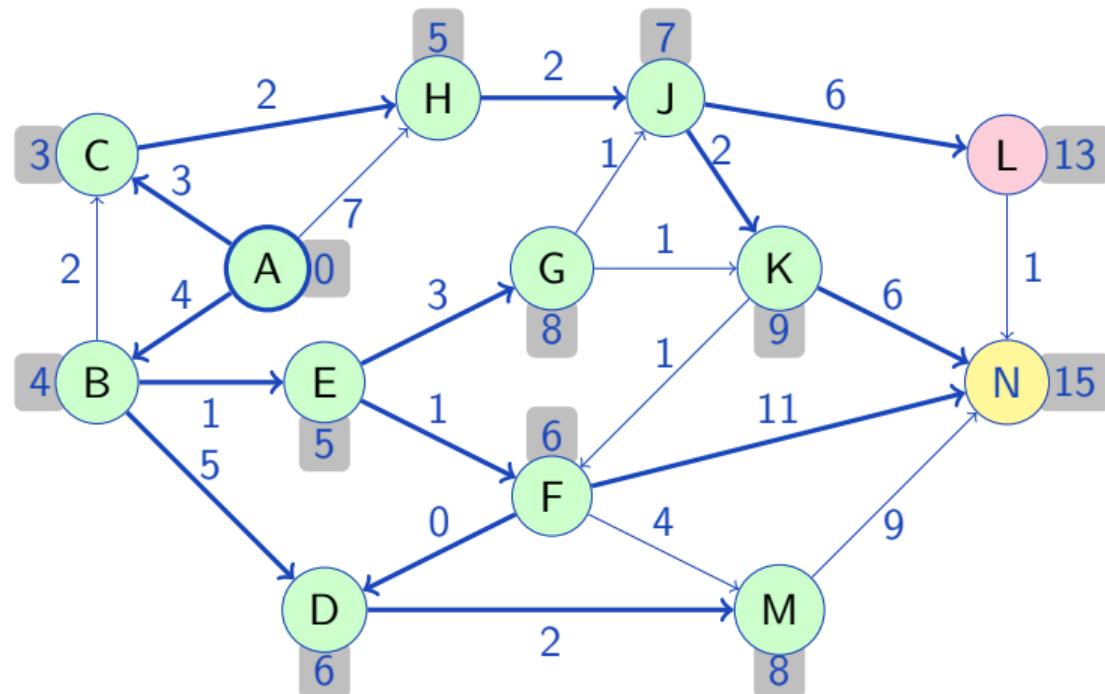


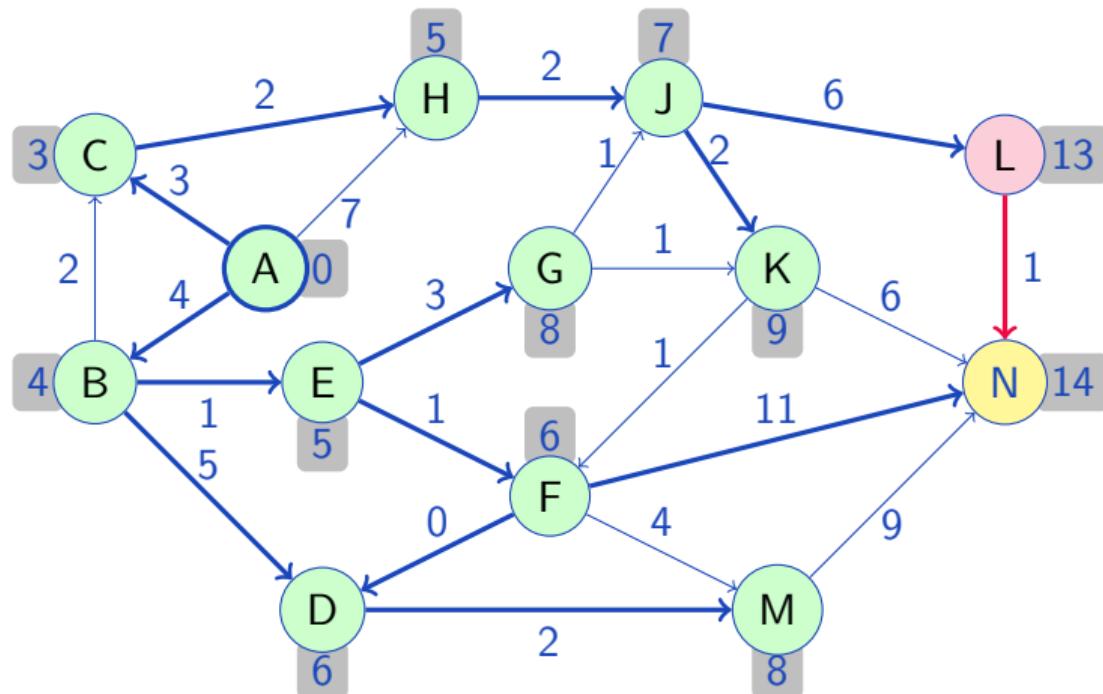


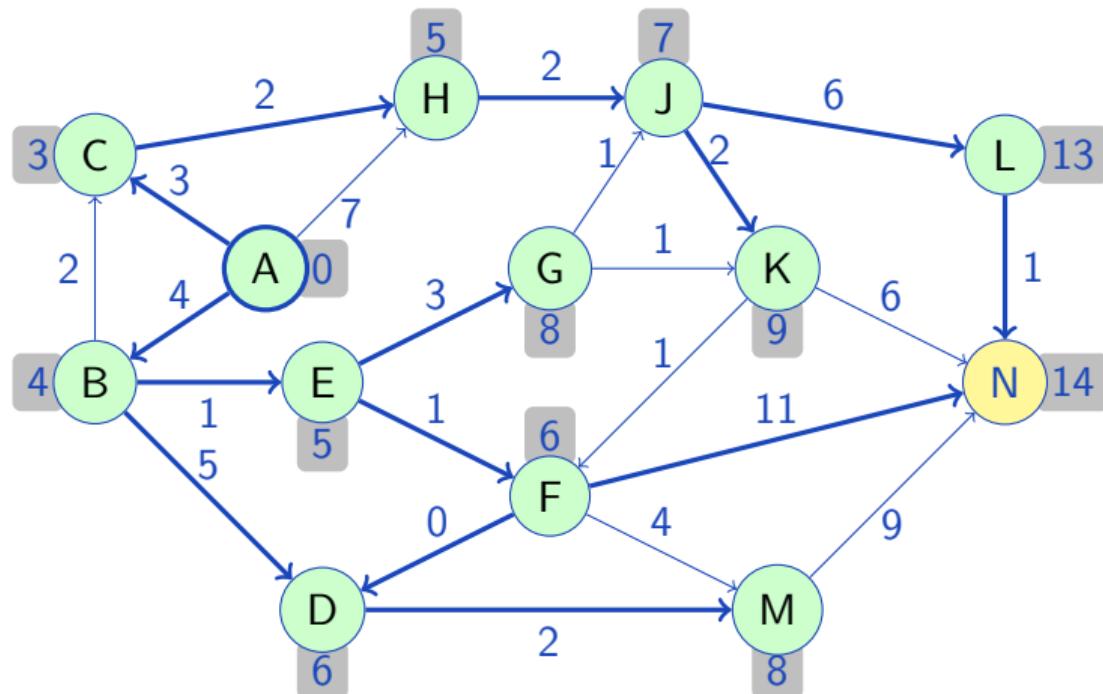


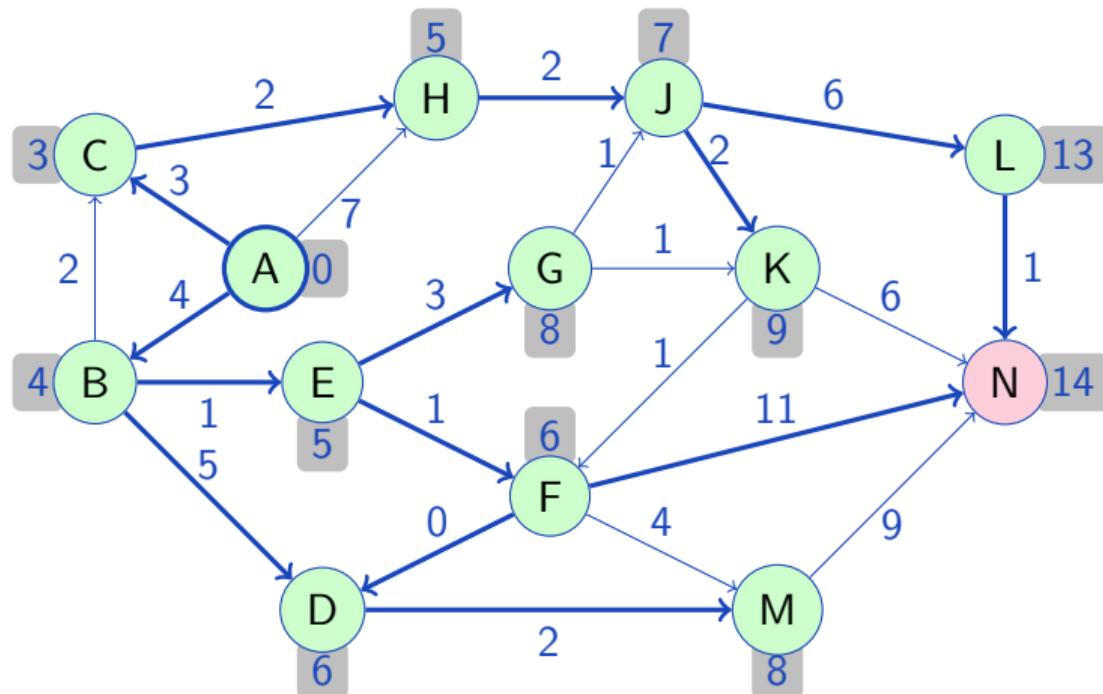


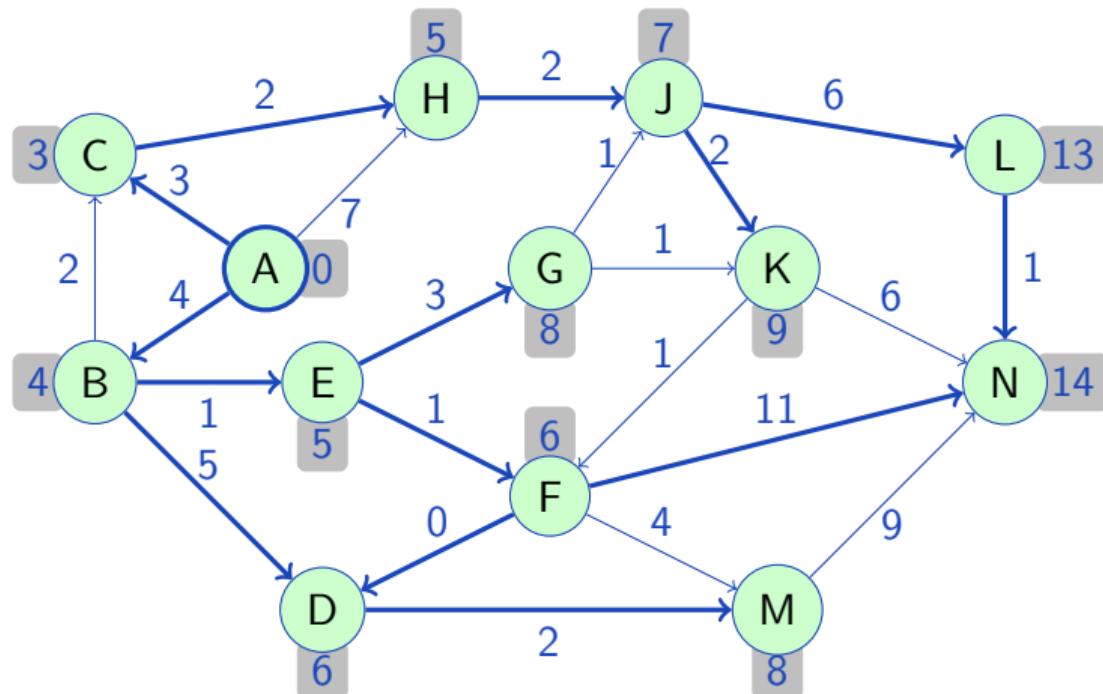












► Recall: How to update S

- Choose $v \notin S$ with the smallest $D'[v]$
- Set $D[v] = D'[v]$
- $S \leftarrow S \cup \{v\}$
- For all edges $(v, v') \in E$, update $D'[v'] \leftarrow \min(D'[v'], D[v] + L(v, v'))$

- ▶ Recall: How to update S
 - ▶ Choose $v \notin S$ with the smallest $D'[v]$
 - ▶ Set $D[v] = D'[v]$
 - ▶ $S \leftarrow S \cup \{v\}$
 - ▶ For all edges $(v, v') \in E$, update $D'[v'] \leftarrow \min(D'[v'], D[v] + L(v, v'))$
- ▶ How to choose vertices with smallest distance?

- ▶ Recall: How to update S
 - ▶ Choose $v \notin S$ with the smallest $D'[v]$
 - ▶ Set $D[v] = D'[v]$
 - ▶ $S \leftarrow S \cup \{v\}$
 - ▶ For all edges $(v, v') \in E$, update $D'[v'] \leftarrow \min(D'[v'], D[v] + L(v, v'))$
- ▶ How to choose vertices with smallest distance?
 1. Naïve way. Iterate each time over vertices
 - ▶ Running time of one iteration: $O(|V|)$
 - ▶ $|V|$ iterations, $O(|V|^2)$ total time. Good for **dense graphs**, bad for **sparse ones**

- ▶ Recall: How to update S
 - ▶ Choose $v \notin S$ with the smallest $D'[v]$
 - ▶ Set $D[v] = D'[v]$
 - ▶ $S \leftarrow S \cup \{v\}$
 - ▶ For all edges $(v, v') \in E$, update $D'[v'] \leftarrow \min(D'[v'], D[v] + L(v, v'))$
- ▶ How to choose vertices with smallest distance?
 1. Naïve way. Iterate each time over vertices
 - ▶ Running time of one iteration: $O(|V|)$
 - ▶ $|V|$ iterations, $O(|V|^2)$ total time. Good for dense graphs, bad for sparse ones
 2. Using binary heap
 - ▶ Choosing – “extract minimum”: $O(\log |V|)$, at most $|V|$ operations
 - ▶ Updating – “decrease key”: $O(\log |V|)$, at most $|E|$ operations
 - ▶ Total running time: $O(|E| \log |V|)$. Good for sparse graphs, bad for dense ones

► Recall: How to update S

- Choose $v \notin S$ with the smallest $D'[v]$
- Set $D[v] = D'[v]$
- $S \leftarrow S \cup \{v\}$
- For all edges $(v, v') \in E$, update $D'[v'] \leftarrow \min(D'[v'], D[v] + L(v, v'))$

► How to choose vertices with smallest distance?

1. Naïve way. Iterate each time over vertices

- Running time of one iteration: $O(|V|)$
- $|V|$ iterations, $O(|V|^2)$ total time. Good for dense graphs, bad for sparse ones

2. Using binary heap

- Choosing – “extract minimum”: $O(\log |V|)$, at most $|V|$ operations
- Updating – “decrease key”: $O(\log |V|)$, at most $|E|$ operations
- Total running time: $O(|E| \log |V|)$. Good for sparse graphs, bad for dense ones

3. Using Fibonacci heap: “decrease key” in amortized $O(1)$ time

- Total running time: $O(|V| \log |V| + |E|)$. However, impractical :(

Contest trick: How to implement Dijkstra with heap using standard libraries?

- ▶ Libraries of C++ and Java do not support heaps with “decrease key” operation

Contest trick: How to implement Dijkstra with heap using standard libraries?

- ▶ Libraries of C++ and Java do not support heaps with “decrease key” operation
- ▶ Basically two choices:

Contest trick: How to implement Dijkstra with heap using standard libraries?

- ▶ Libraries of C++ and Java do not support heaps with “decrease key” operation
- ▶ Basically two choices:
 1. Simulate binary heap with a **binary tree** of vertices ordered by distance
 - ▶ “Extract minimum”: remove the minimum (leftmost) vertex
 - ▶ “Decrease key”: remove vertex, change distance, insert vertex

Contest trick: How to implement Dijkstra with heap using standard libraries?

- ▶ Libraries of C++ and Java do not support heaps with “decrease key” operation
- ▶ Basically two choices:
 1. Simulate binary heap with a **binary tree** of vertices ordered by distance
 - ▶ “Extract minimum”: remove the minimum (leftmost) vertex
 - ▶ “Decrease key”: remove vertex, change distance, insert vertex
 - ▶ $O(|E| \log |V|)$ but quite **slow** due to tree’s hidden constant

Contest trick: How to implement Dijkstra with heap using **standard libraries**?

- ▶ Libraries of C++ and Java do not support heaps with “decrease key” operation
- ▶ Basically two choices:
 1. Simulate binary heap with a **binary tree** of vertices ordered by distance
 - ▶ “Extract minimum”: remove the minimum (leftmost) vertex
 - ▶ “Decrease key”: remove vertex, change distance, insert vertex
 - ▶ $O(|E| \log |V|)$ but quite **slow** due to tree’s hidden constant
 2. Simulate binary heap with a **priority queue** of **vertex-distance pairs**
 - ▶ “Extract minimum”: remove the minimum record,
discard and continue if distance in pair differs from current distance to that vertex
 - ▶ “Decrease key”: just insert a vertex-distance pair with the new distance

Contest trick: How to implement Dijkstra with heap using standard libraries?

- ▶ Libraries of C++ and Java do not support heaps with “decrease key” operation
- ▶ Basically two choices:
 1. Simulate binary heap with a **binary tree** of vertices ordered by distance
 - ▶ “Extract minimum”: remove the minimum (leftmost) vertex
 - ▶ “Decrease key”: remove vertex, change distance, insert vertex
 - ▶ $O(|E| \log |V|)$ but quite **slow** due to tree’s hidden constant
 2. Simulate binary heap with a **priority queue** of **vertex-distance pairs**
 - ▶ “Extract minimum”: remove the minimum record,
discard and continue if distance in pair differs from current distance to that vertex
 - ▶ “Decrease key”: just insert a vertex-distance pair with the new distance
 - ▶ $O(|E| \log |E|)$ but rather **fast**, generally better than tree